

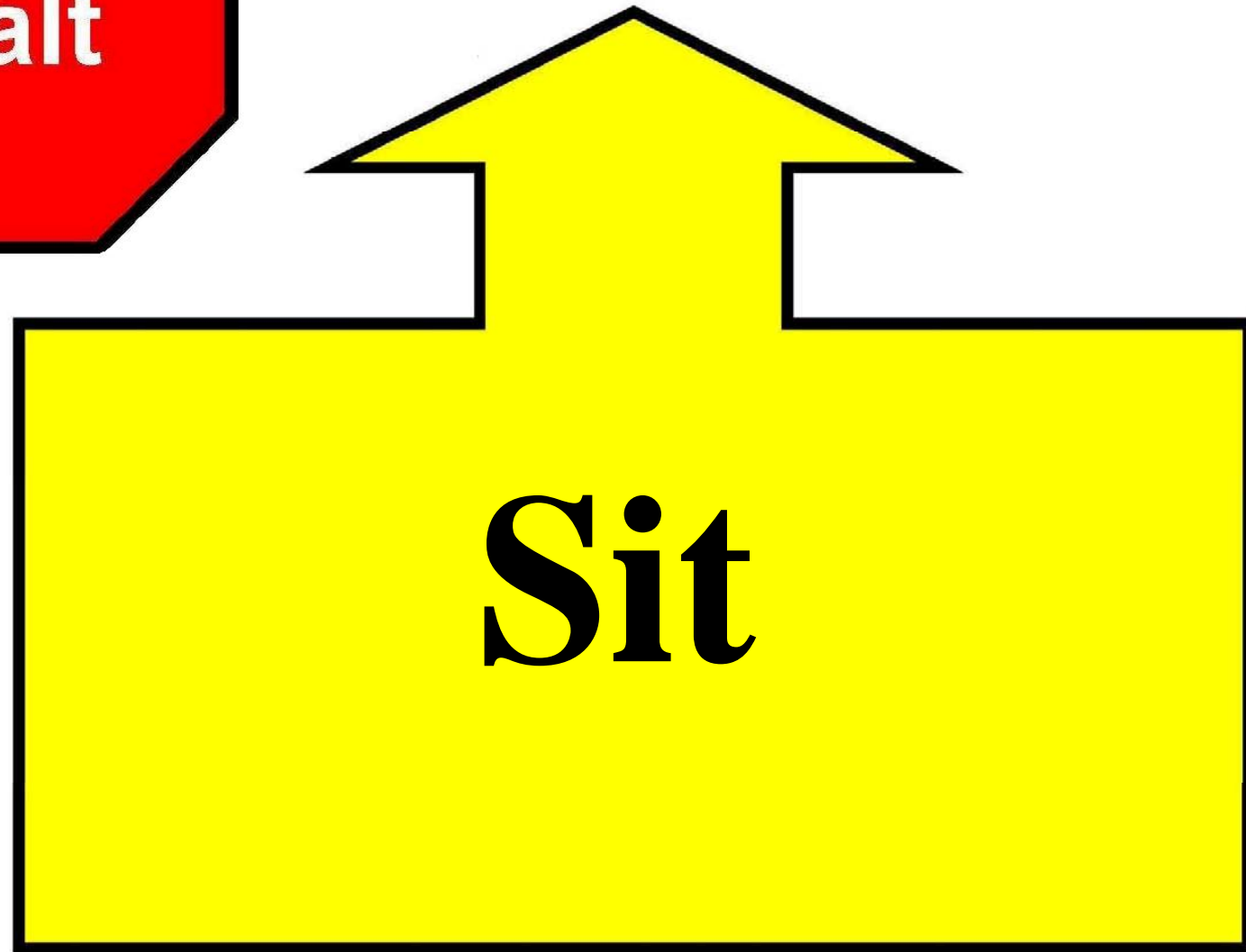


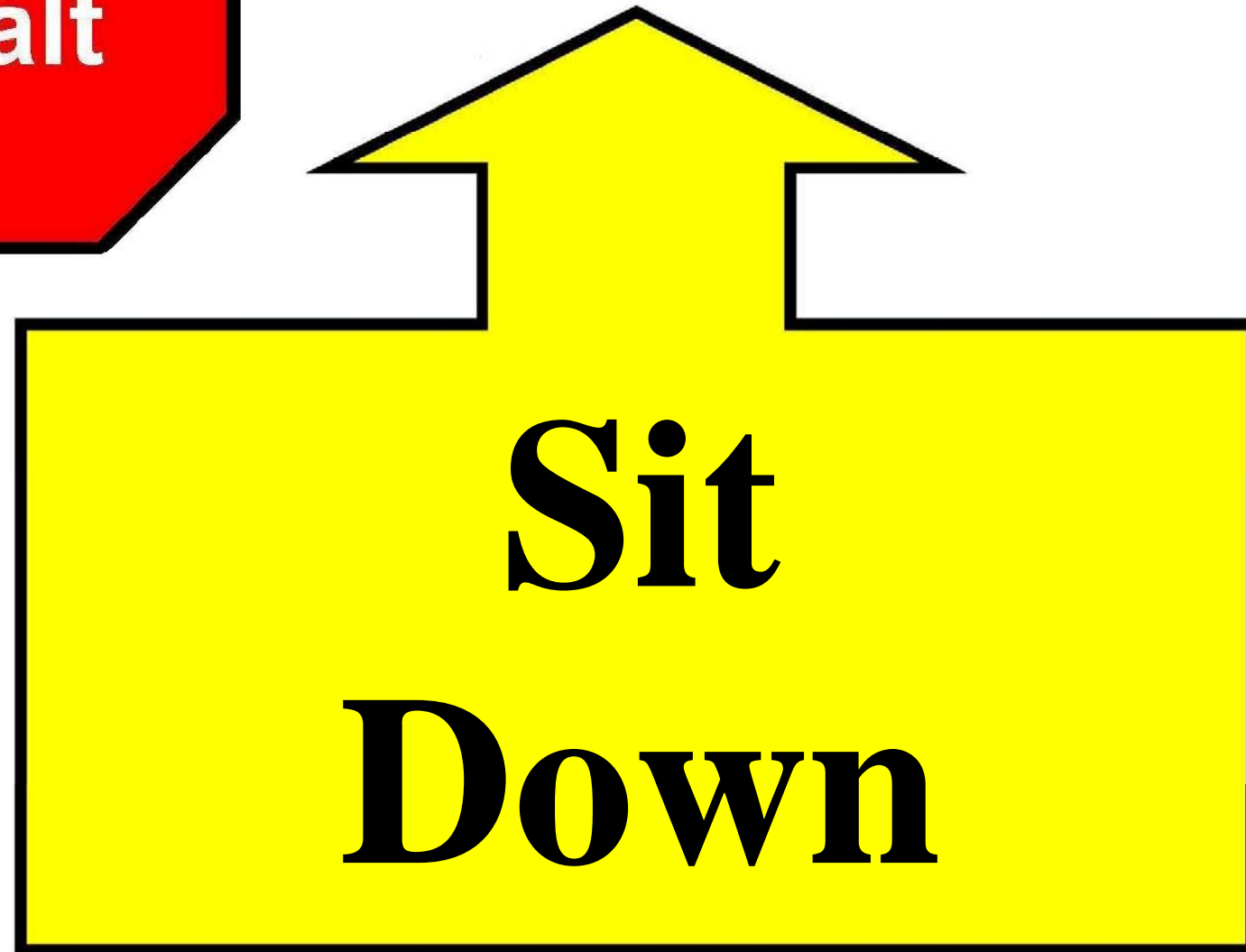
**Start**

**N,I,A,X,M – # 2**

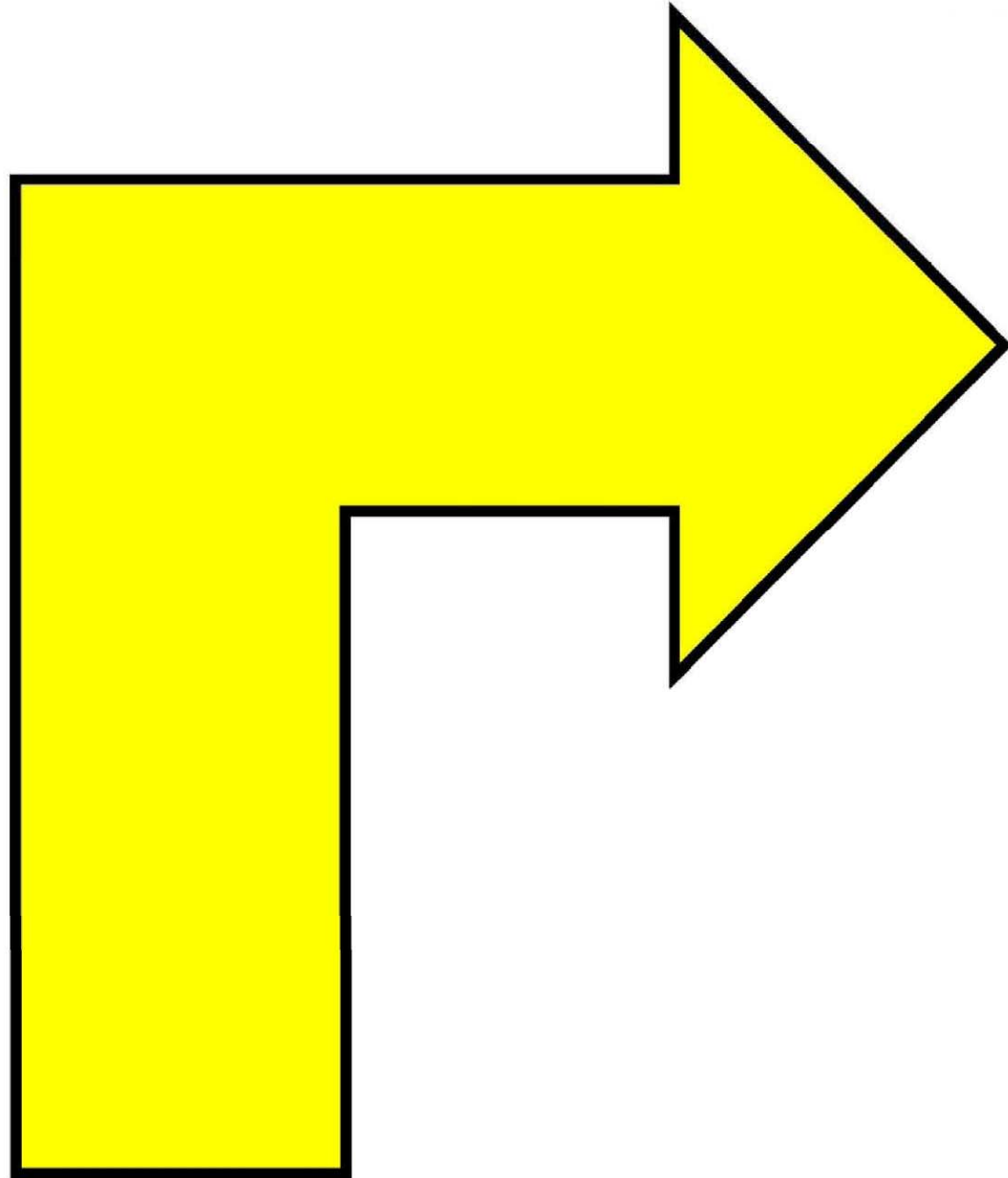


**Finish**

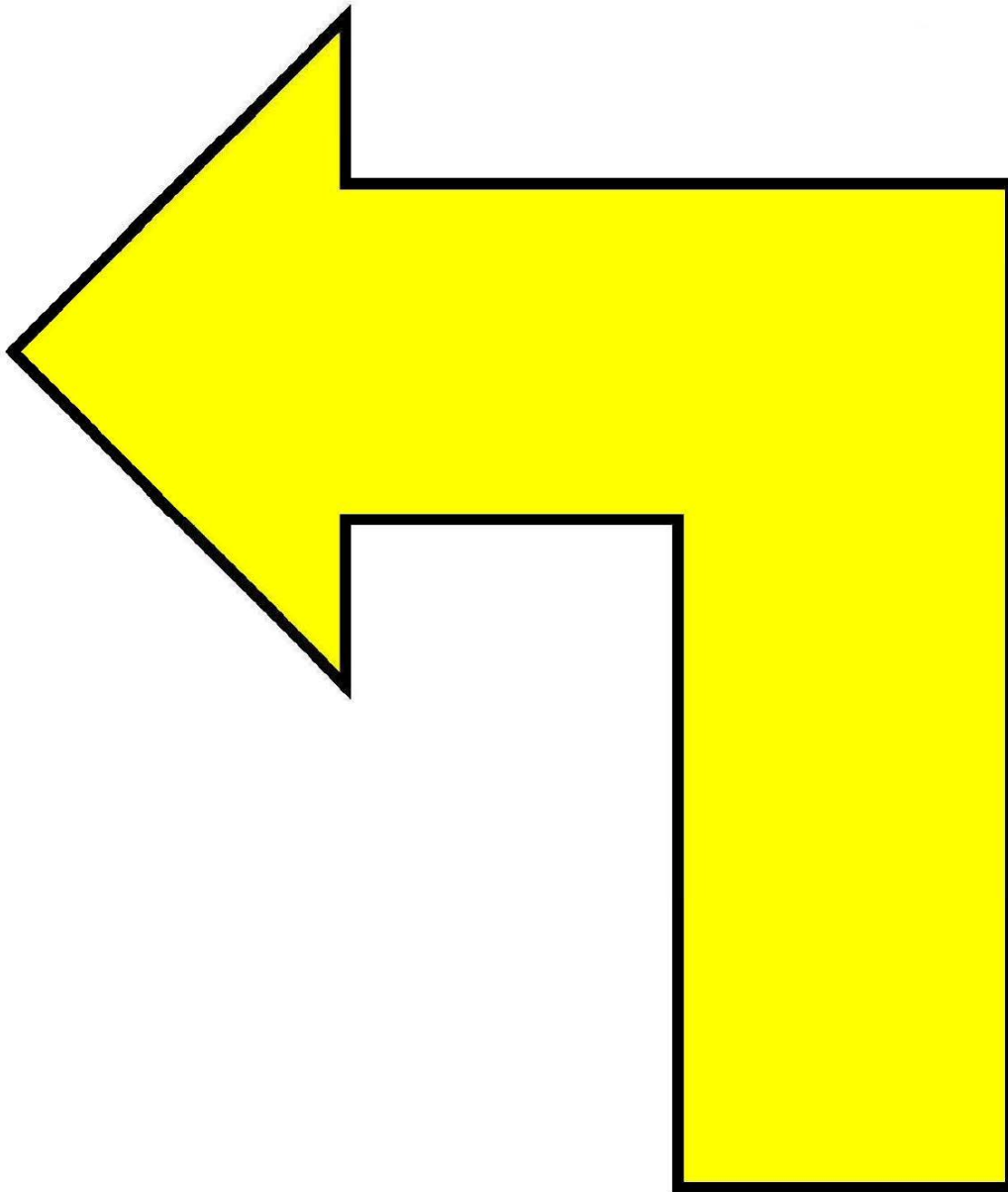




**Right  
Turn**

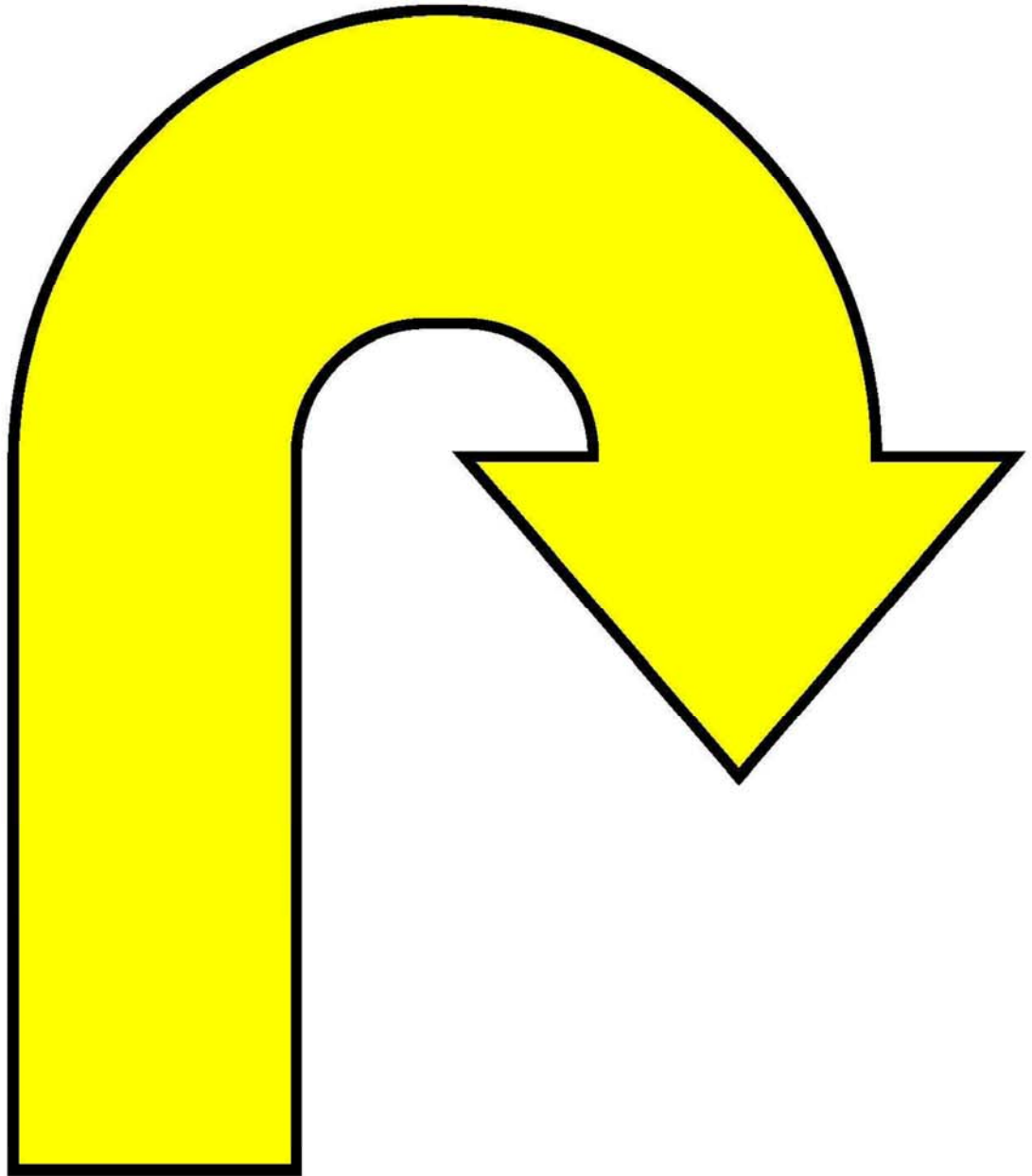


**N,I,A,X,M - # 6**

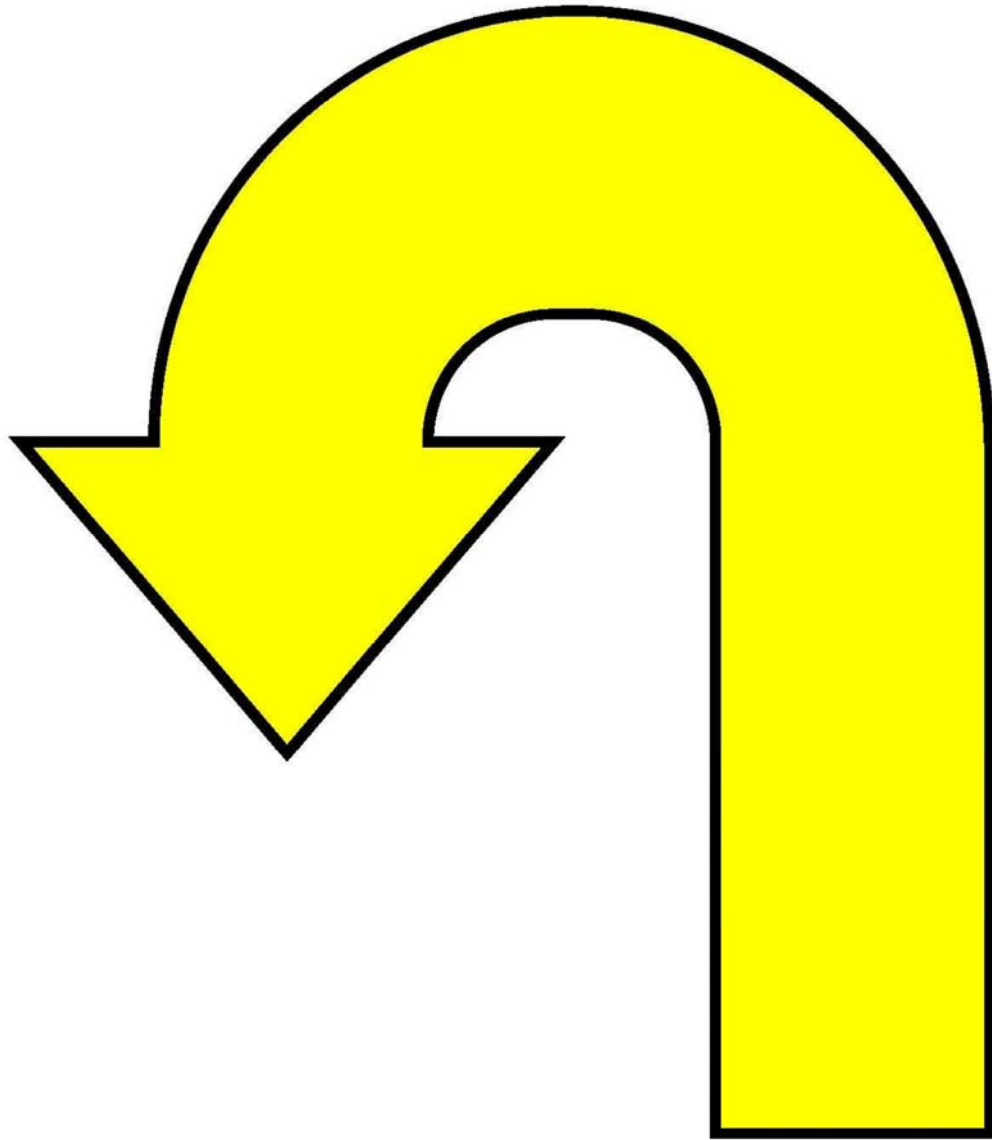


**Left  
Turn**

**About  
Turn  
Right**



**N,I,A,X,M - # 8**



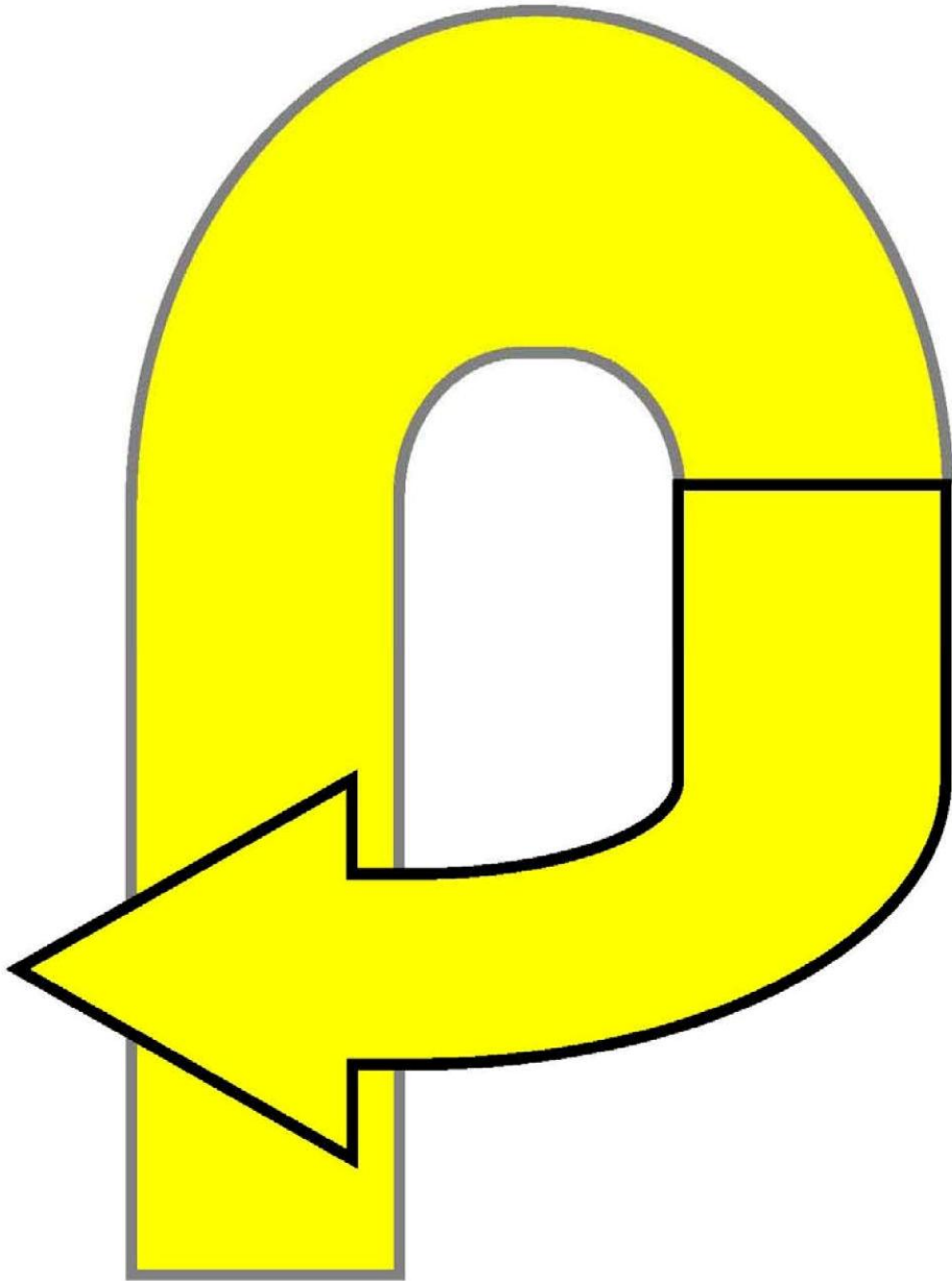
**About**

**“U”**

**Turn**



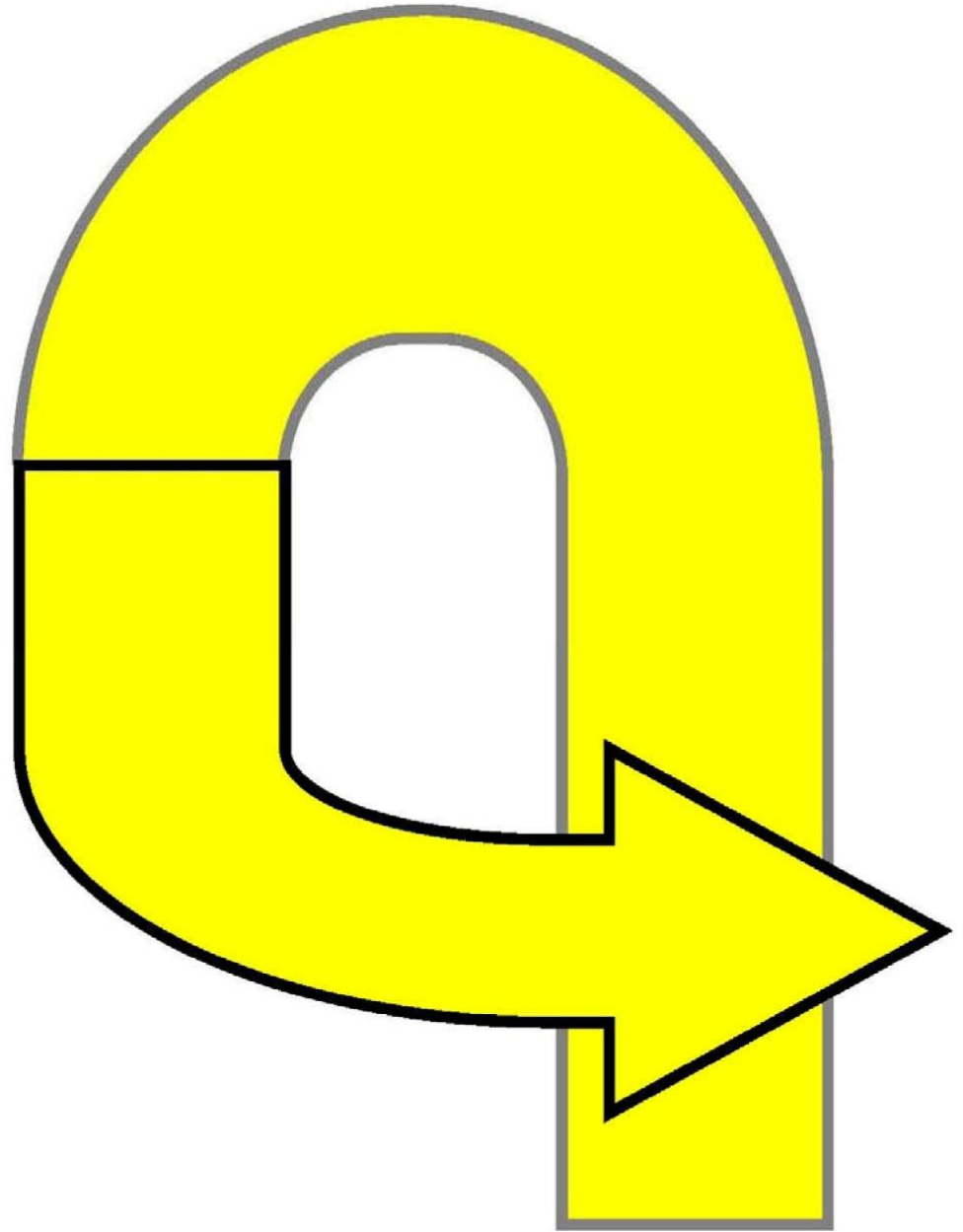
**N,I,A,X,M - # 9**

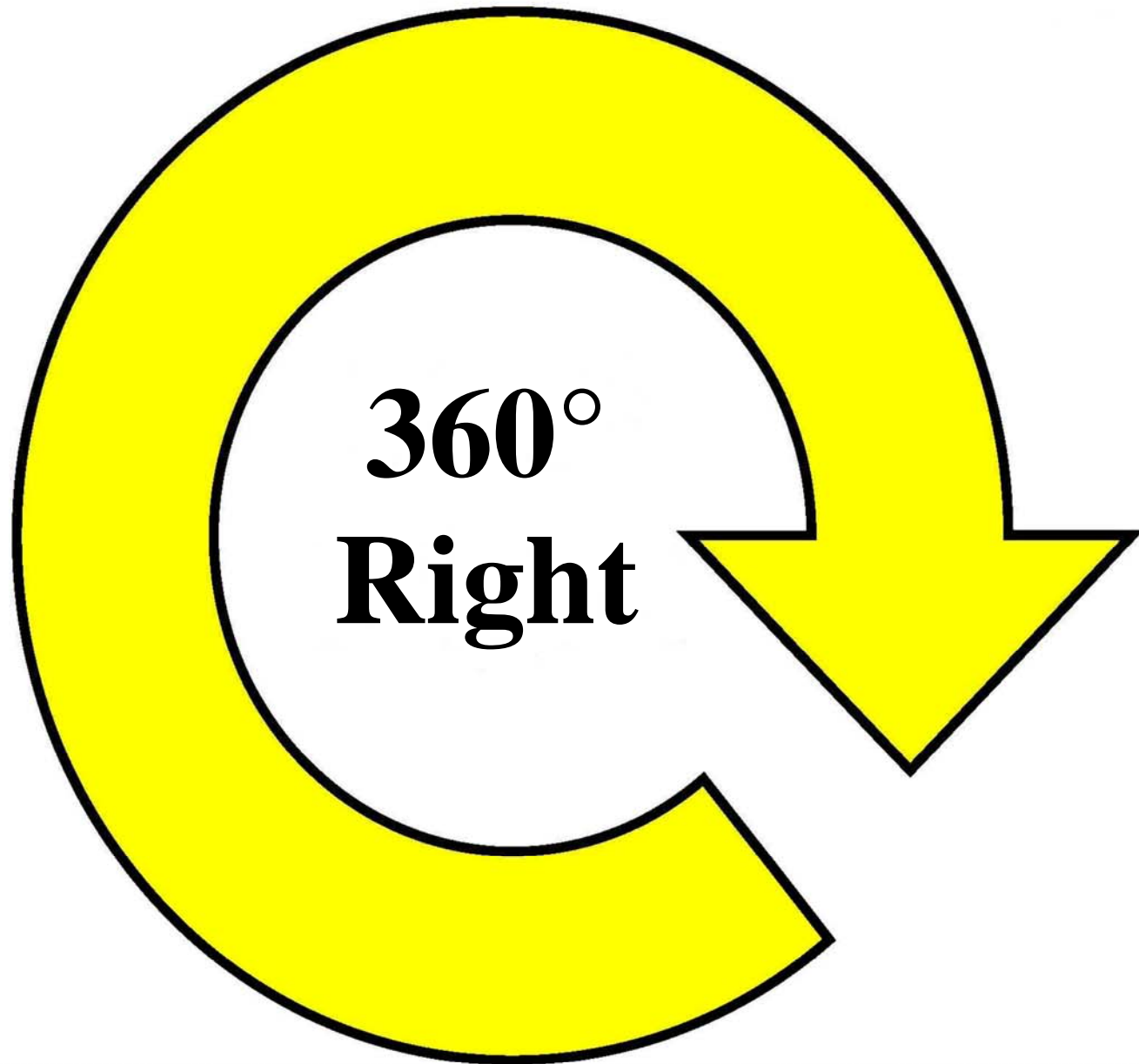


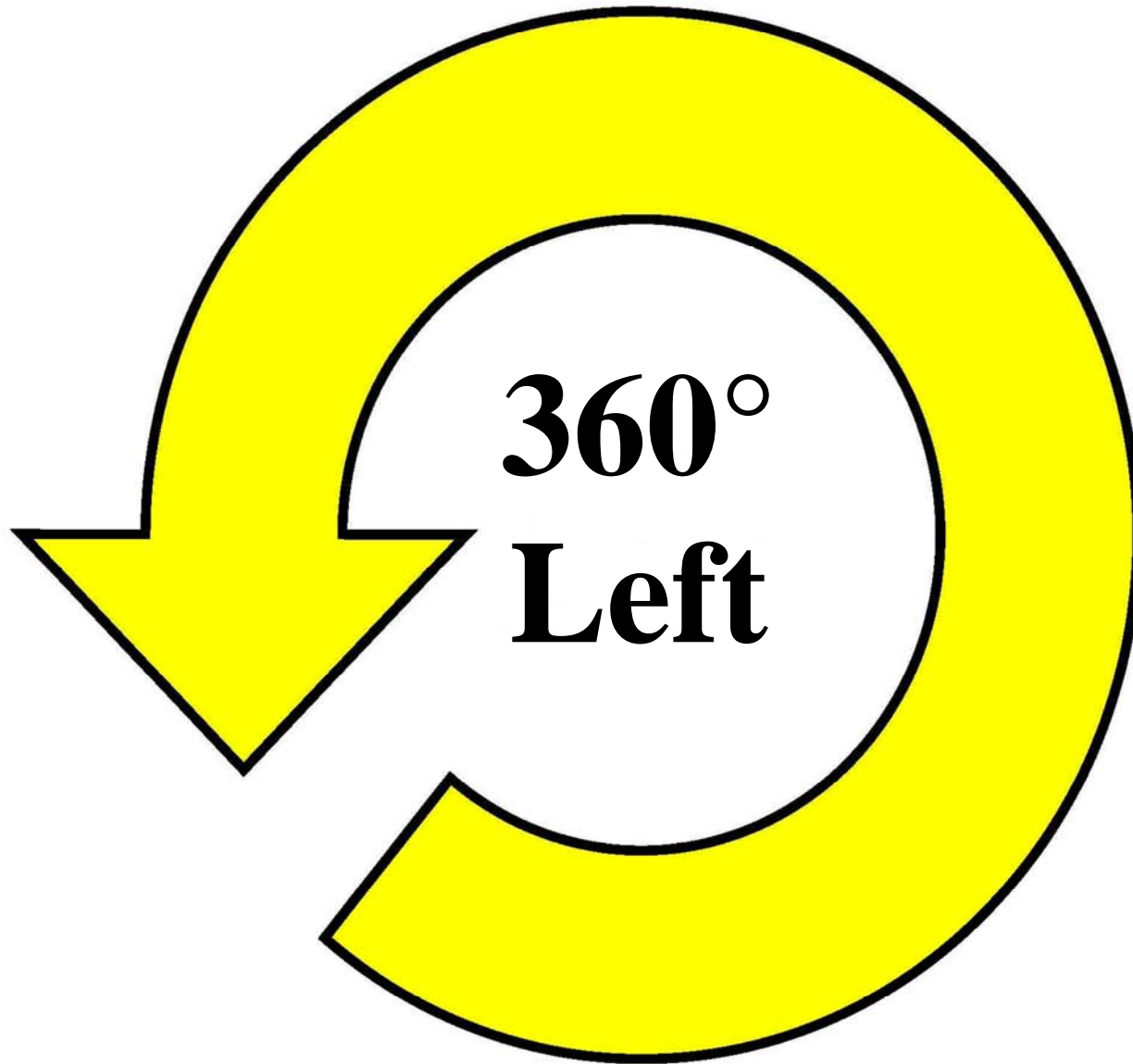
**270°**

**Right**

**270°  
Left**







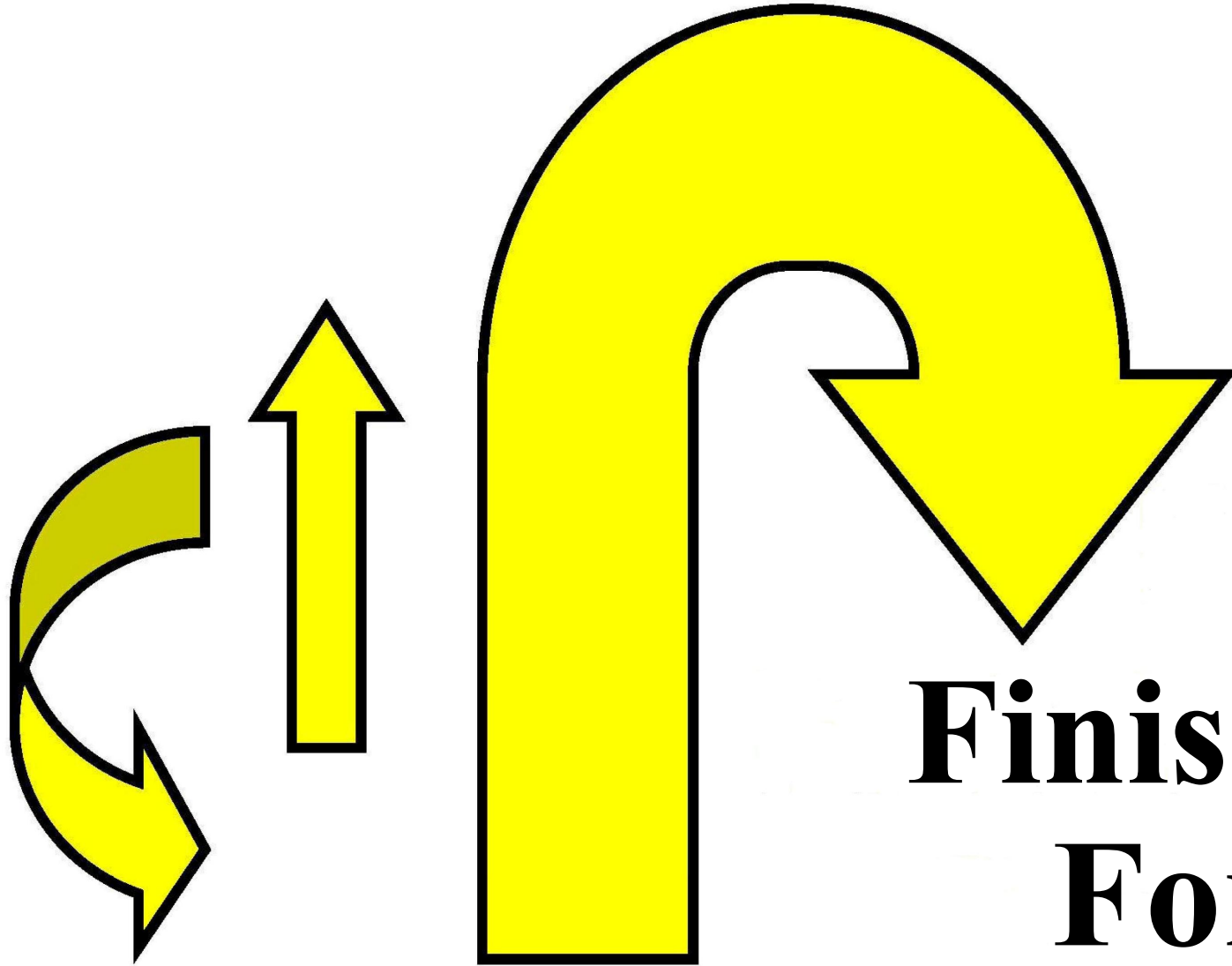
**N,I,A,X,M – # 13**



**Call  
Front**

**Finish Right**

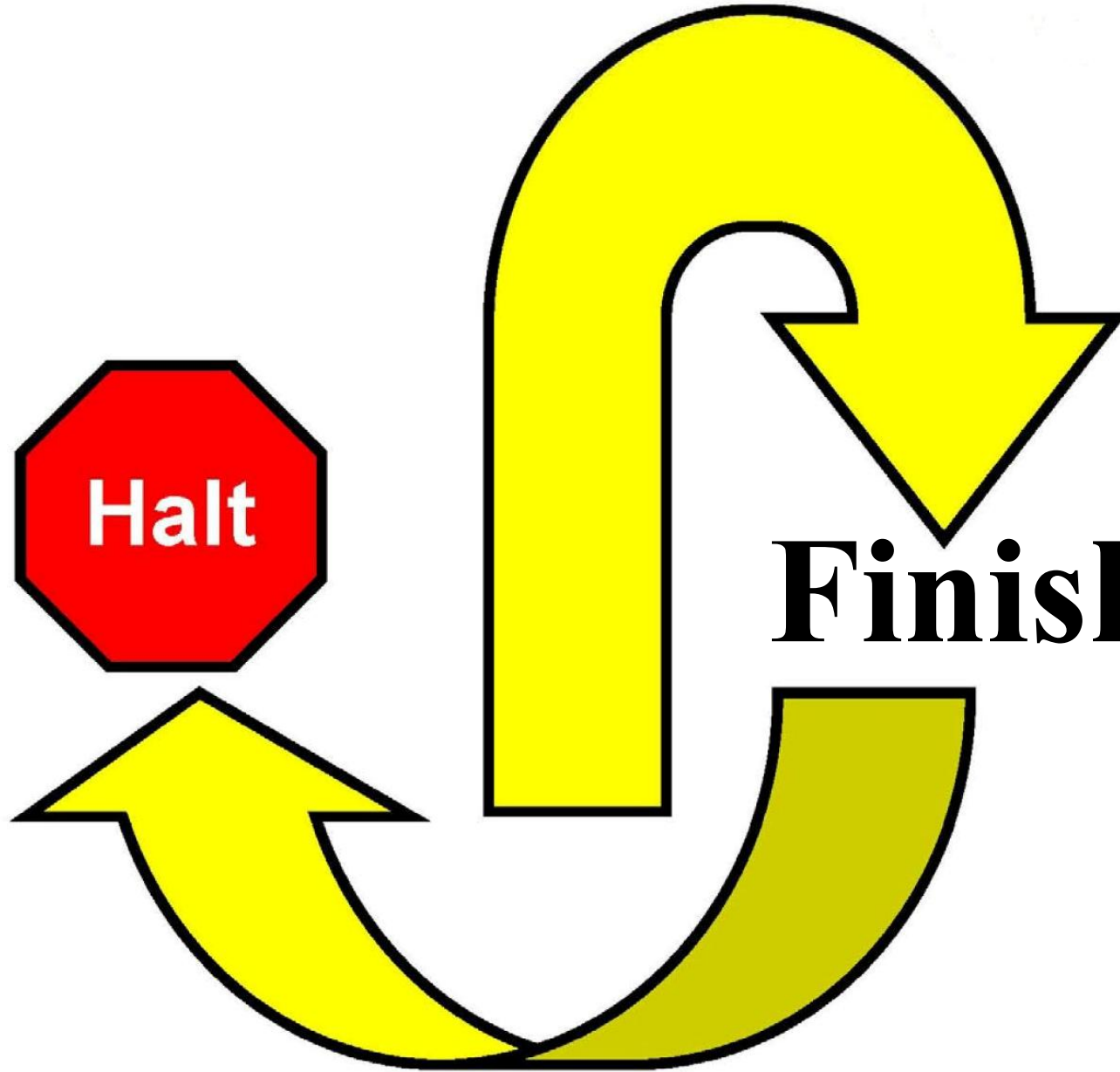
**Forward**



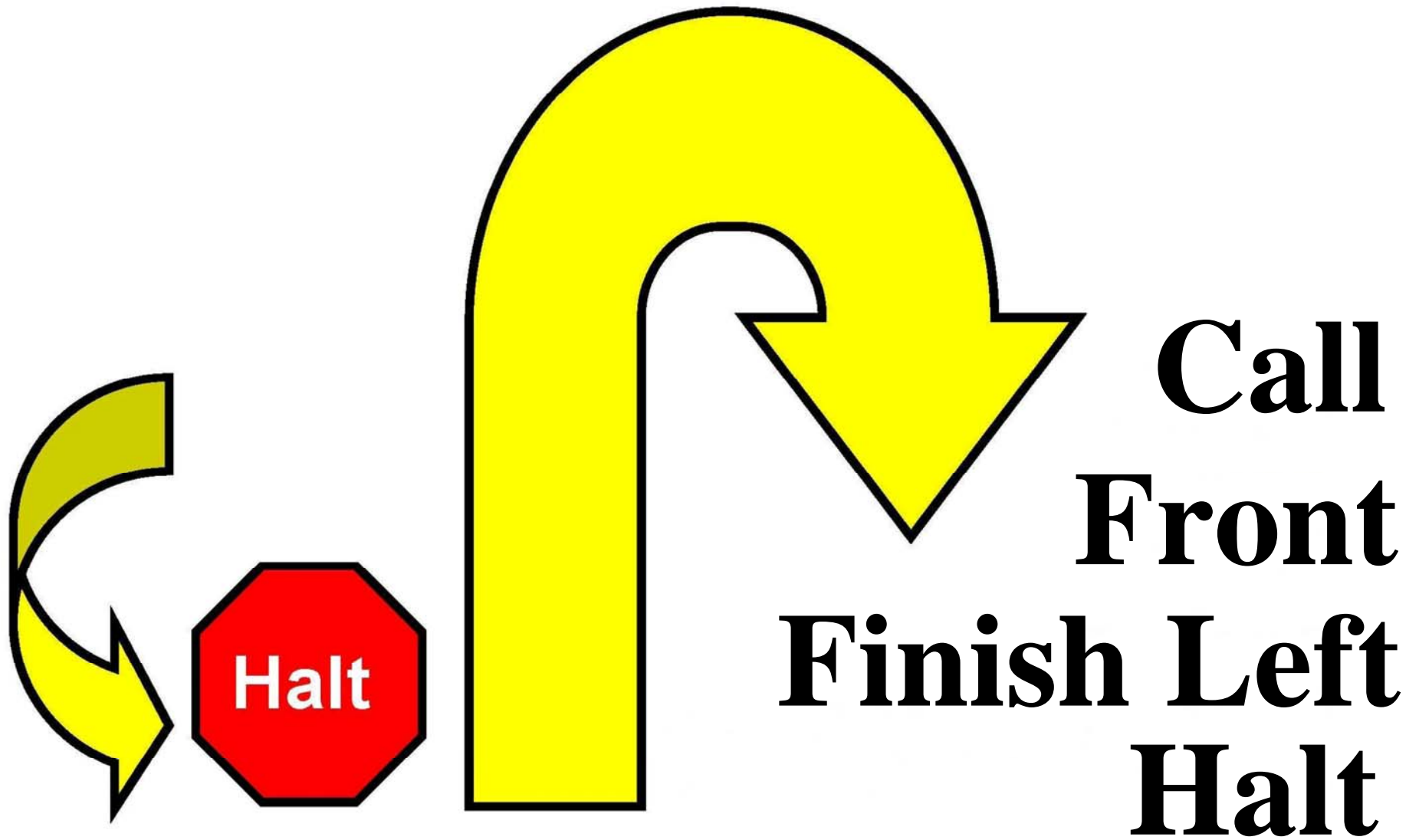
**Call  
Front**

**Finish Left**

**Forward**



**Call  
Front  
Finish Right  
Halt**







**Slow  
Pace**

**N,I,A,X,M – # 18**

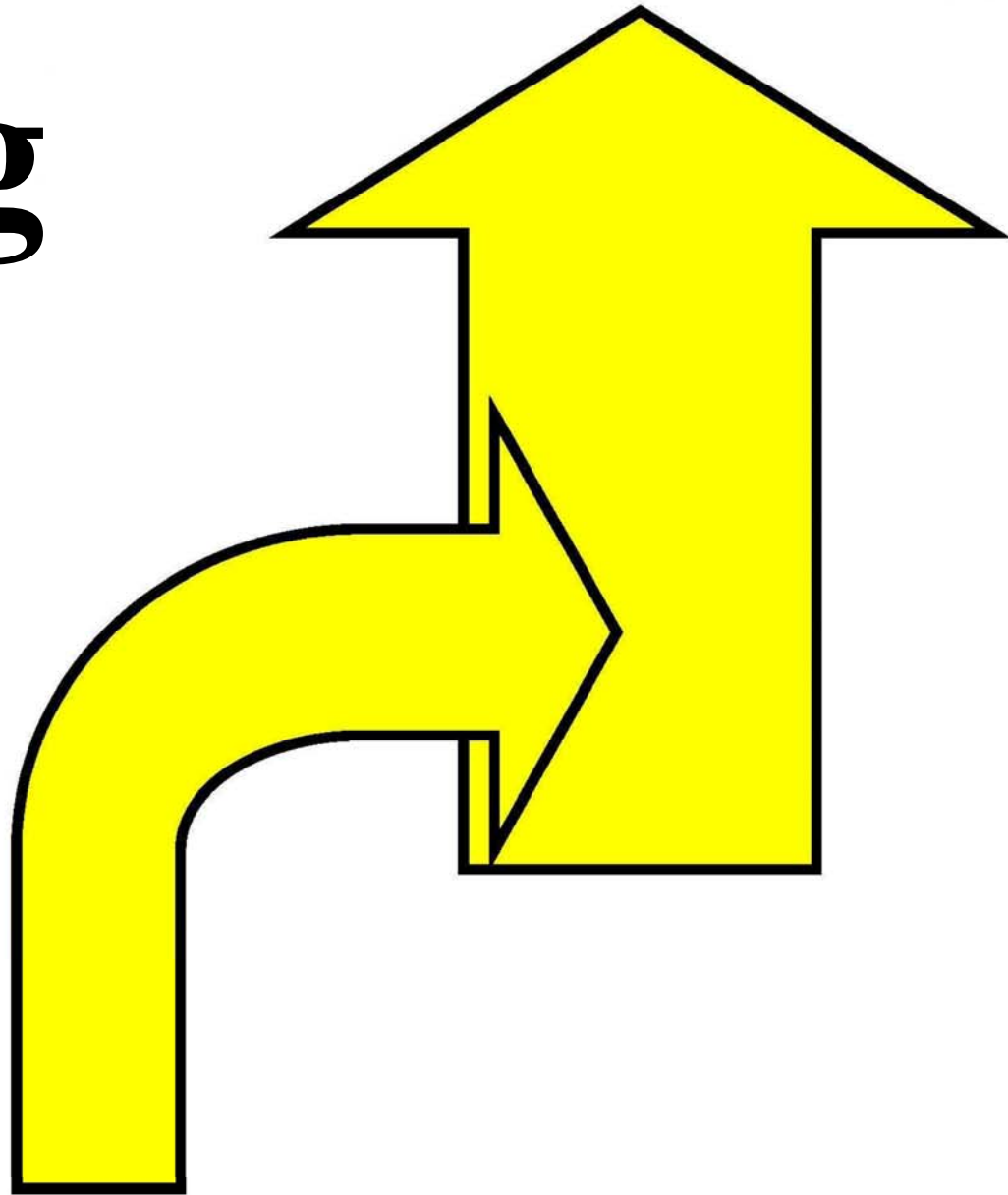


**Fast  
Pace**

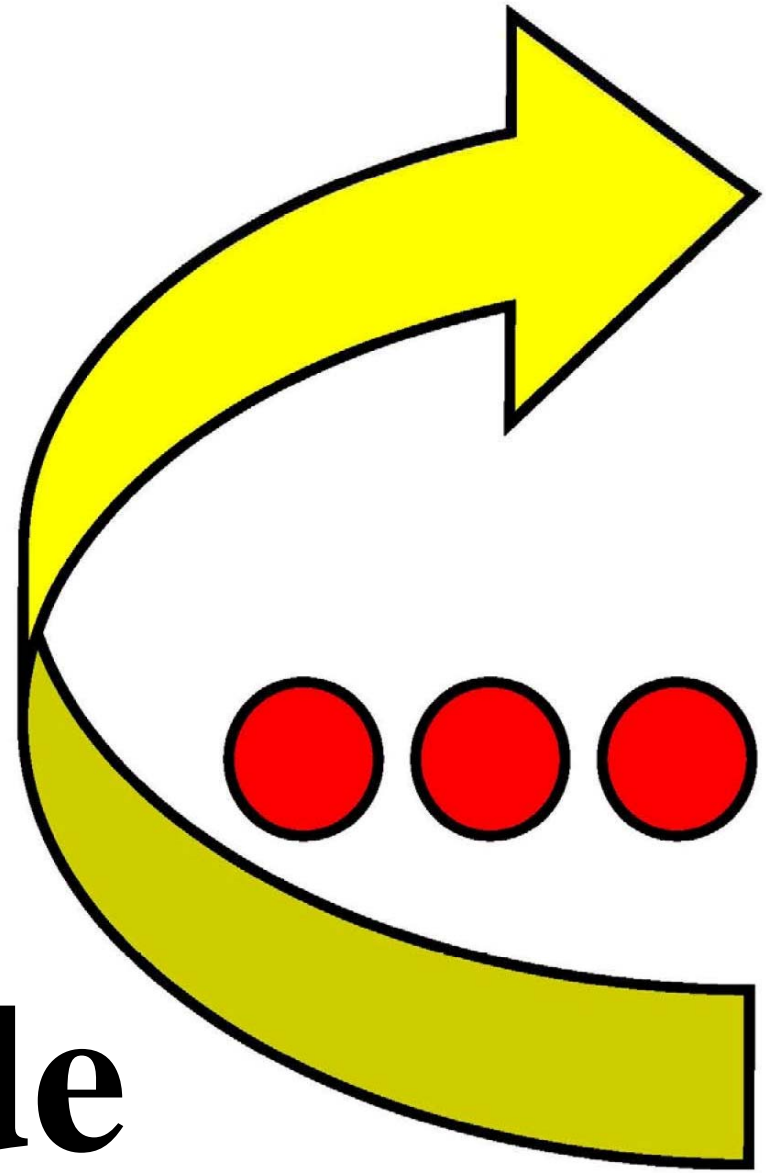


**Normal  
Pace**

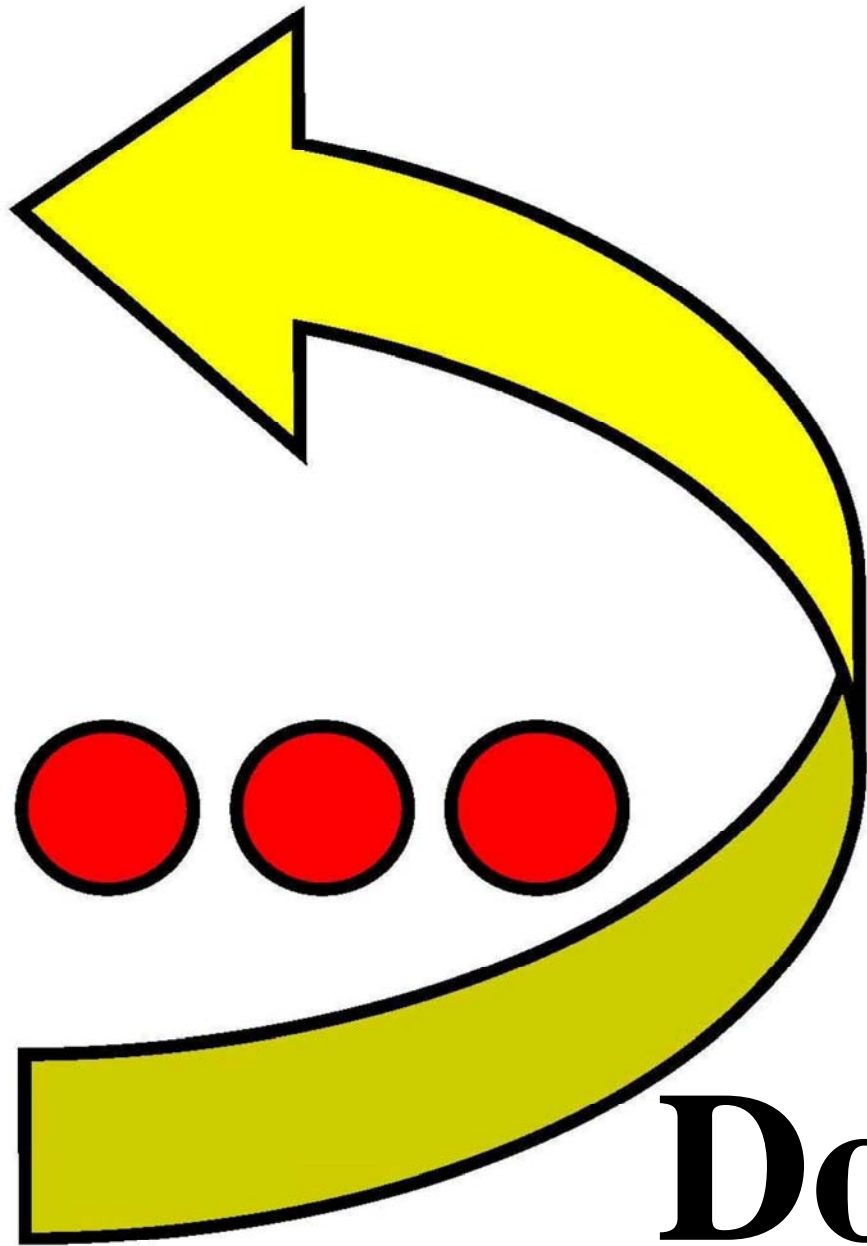
**Moving  
Side  
Step  
Right**



**Spiral  
Right**



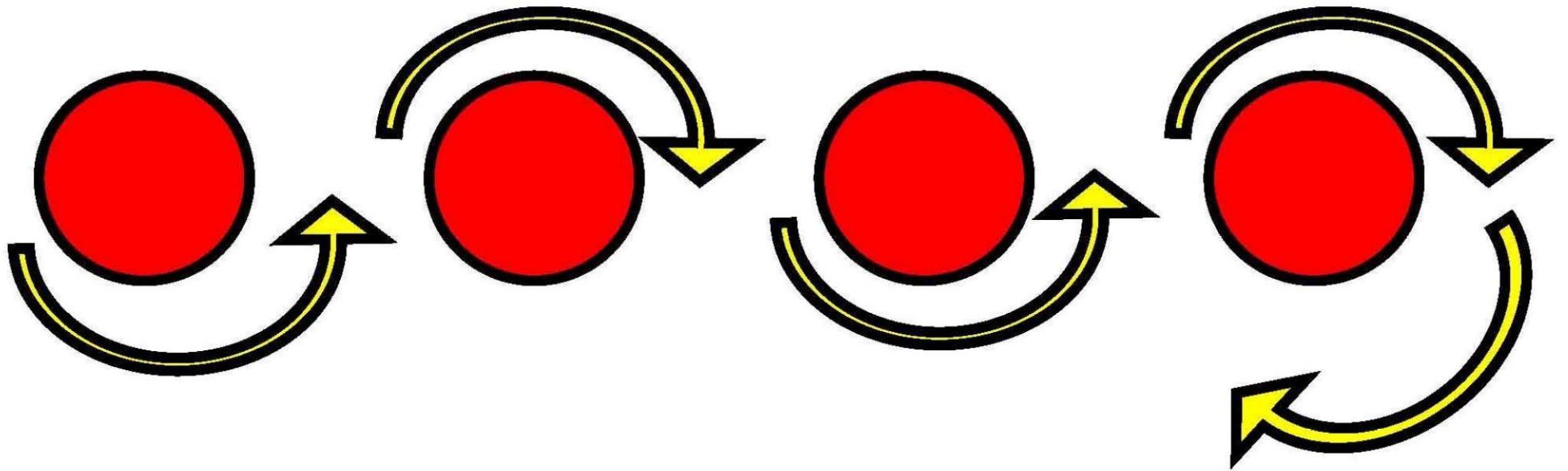
**Dog Outside**



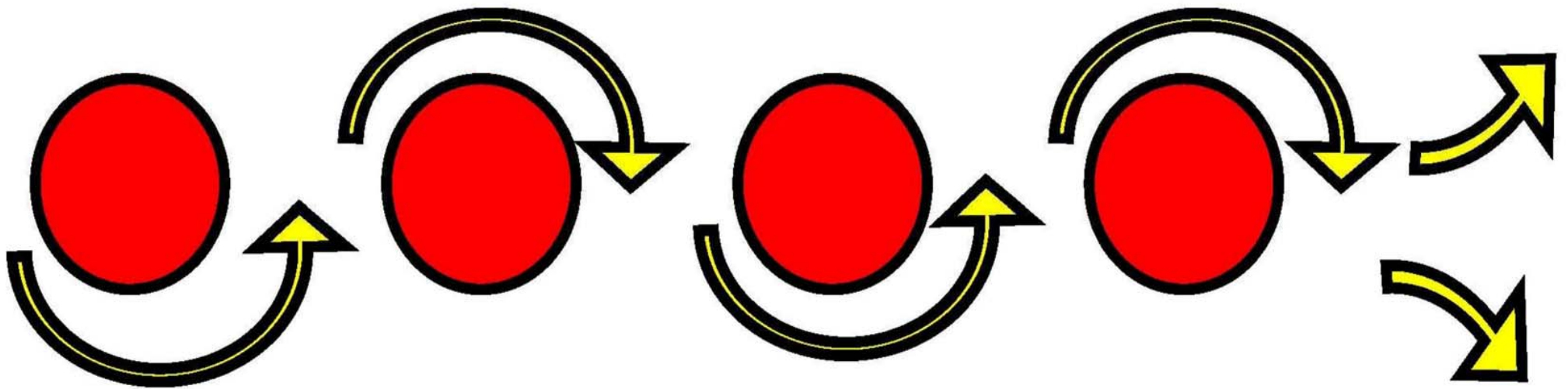
**Spiral  
Left**

**Dog Inside**

# **Serpentine Weave Twice**



# **Serpentine Weave Once**







**1 Step**

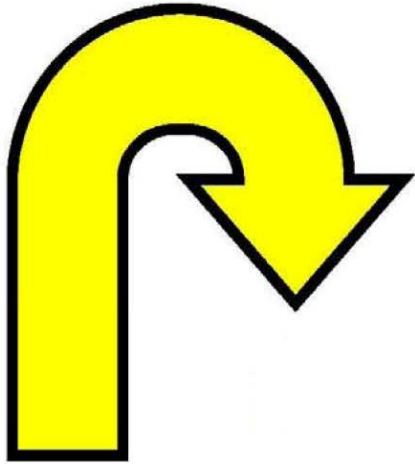


**2 Steps**



**3 Steps**





# Call Front

**1 Step Back**



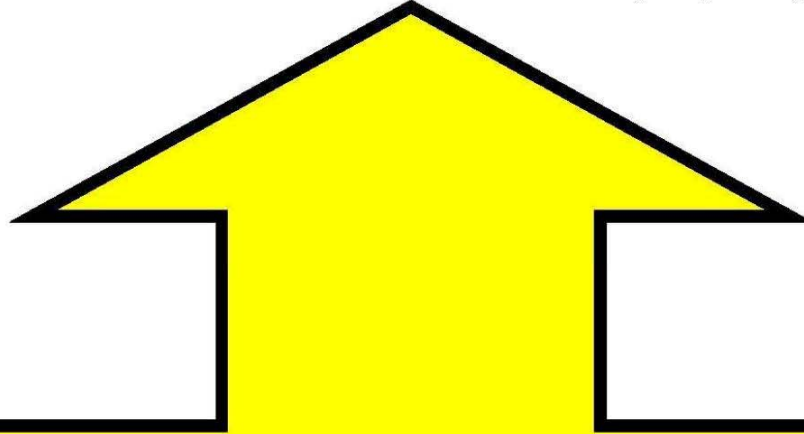
**2 Steps Back**



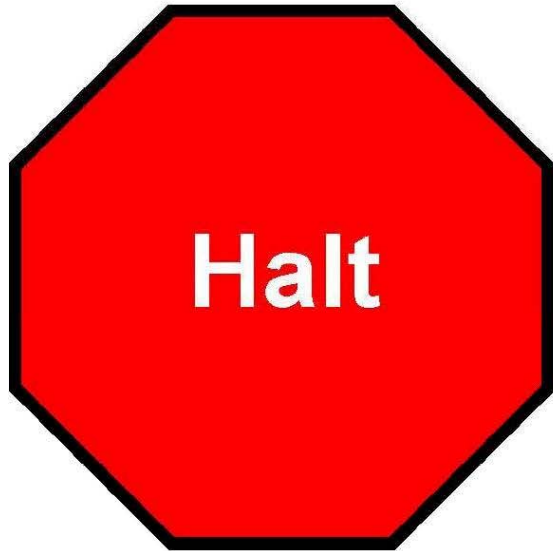
**3 Steps Back**



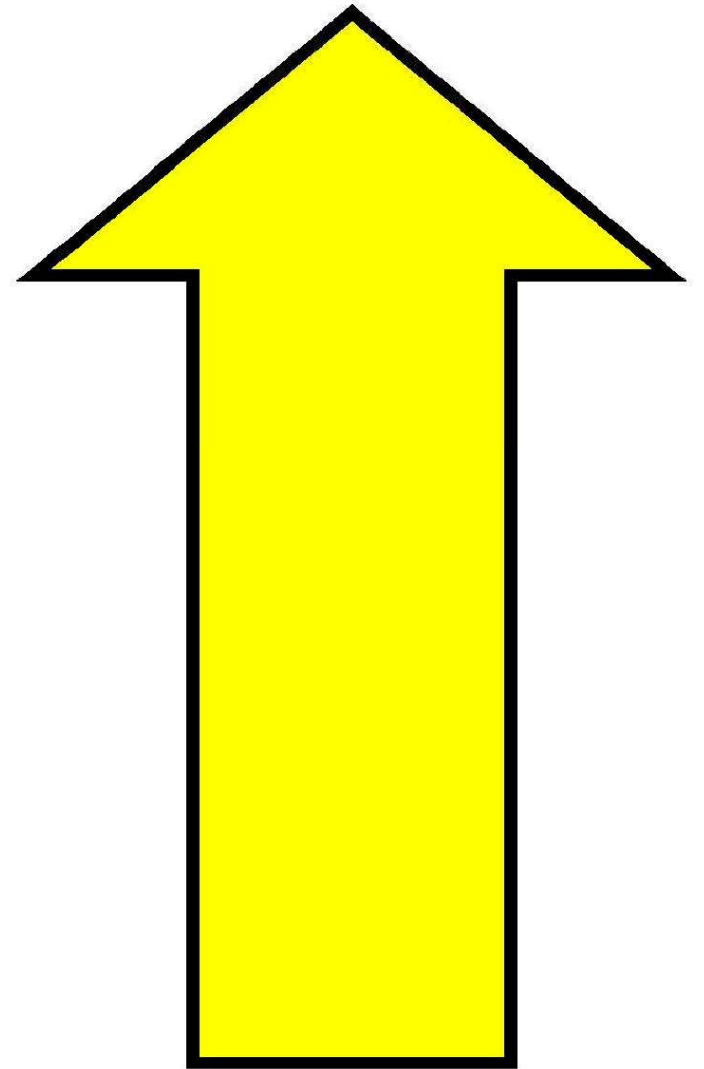
**N,I,A,X,M – # 27**



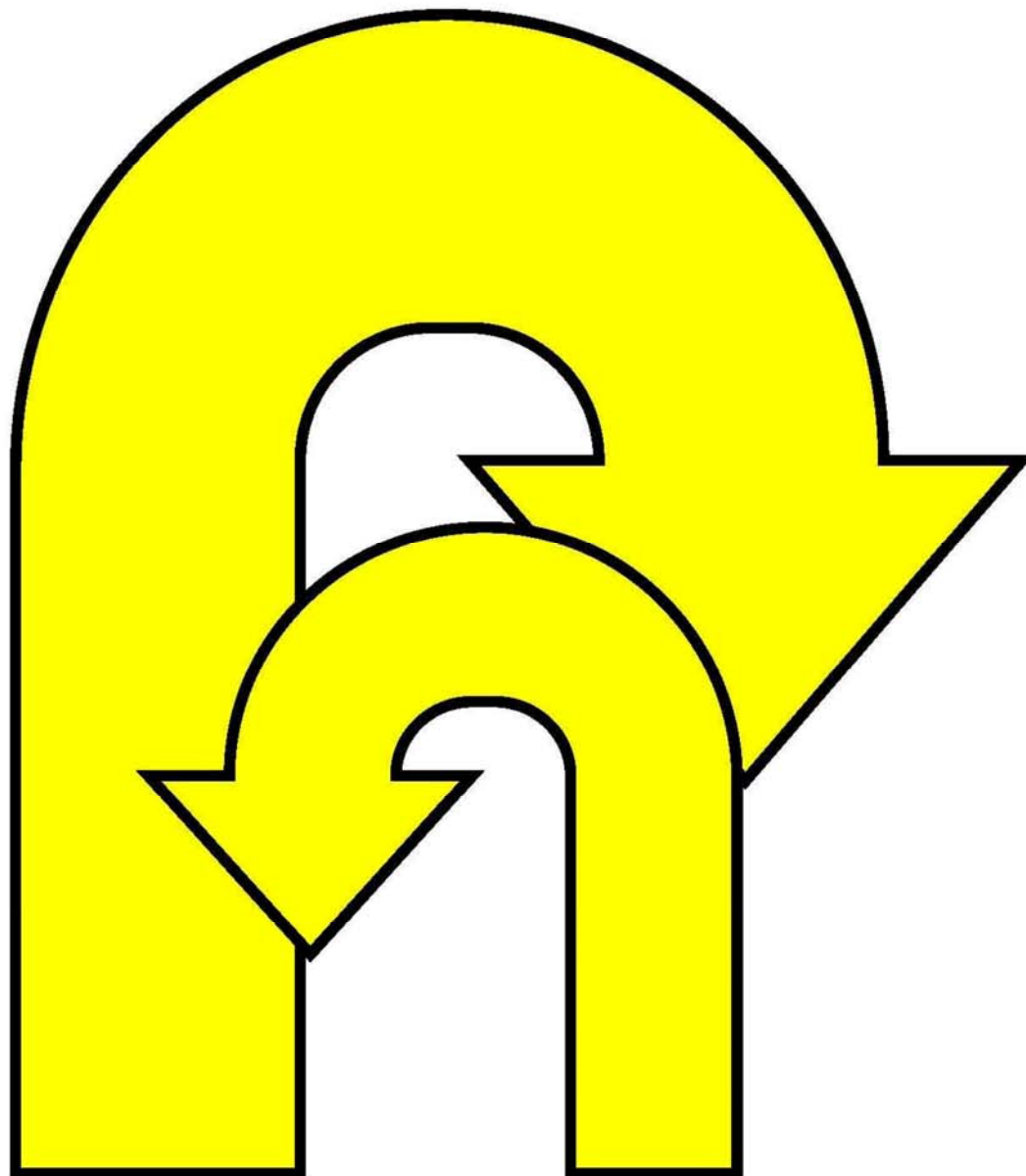
**Down  
and  
Stop**

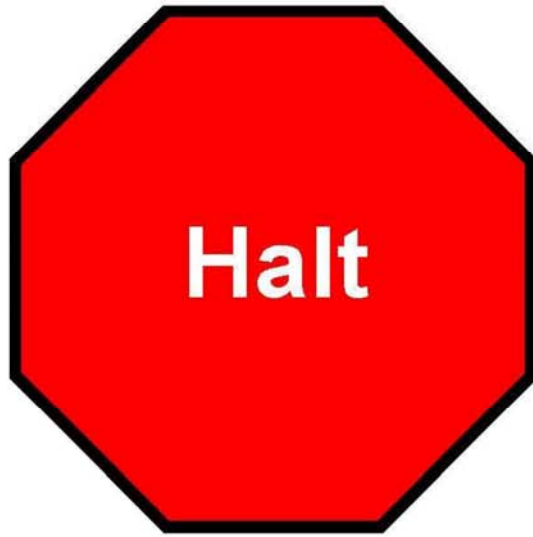


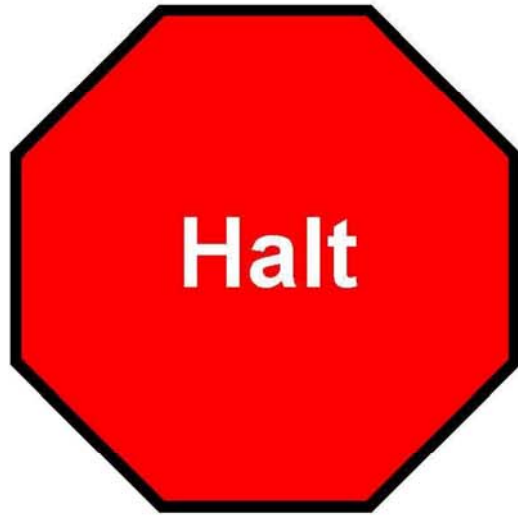
**Fast  
Forward  
From Sit**

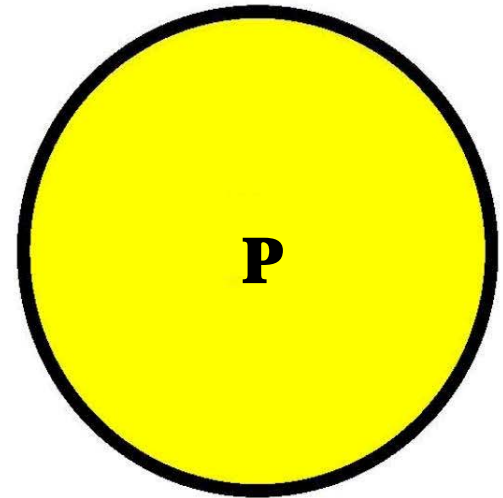
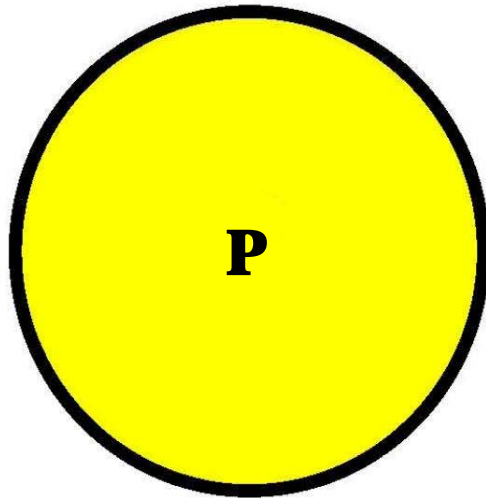


**Left  
About  
Turn**





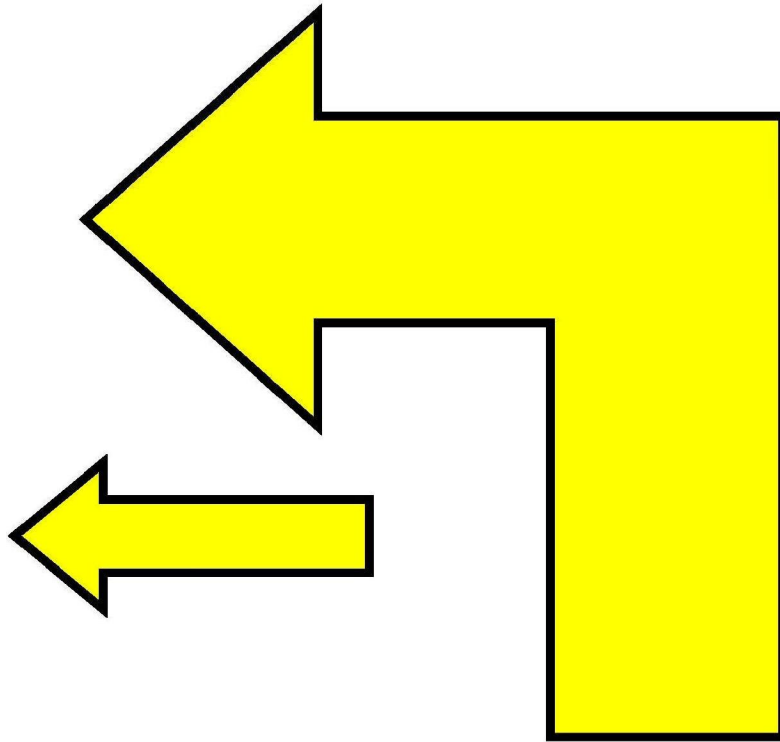




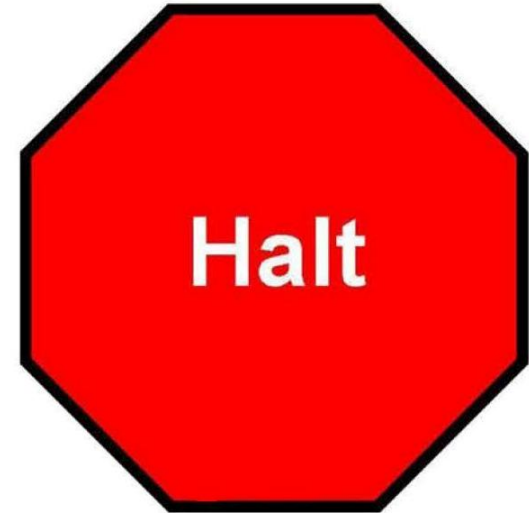
**Figure 8**

**No Distractions**



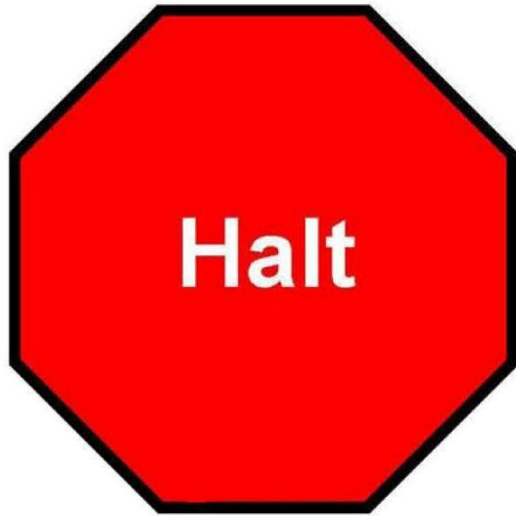


**Forward**



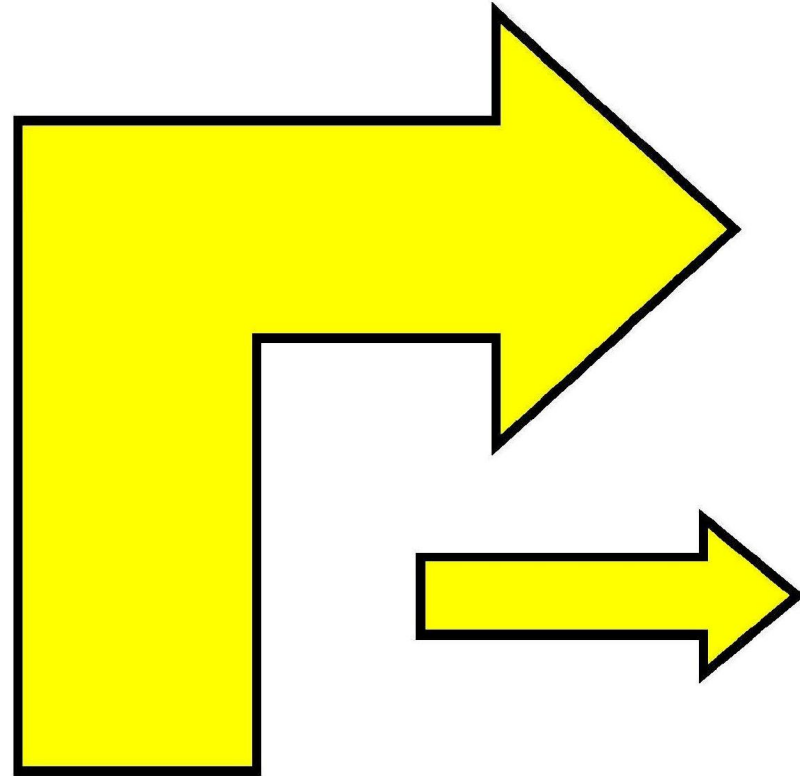
**Left**

**Turn**

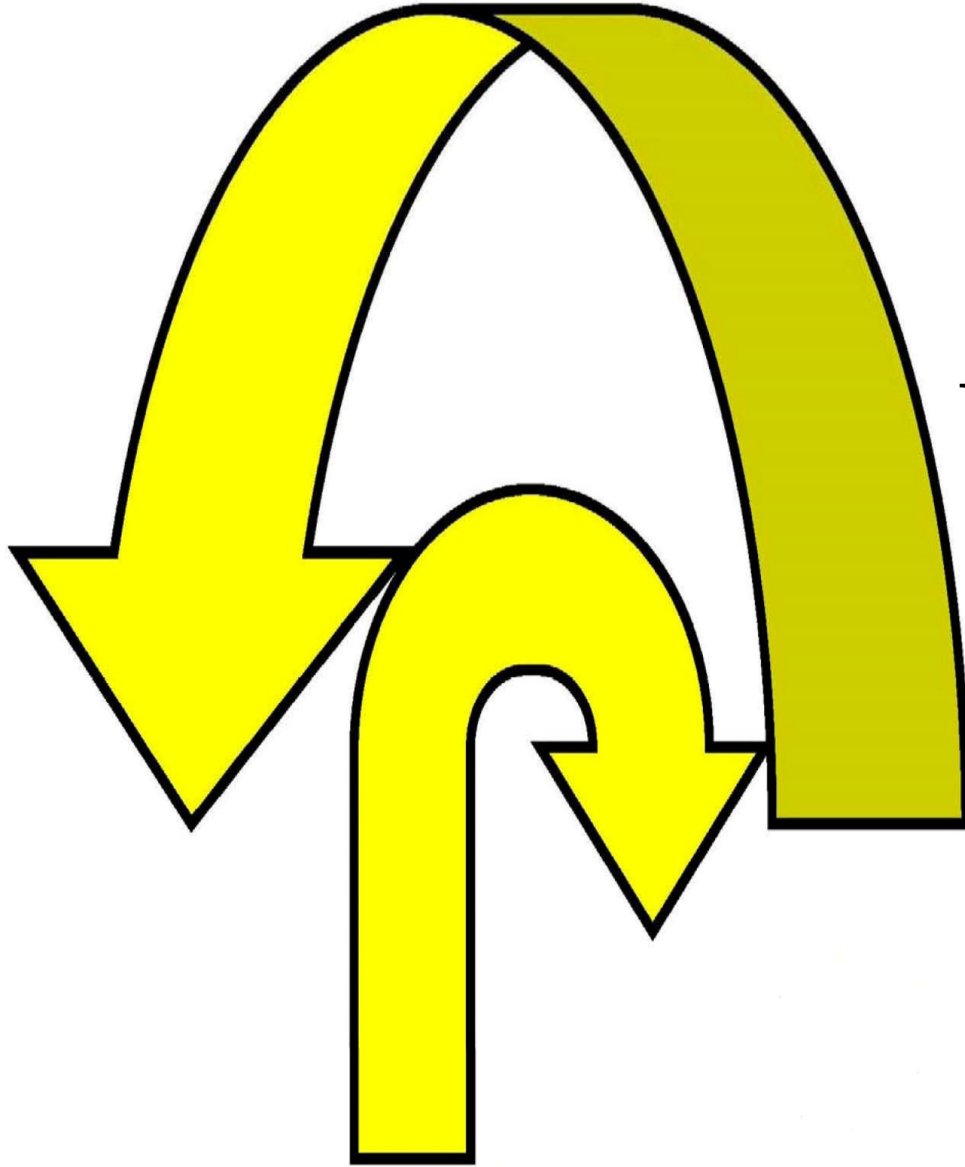


**Right**

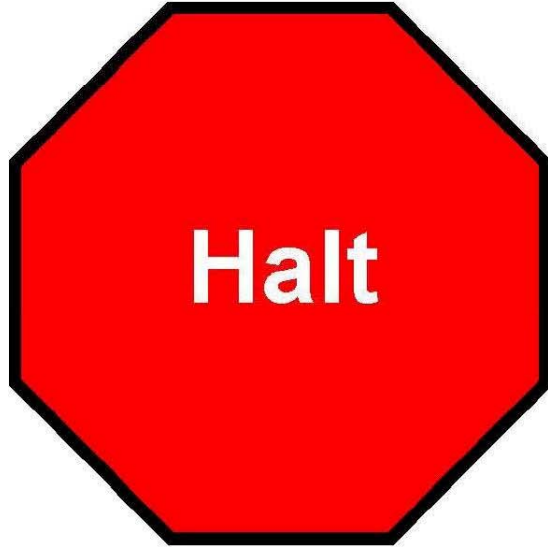
**Turn**



**Forward**

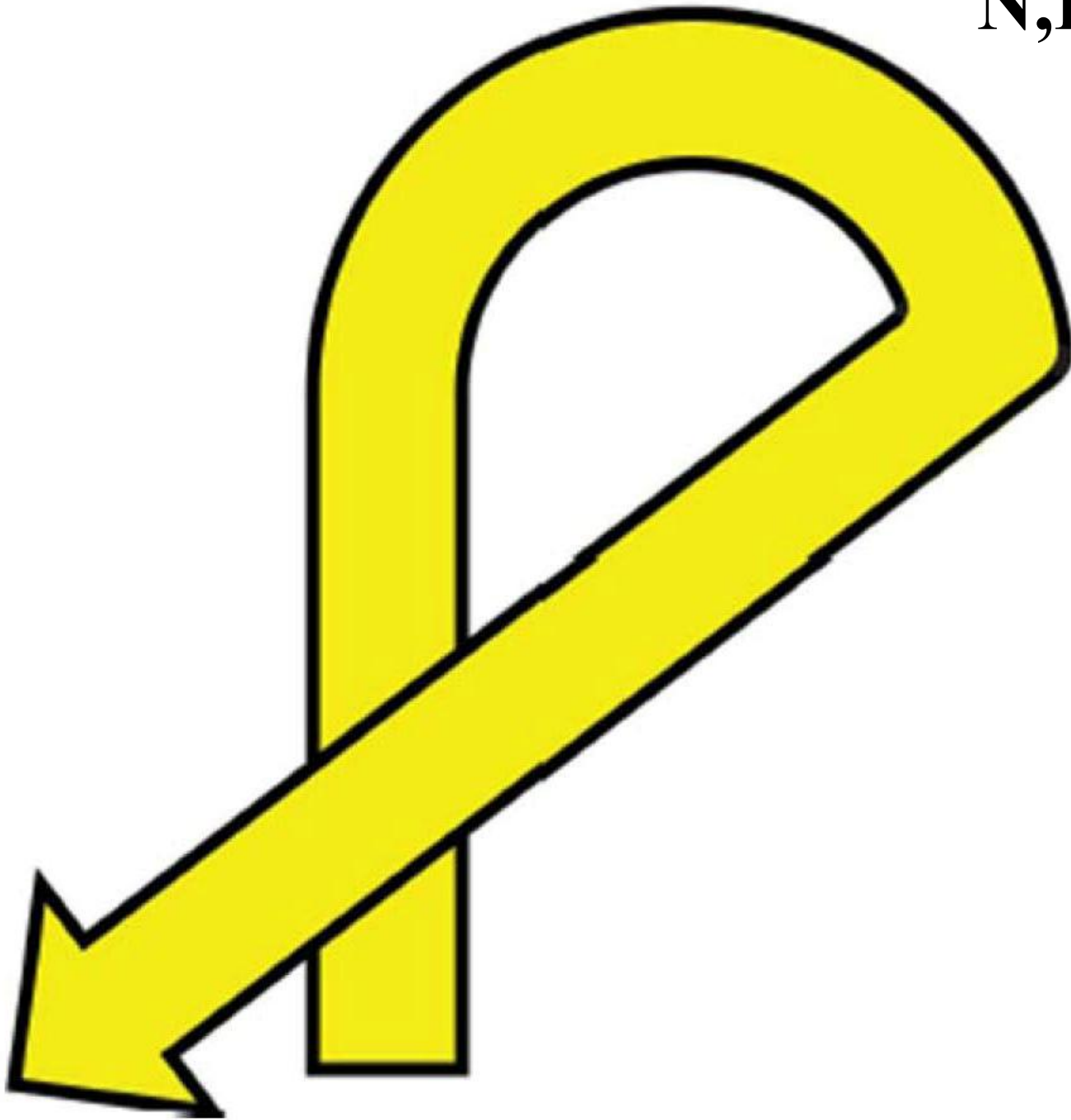


**Call Front  
Walk Around  
Dog**



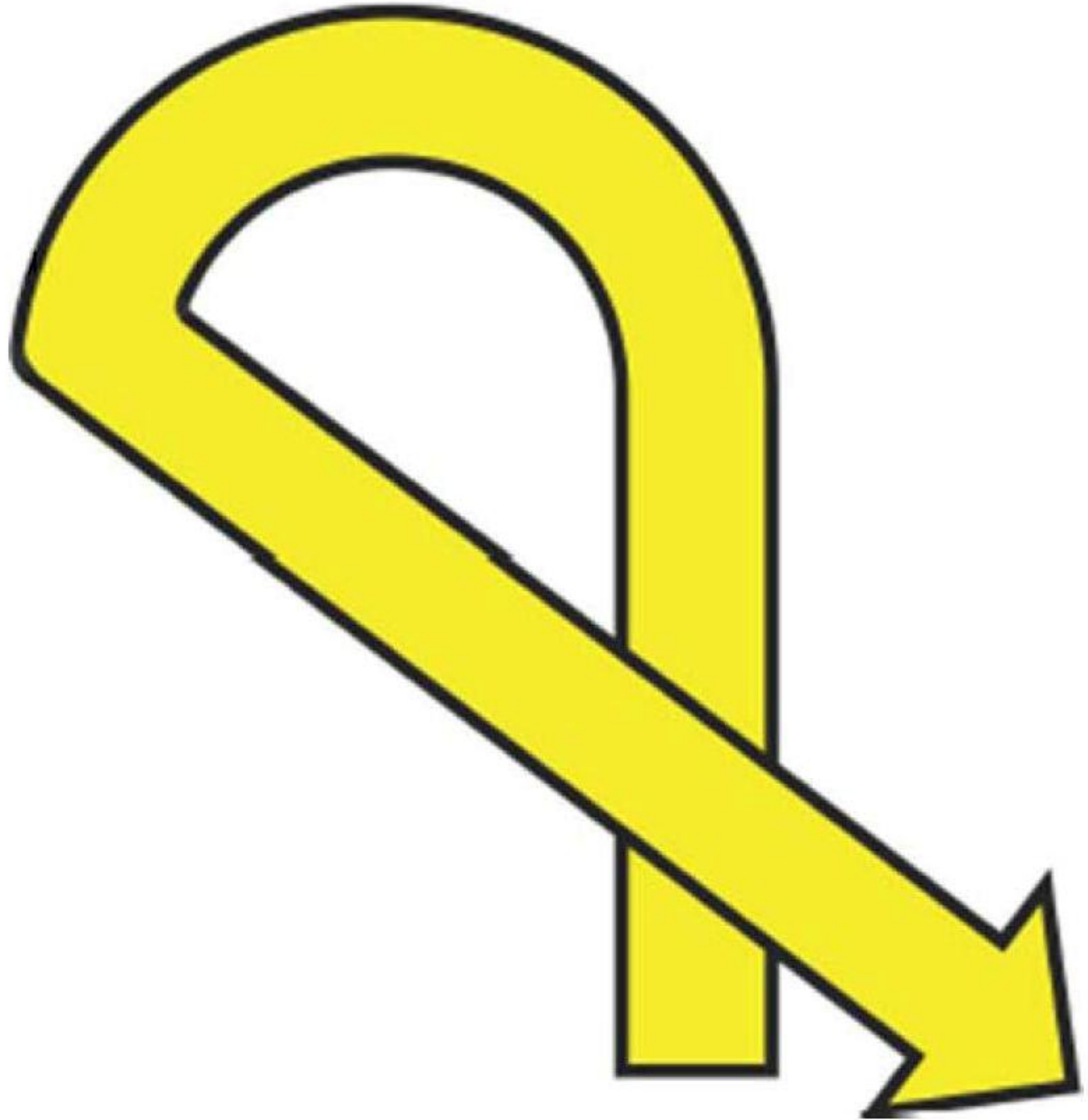
**Slow Forward  
From Sit**

**N,I,A,X,M – # 37**

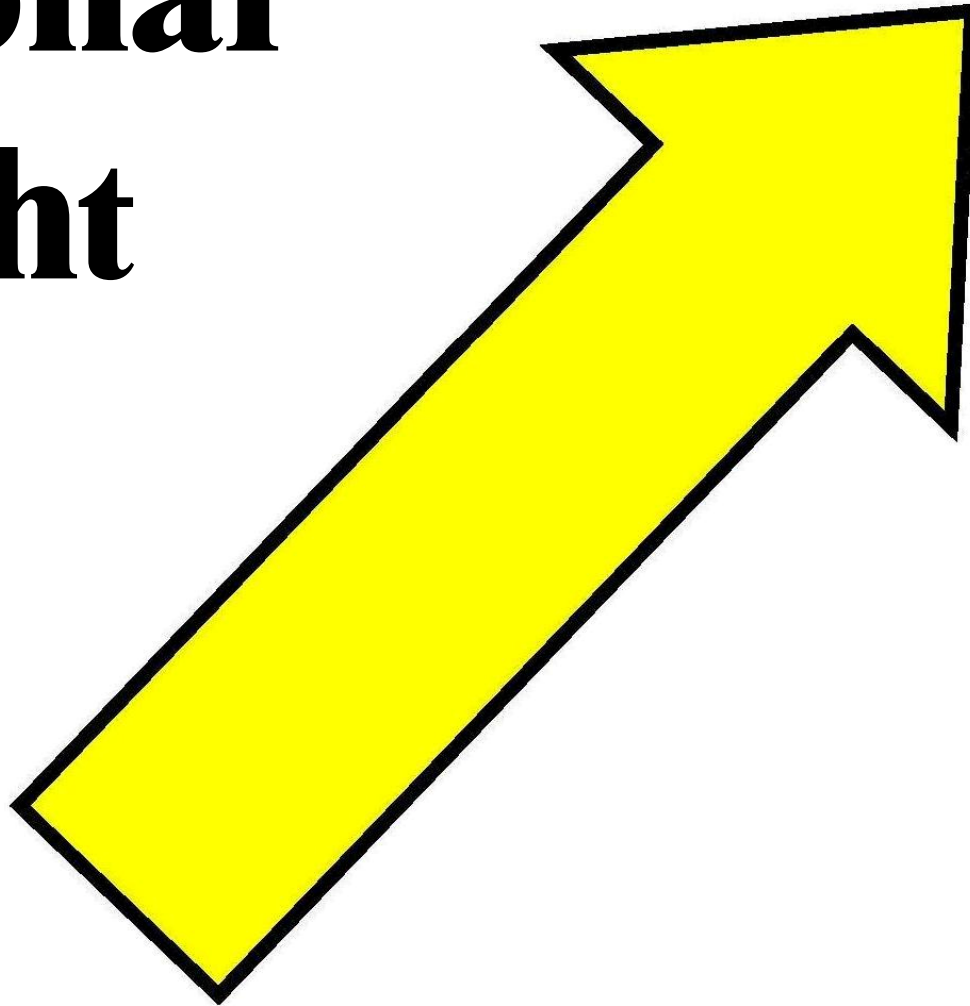


**Loop  
Right**

**Loop  
Left**

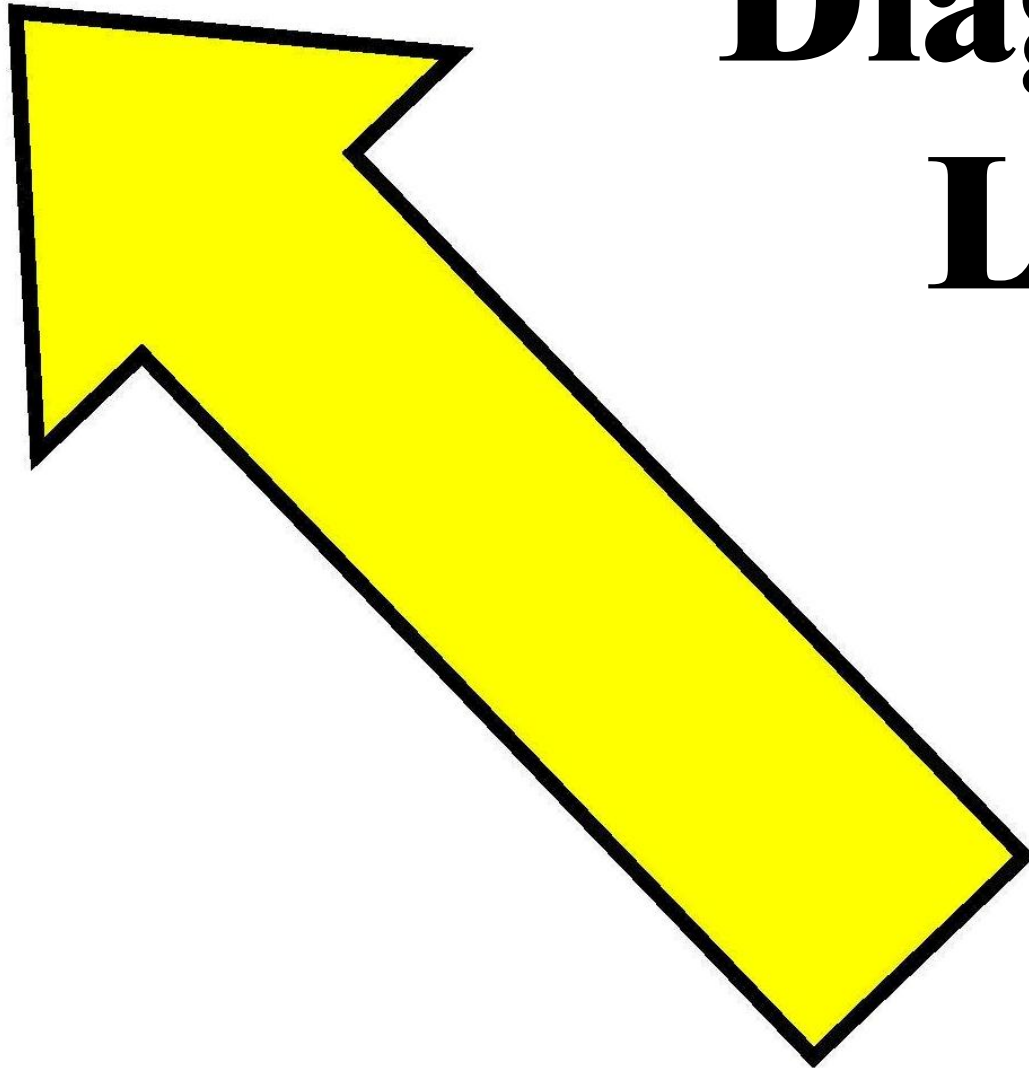


**Diagonal  
Right**



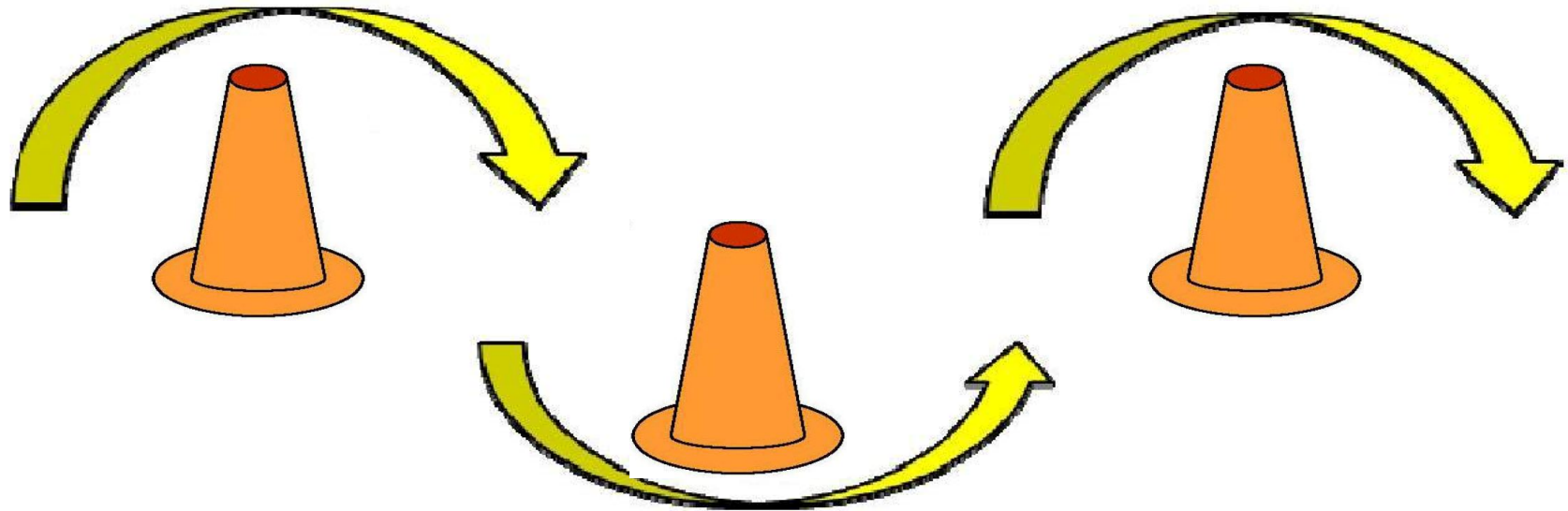
**N,I,A,X,M – # 40**

**Diagonal  
Left**

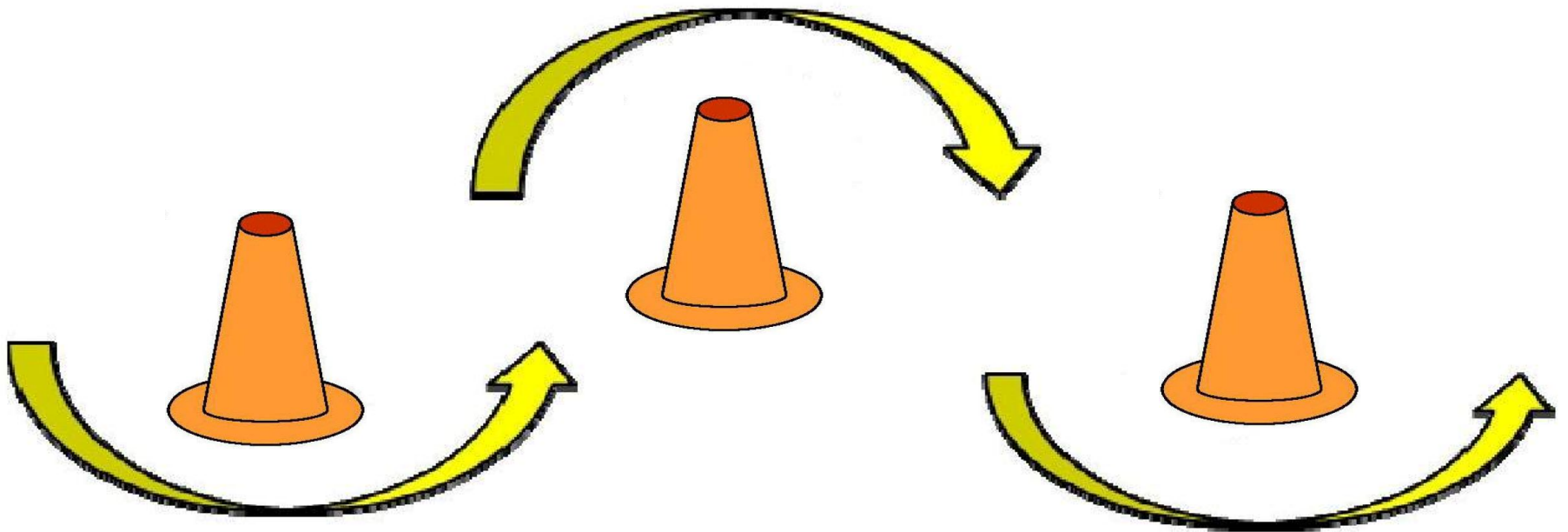


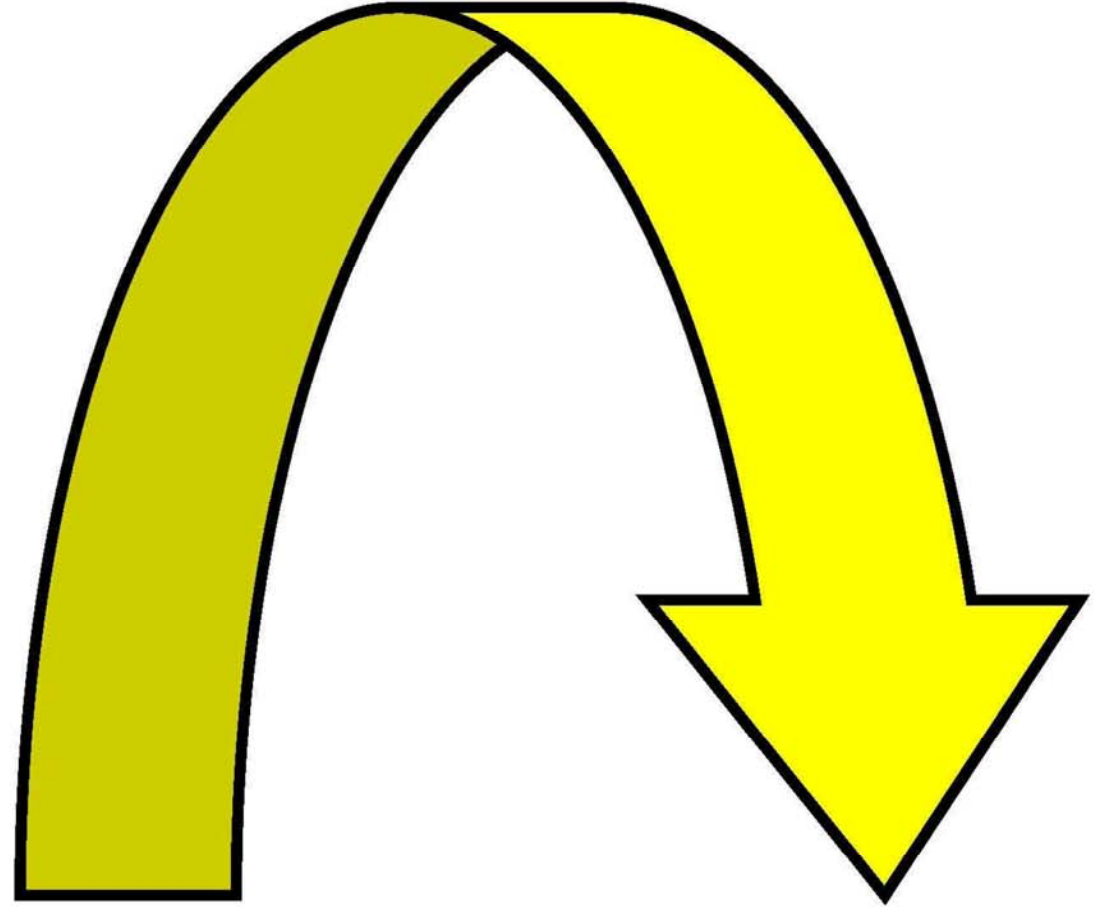
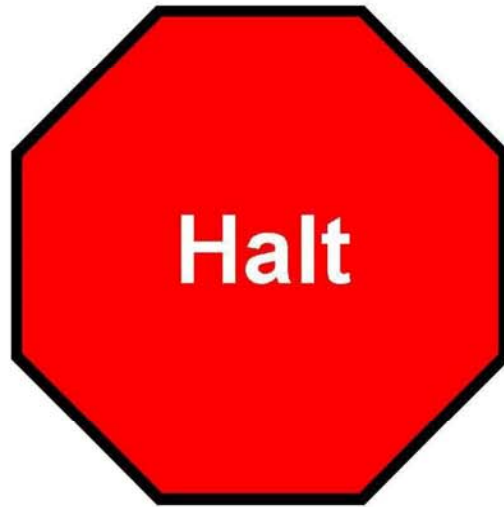


# Off Set Serpentine Right

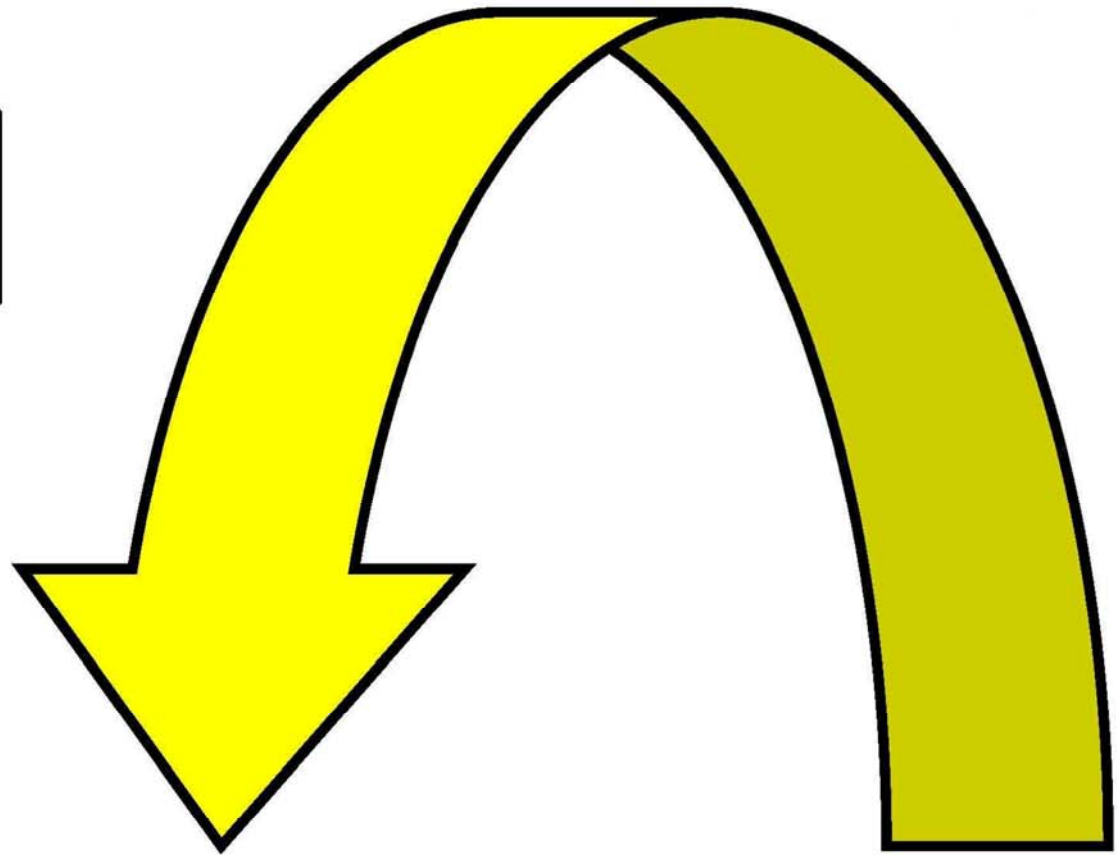
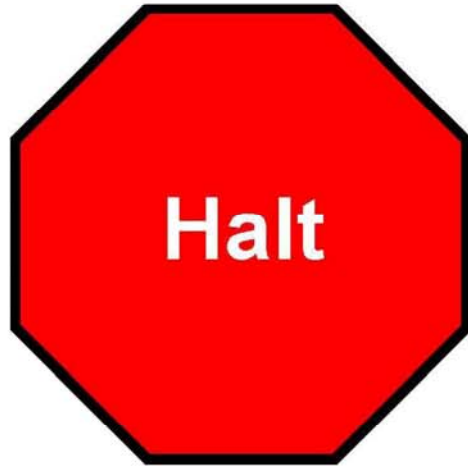


# Off Set Serpentine Left



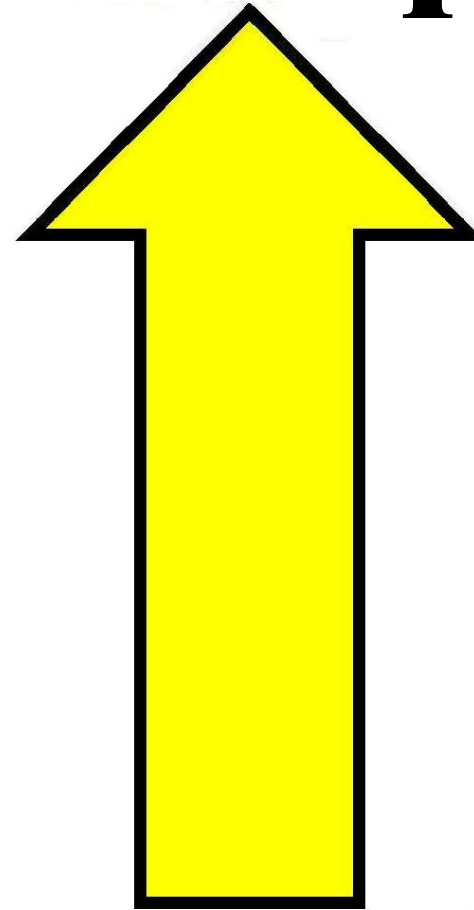
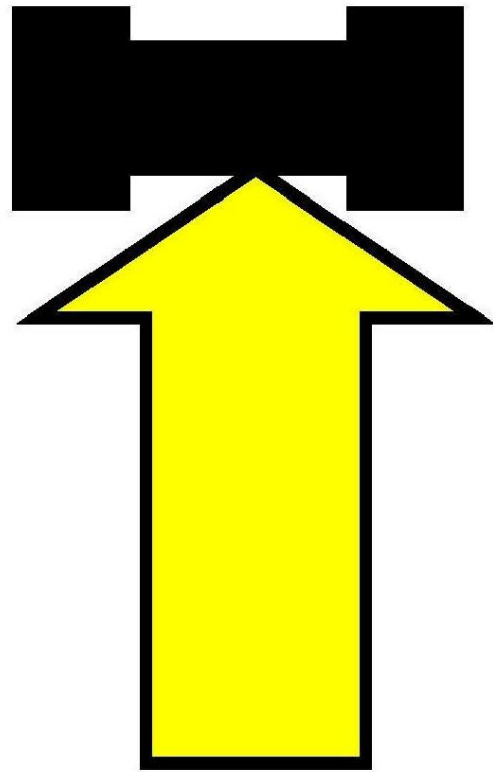


**About Turn Right  
Forward**

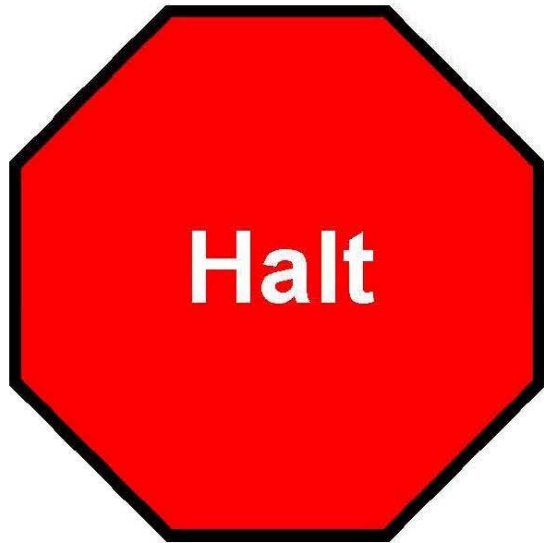


**About “U” Turn  
Forward**

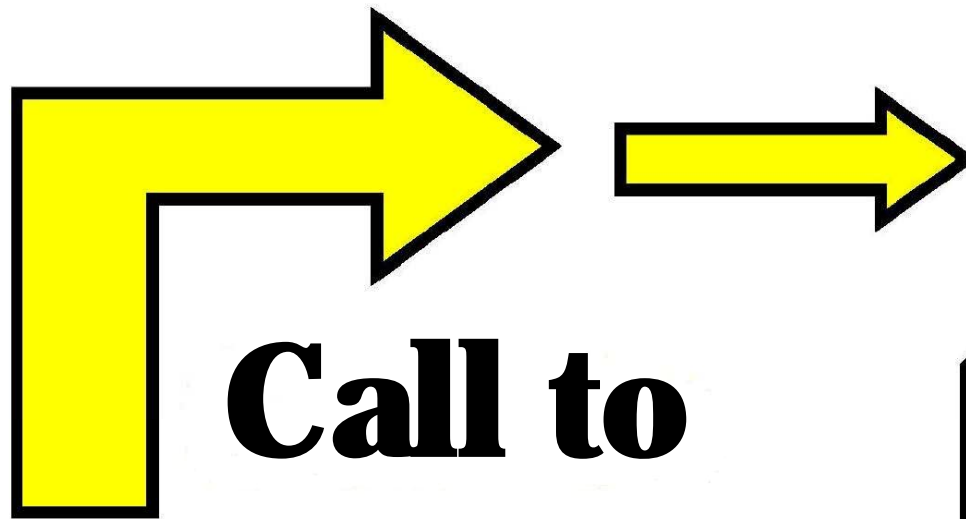
# **Send Over Jump**



**Handler Passes By**



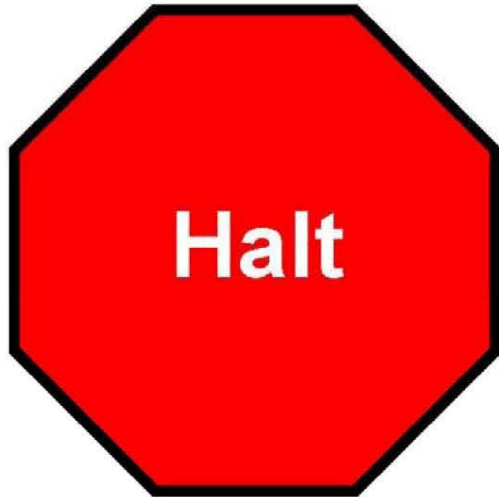
**Turn Right  
1 Step**

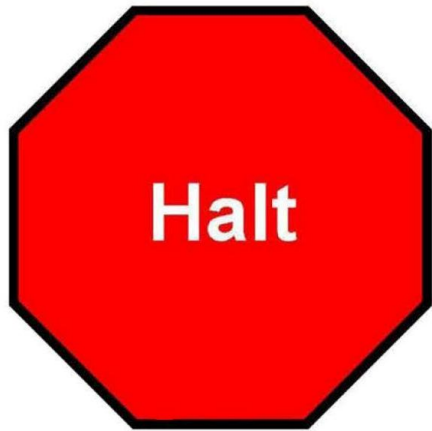


**Call to  
Heel**



**I,A,X,M – # 105**

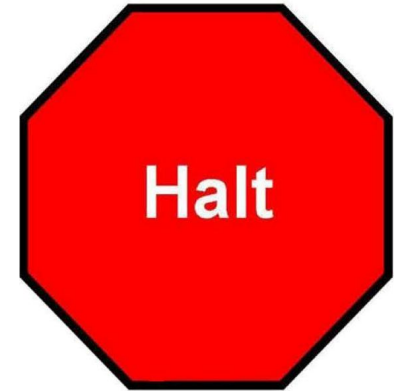
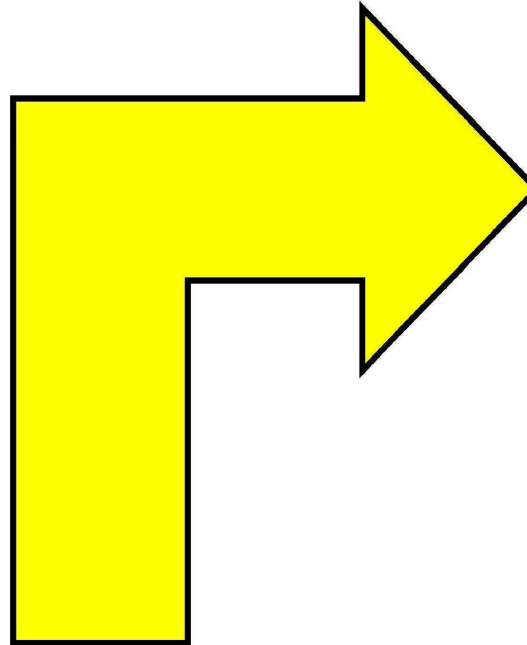




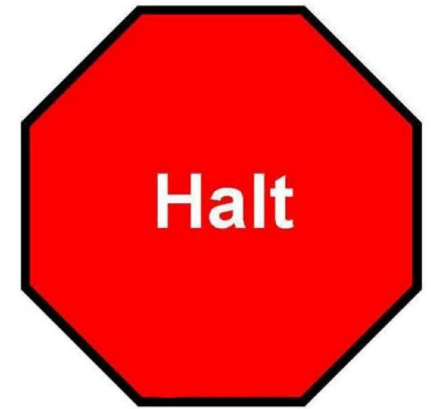
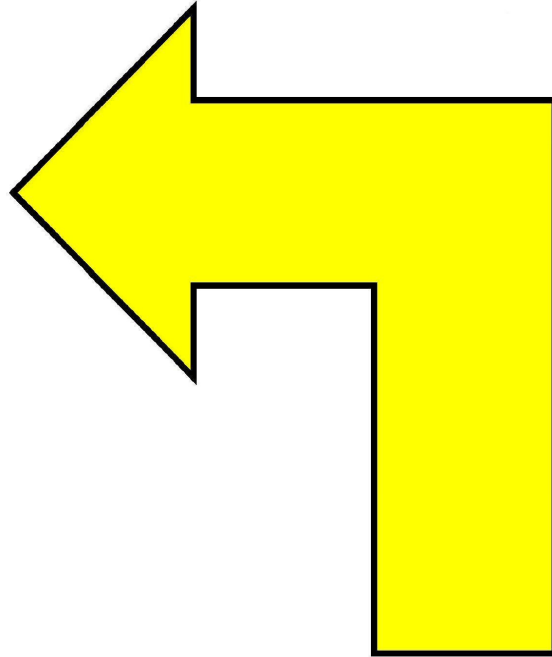
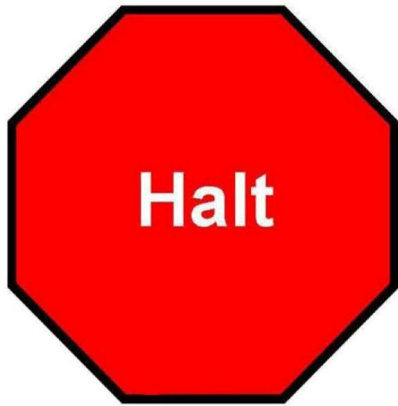
**90°**

**Pivot**

**Right**



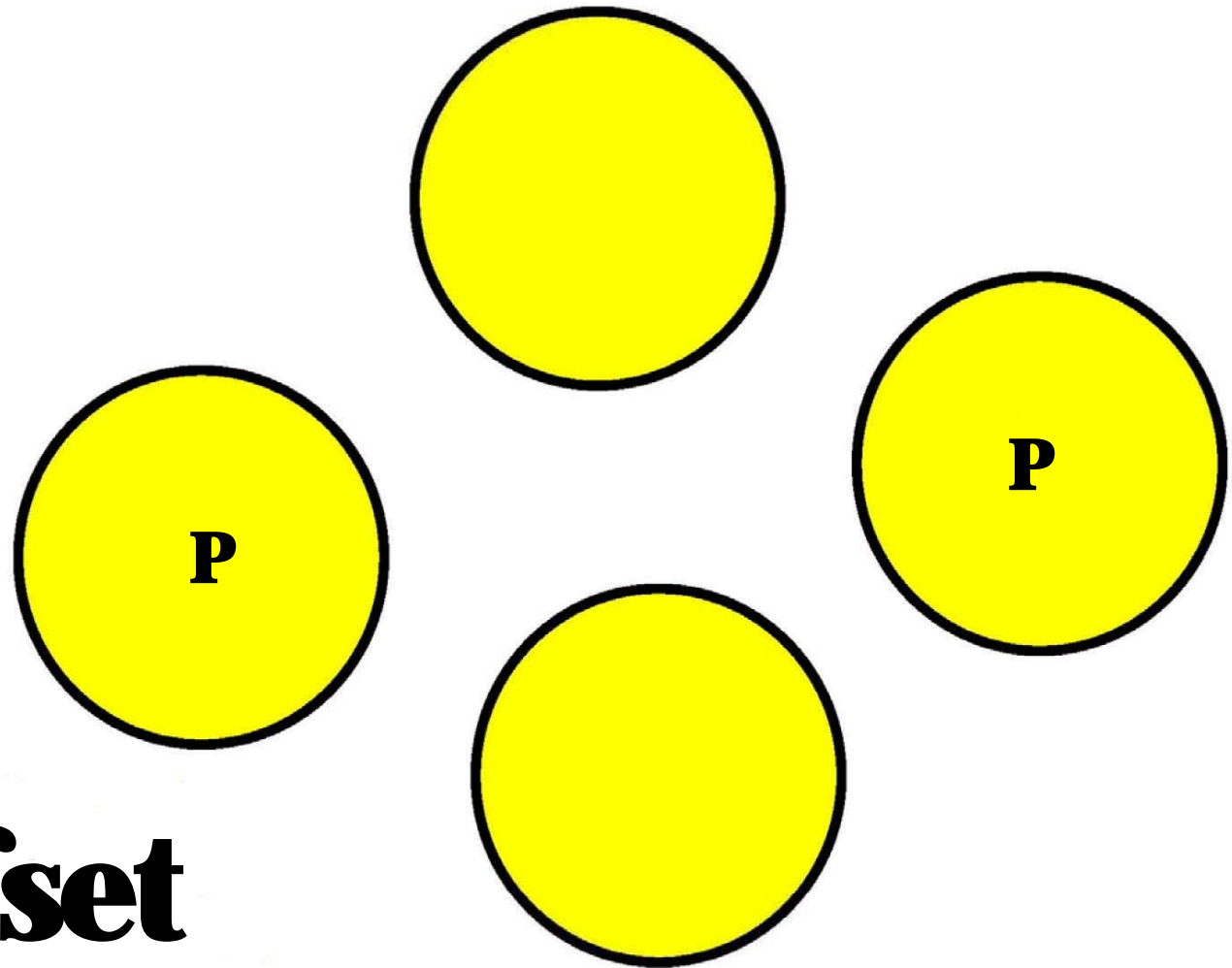




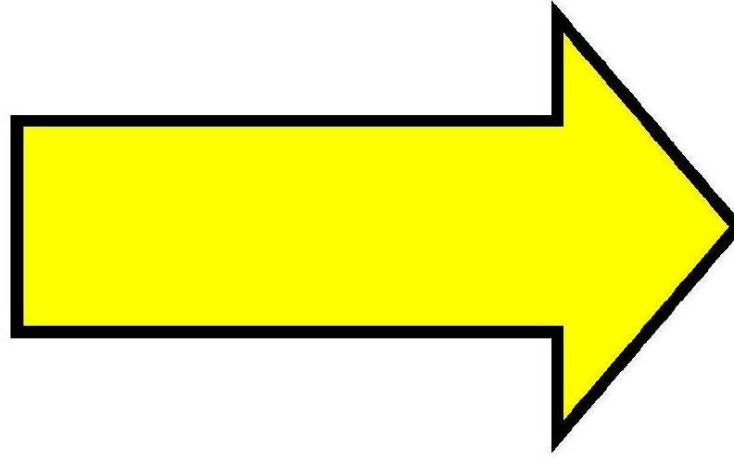
**90°**

**Pivot**

**Left**

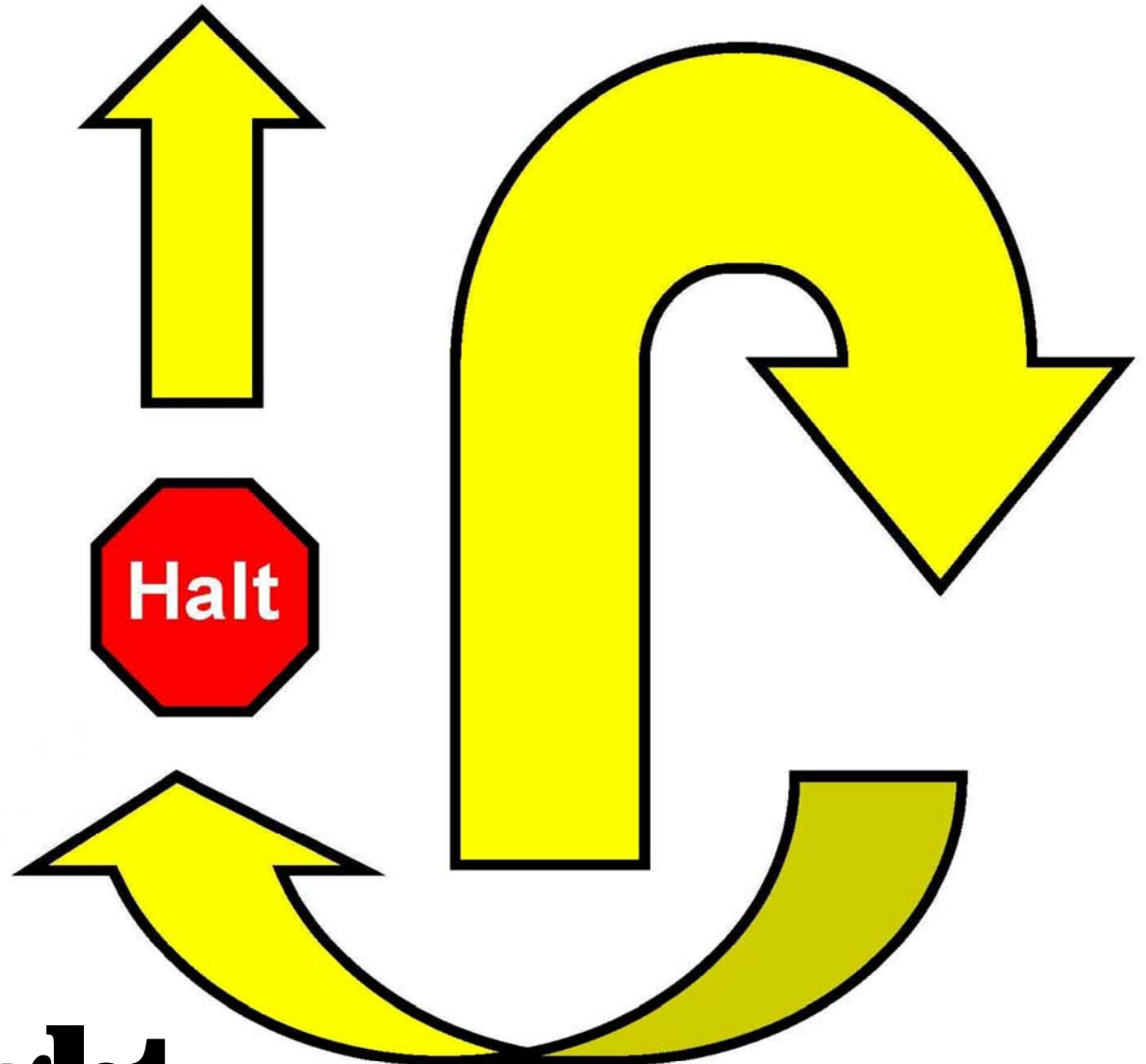
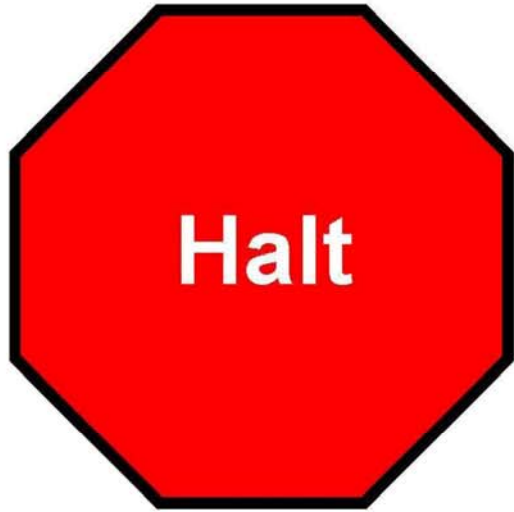


**Offset**  
**Figure 8**



**Side Step**

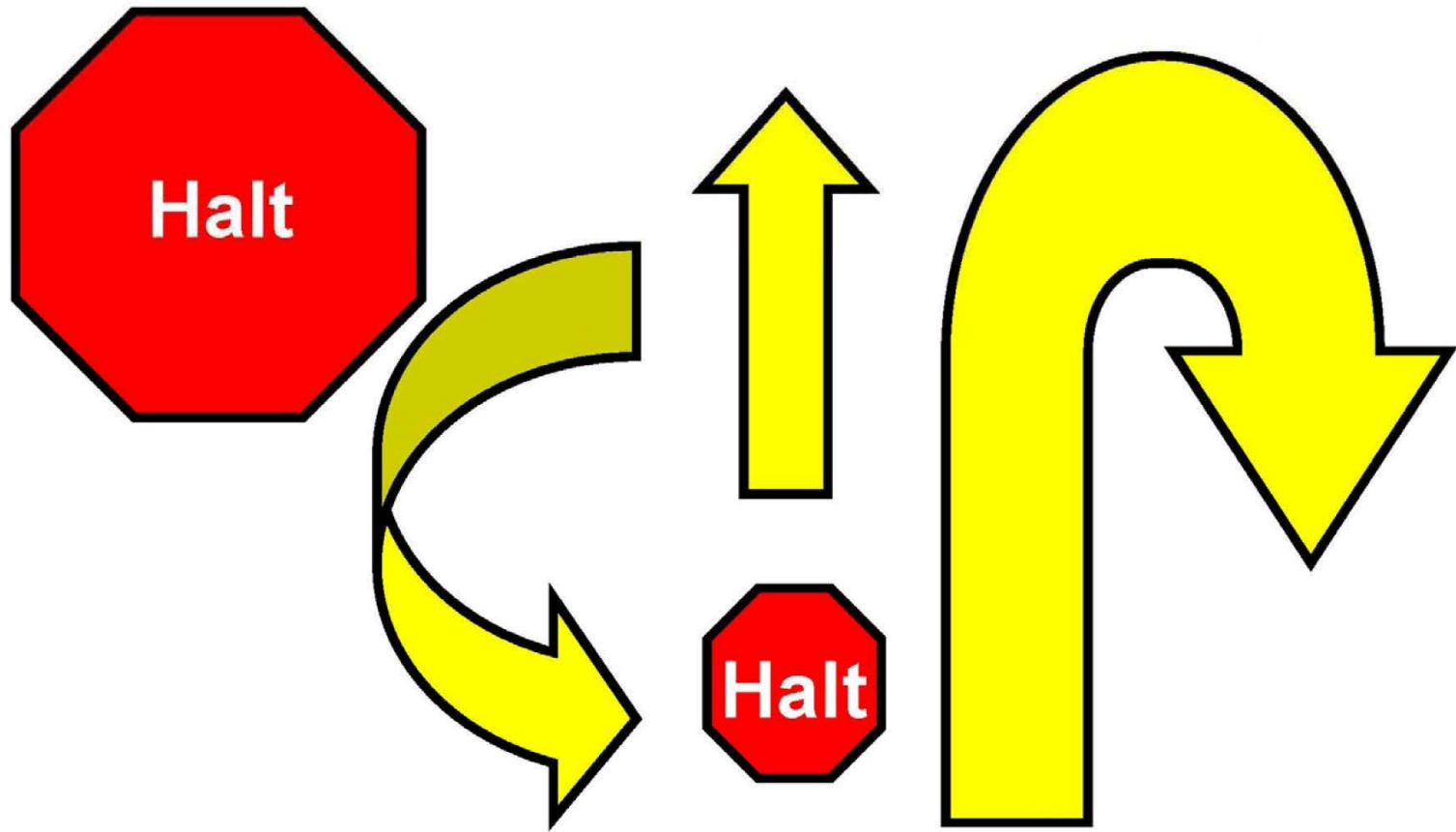
**Right**



**Call Dog**

**Front**

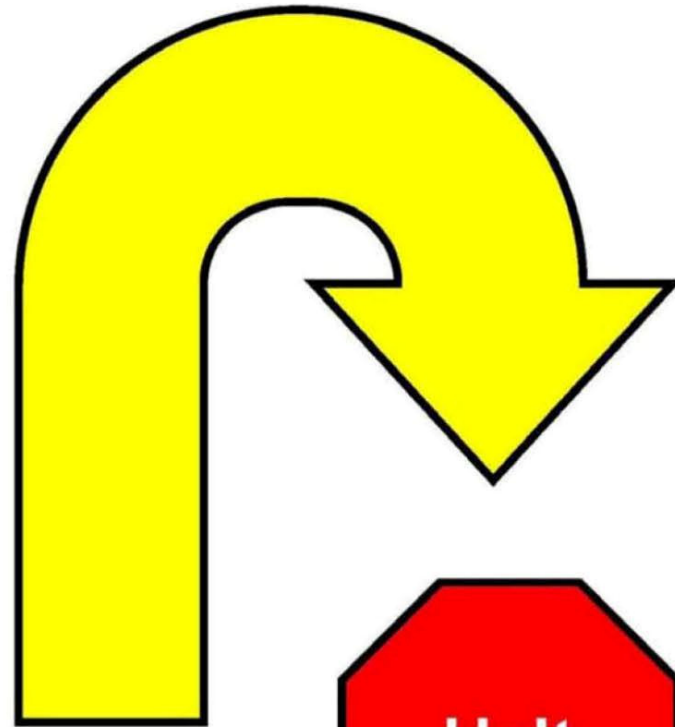
**Finish Right**

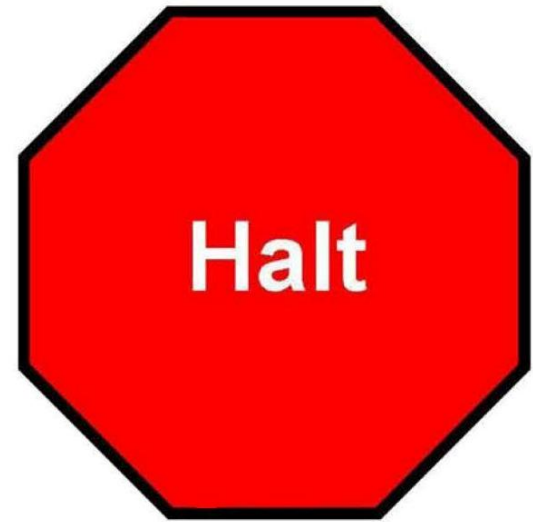
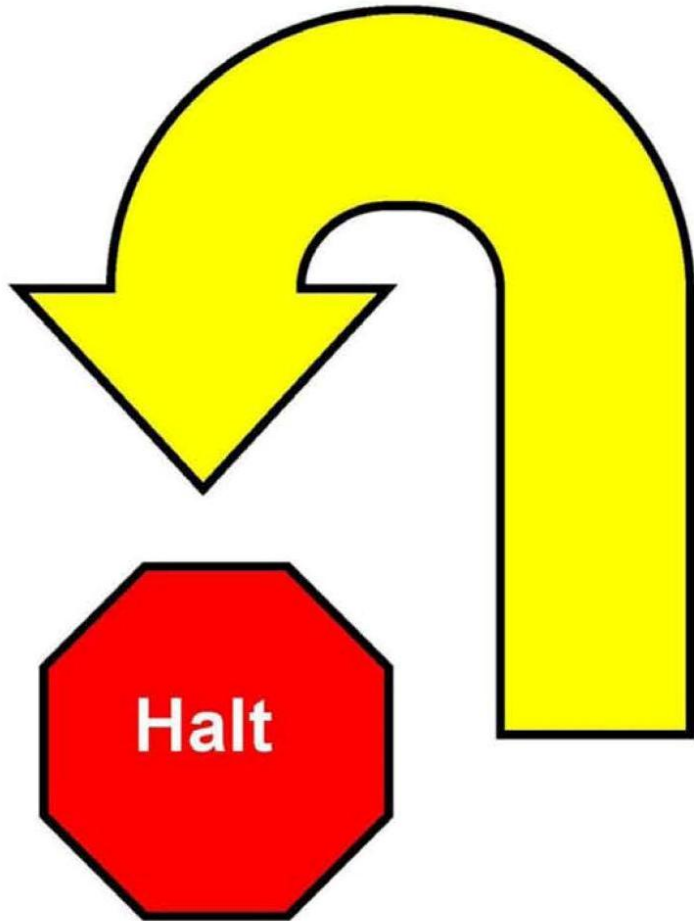


**Call Dog Front**  
**Finish Left**

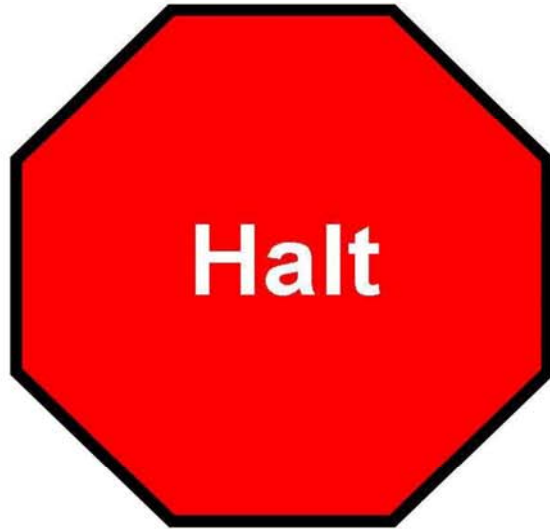


**180°  
Pivot  
Right**

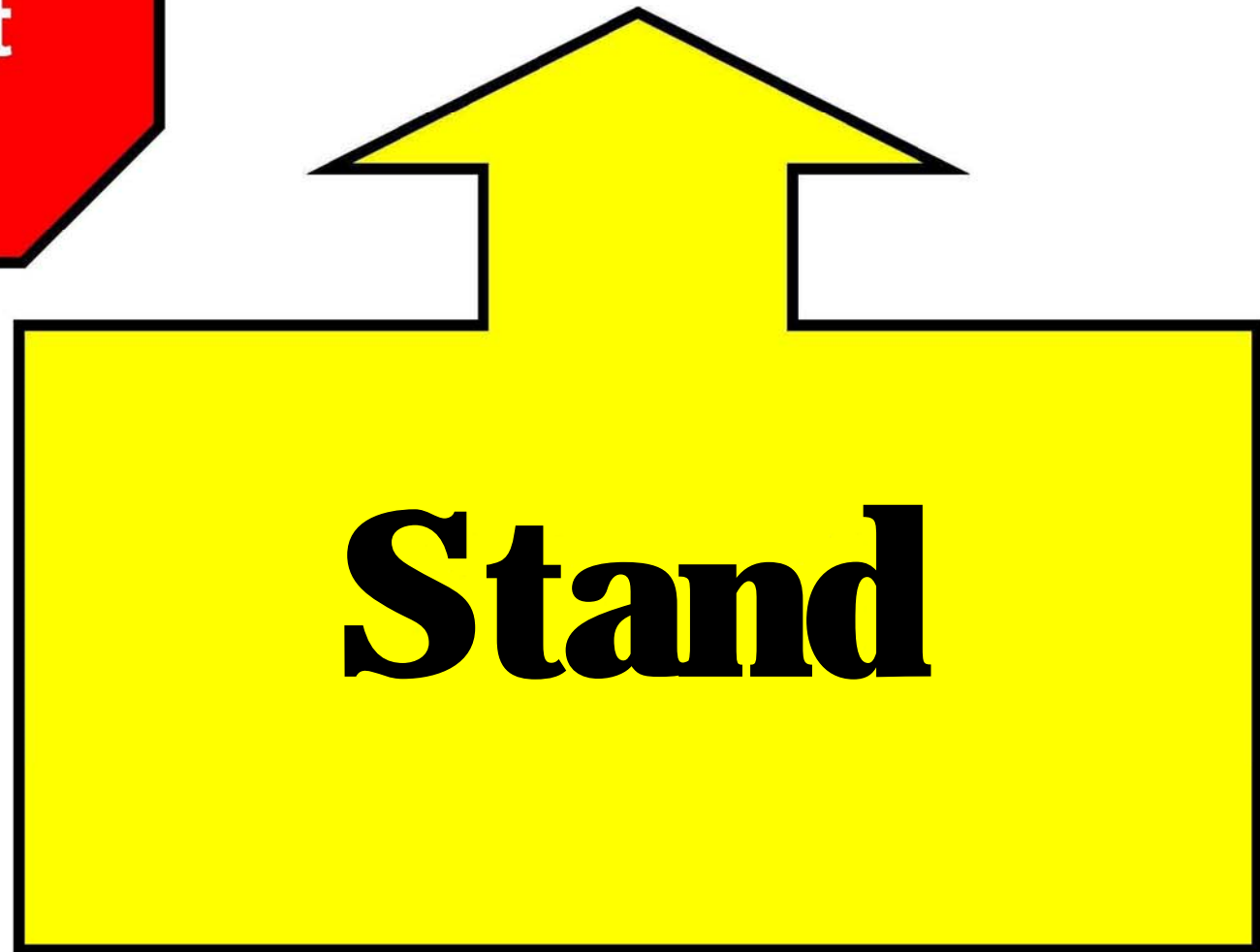
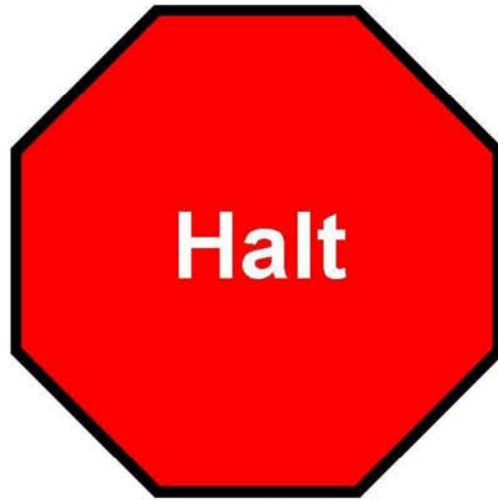


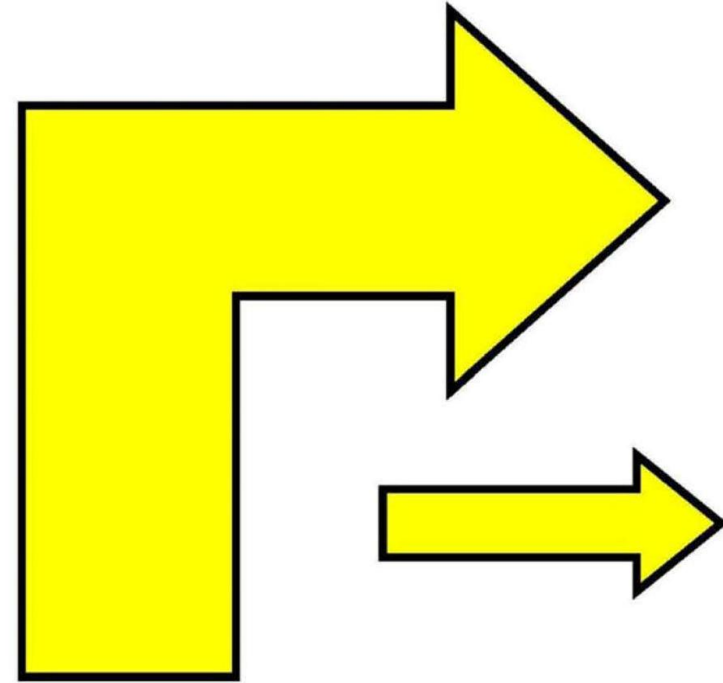
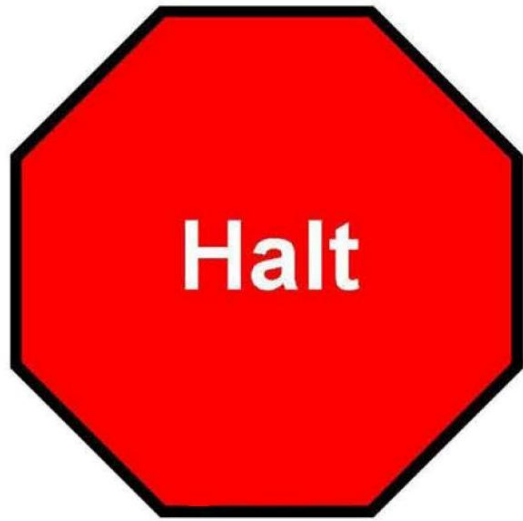


**180°  
Pivot  
Left**







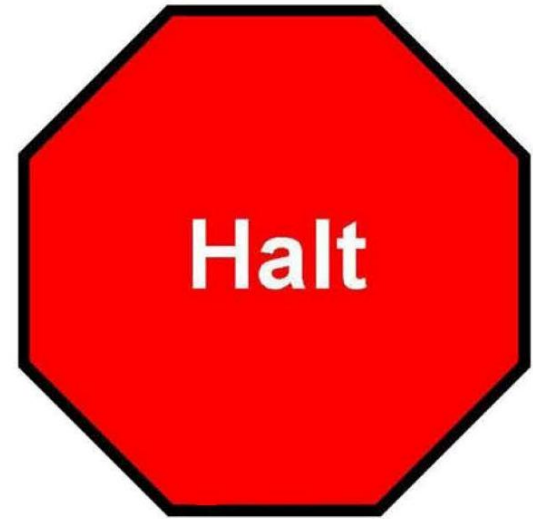
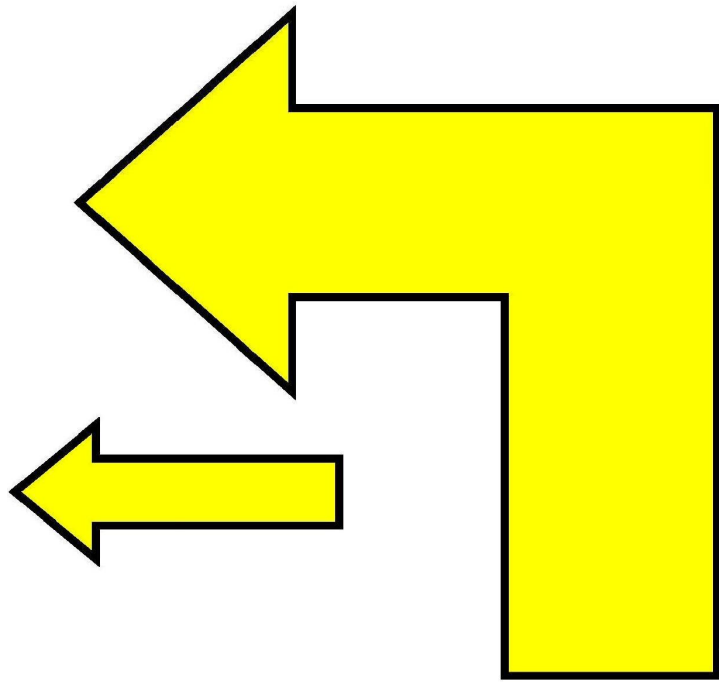


**Pivot**

**Right**



**Forward**



**Pivot**

**Forward**



**Left**

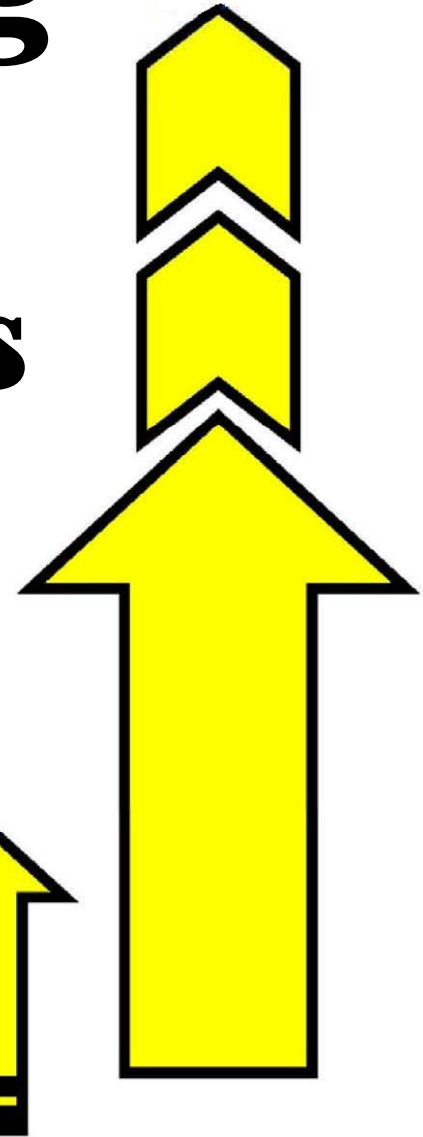


**Leave Dog**

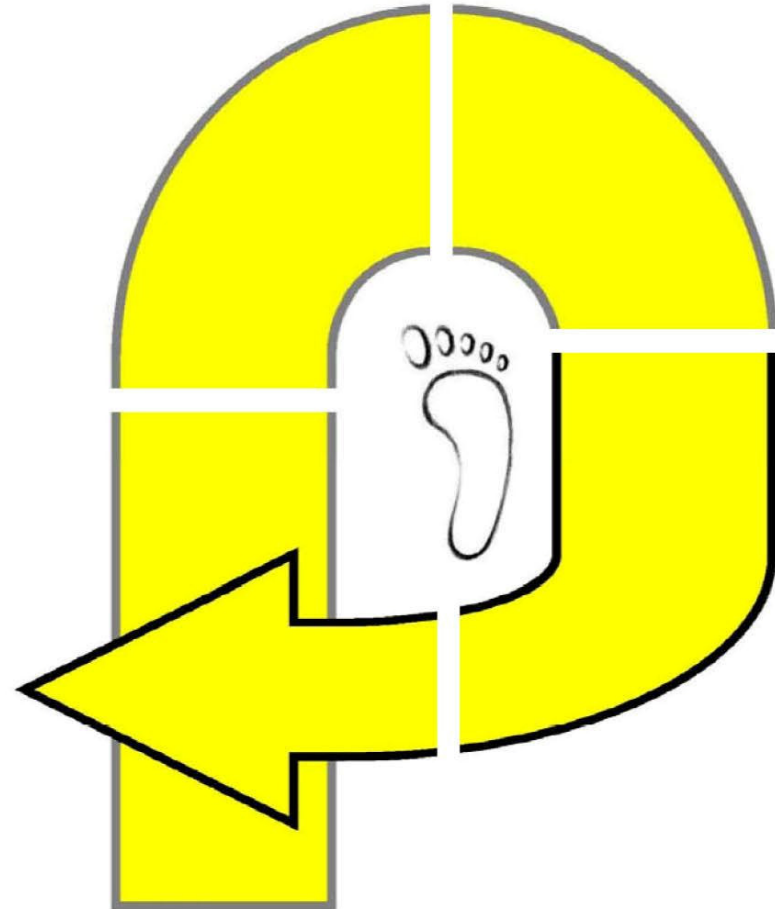
**2 Steps**

**Call to Heel**

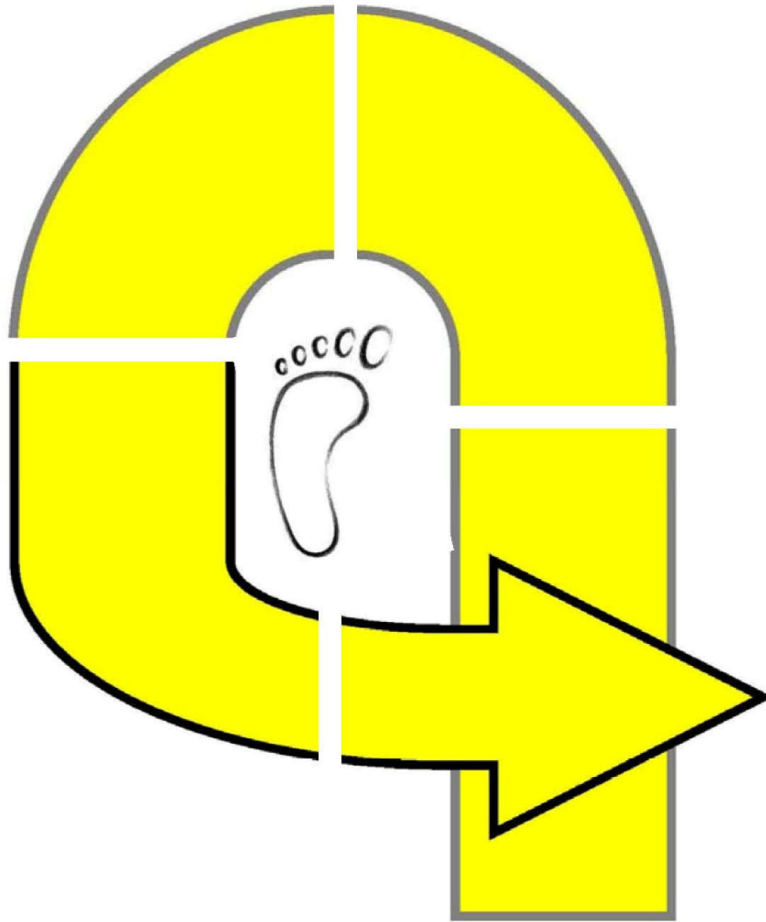
**Forward**



**270°  
Pivot  
Right**

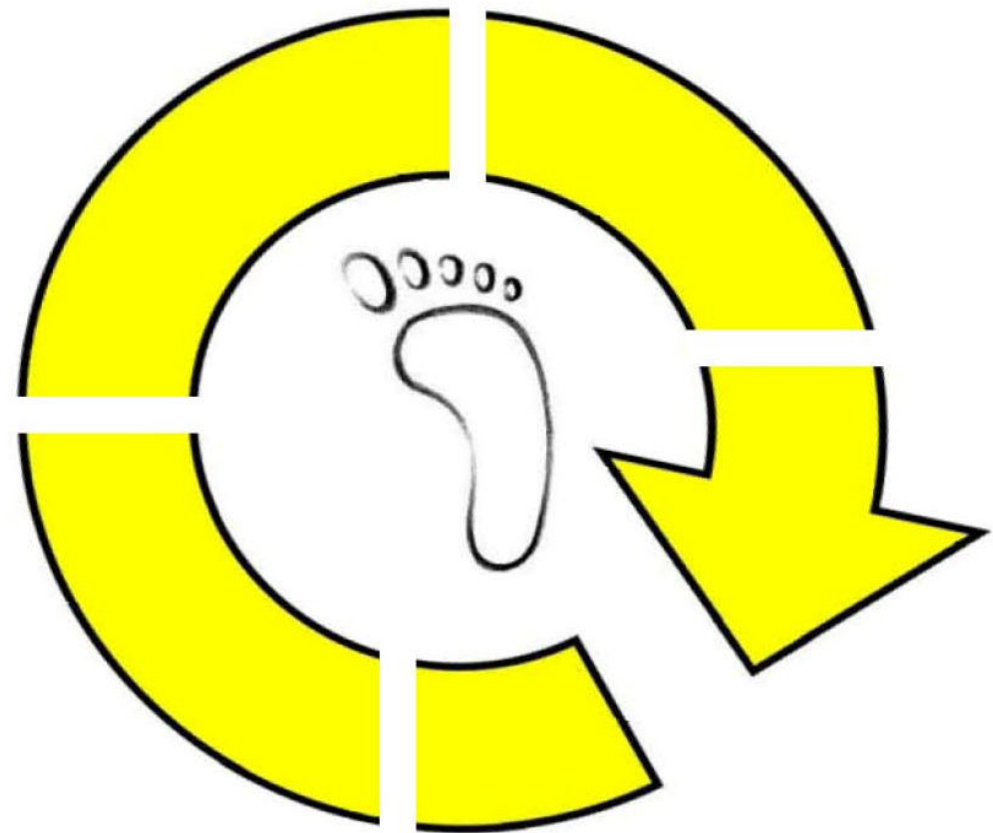


**I,A,X,M - # 120**

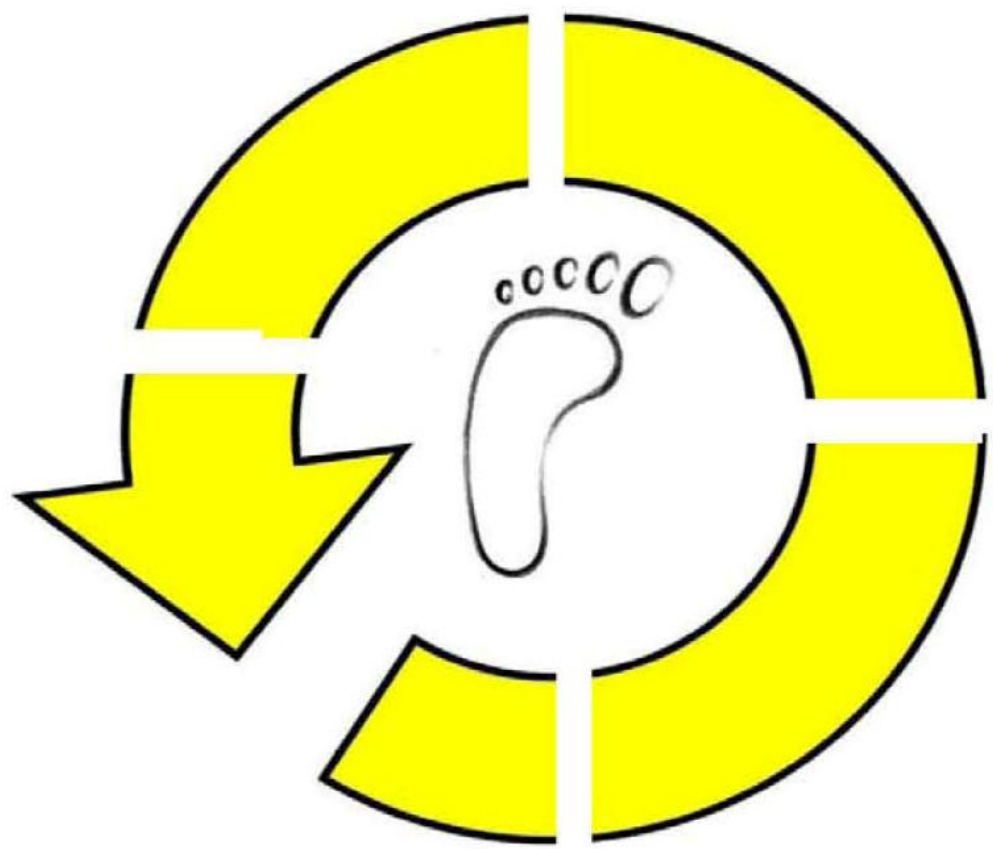


**270°  
Pivot  
Left**

**360°  
Pivot  
Right**



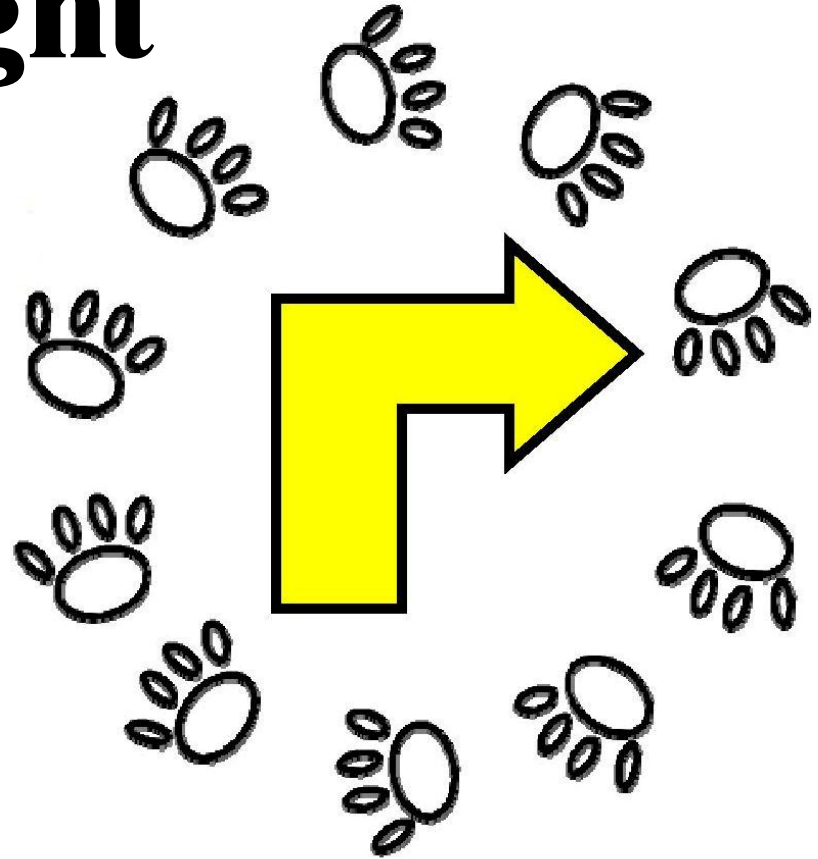
**I,A,X,M - # 122**



**360°**  
**Pivot**  
**Left**



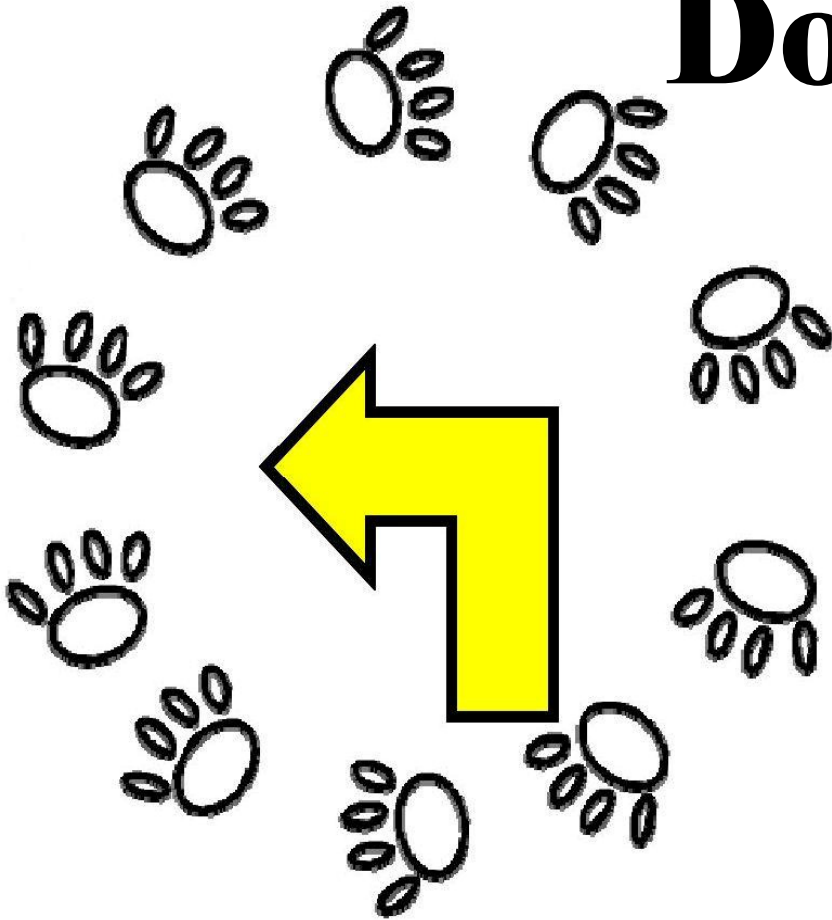
# Right Turn Dog Circles Right Forward

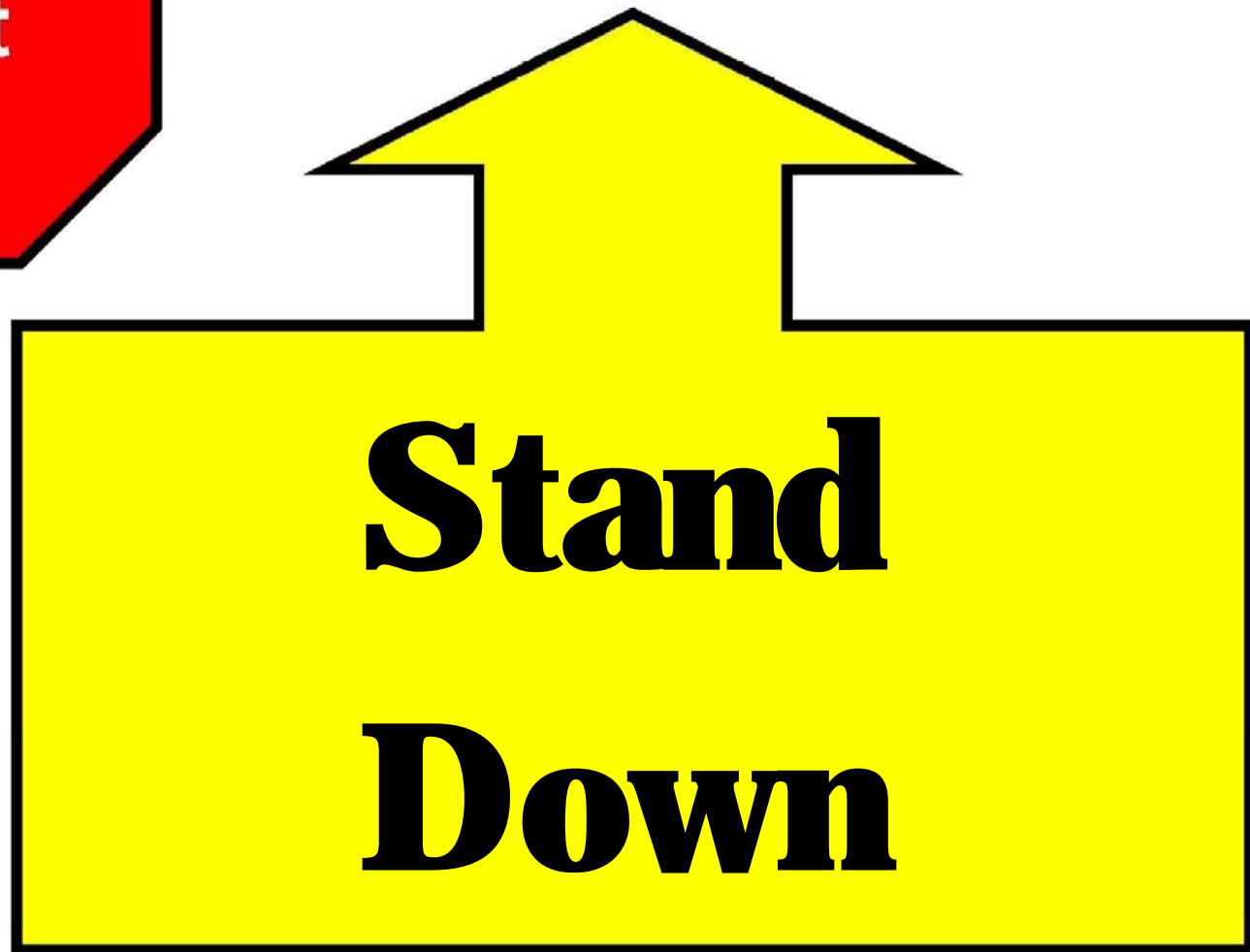
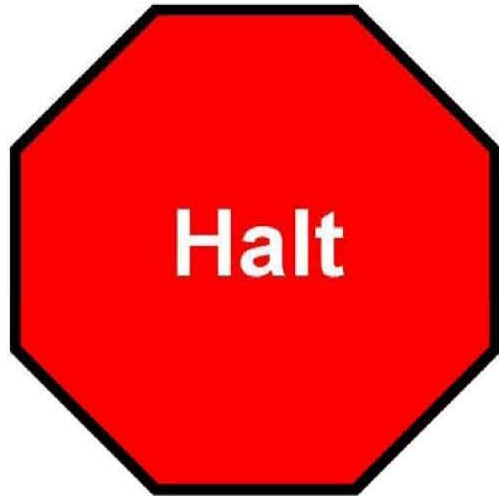


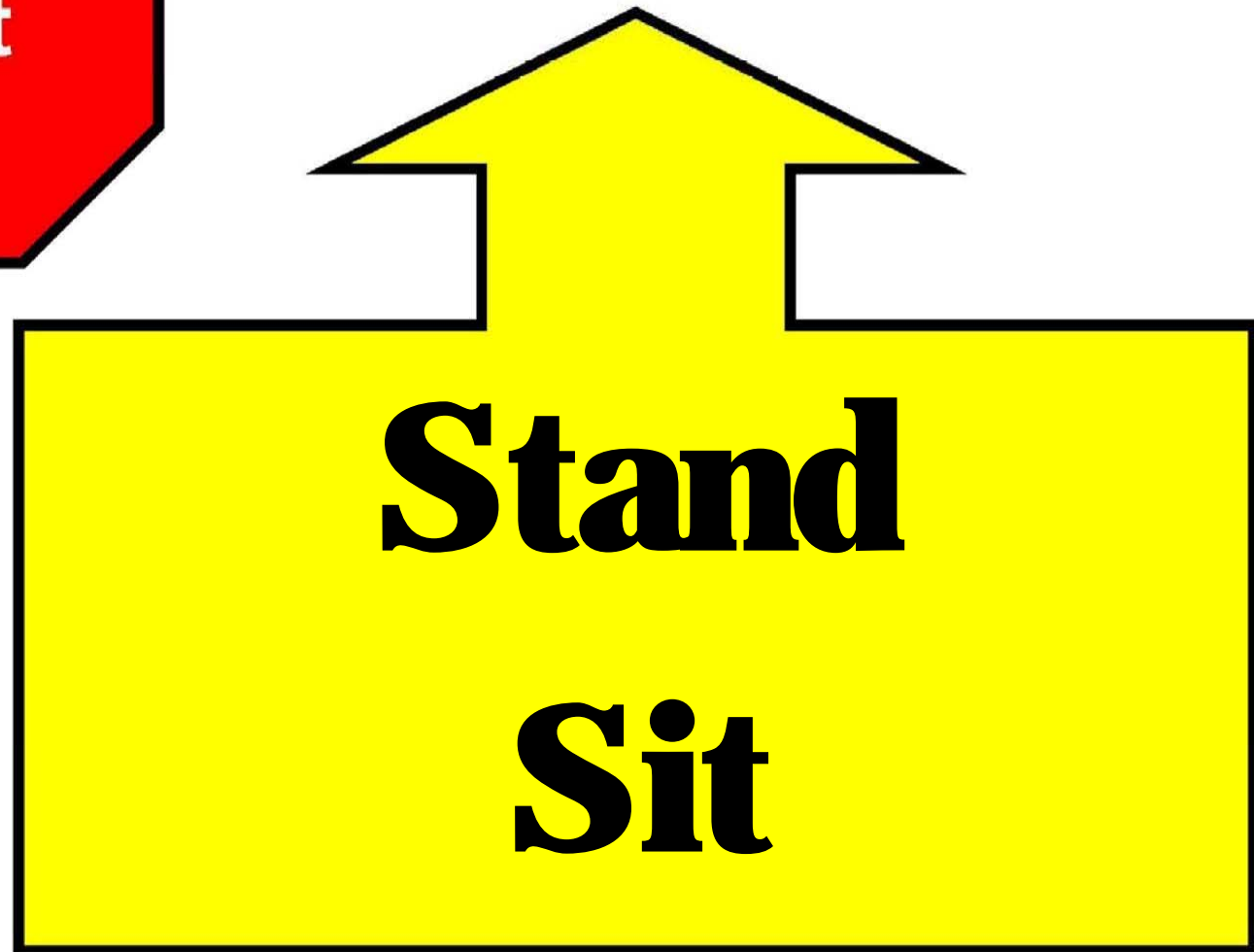
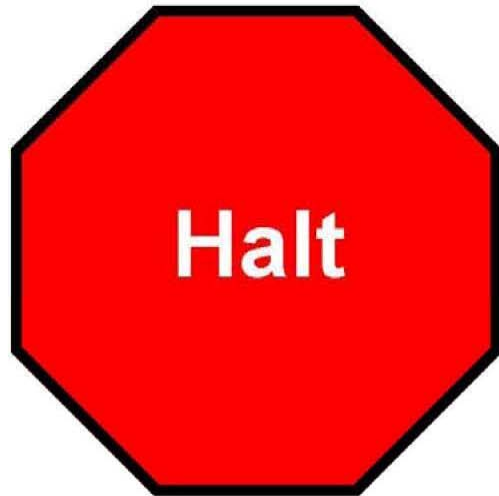
**I,A,X,M – # 124**

# **Left Turn**

**Dog Circles Right  
Forward**









**Moving Stand**  
**Walk Around**  
**Dog**

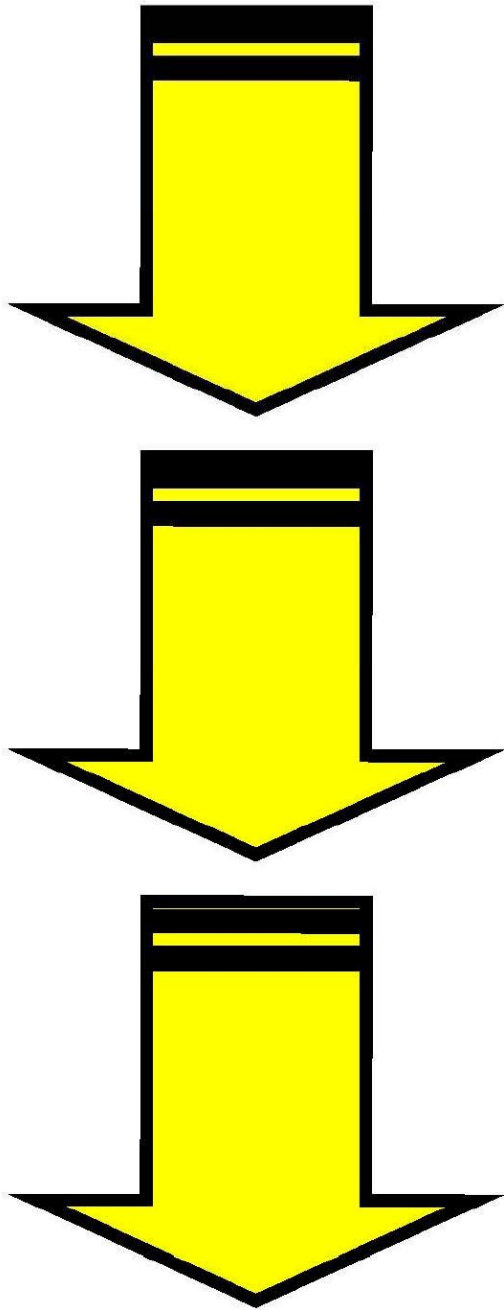


**Moving Down**

**Walk Around**

**Dog**

**X,M – # 205**

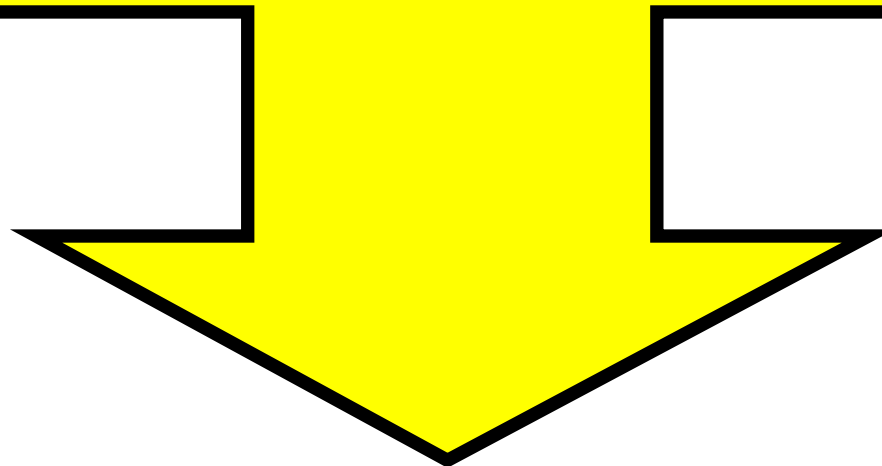


**Back Up  
3 Steps  
Dog  
Stays in  
Position**

**Moving Down**

**Call to Heel**

**Halt**

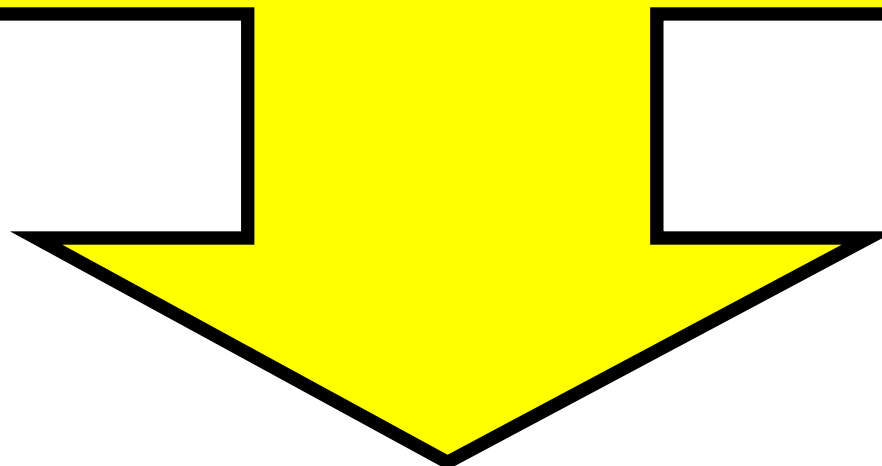




**Moving Stand**

**Call to Heel**

**Halt**

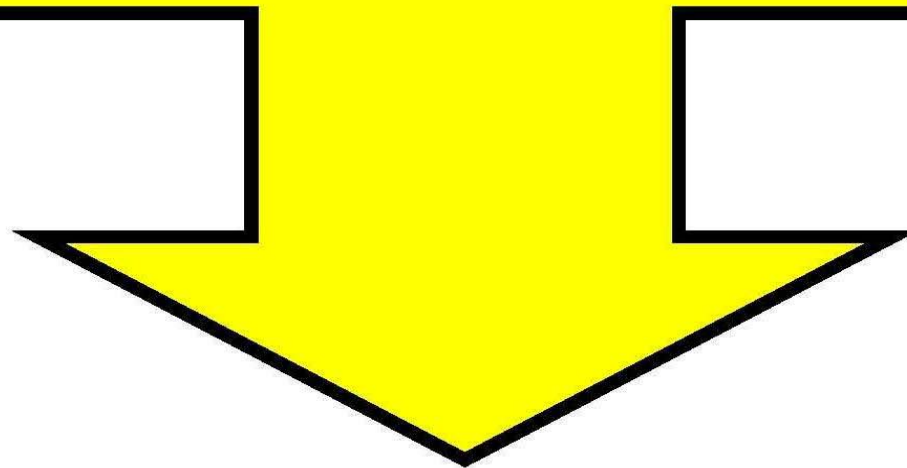


**Stand**

**Leave Dog**

**Sit Dog**

**Call Front - Finish**

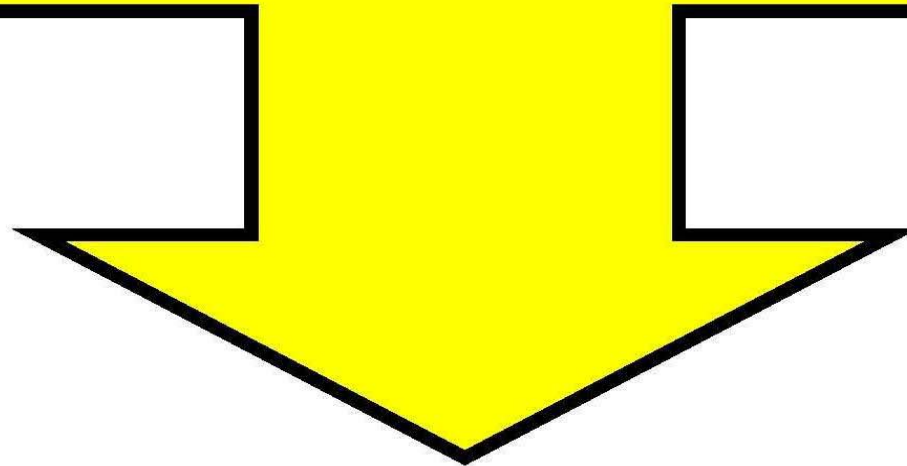


**Stand**

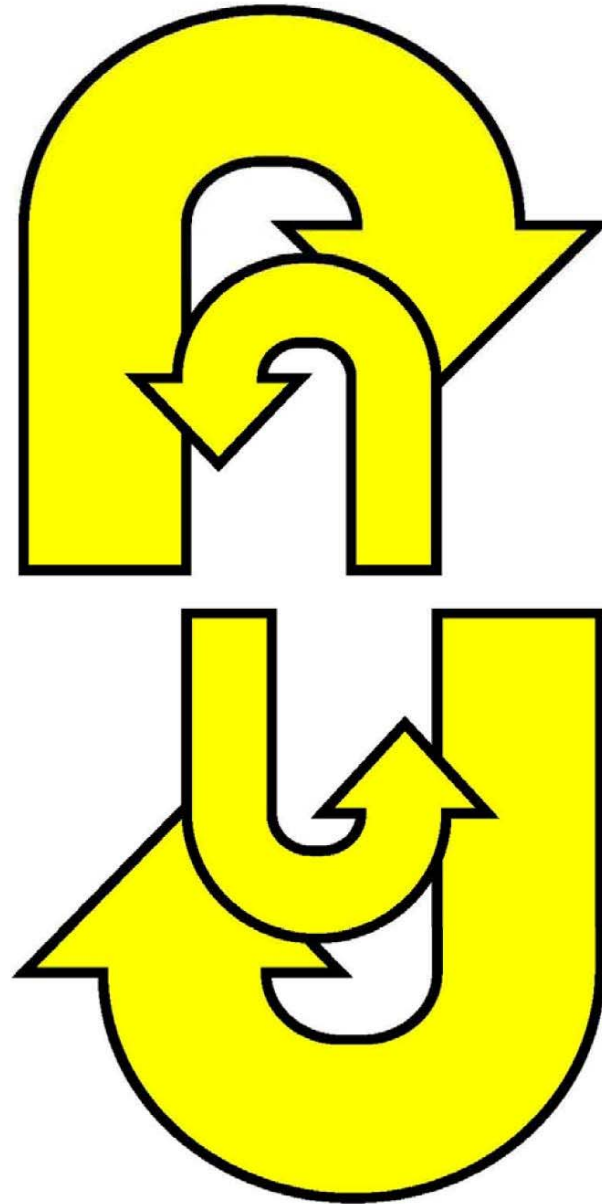
**Leave Dog**

**Down Dog**

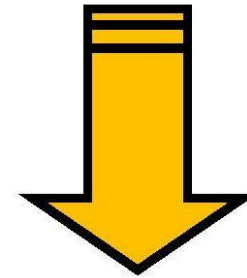
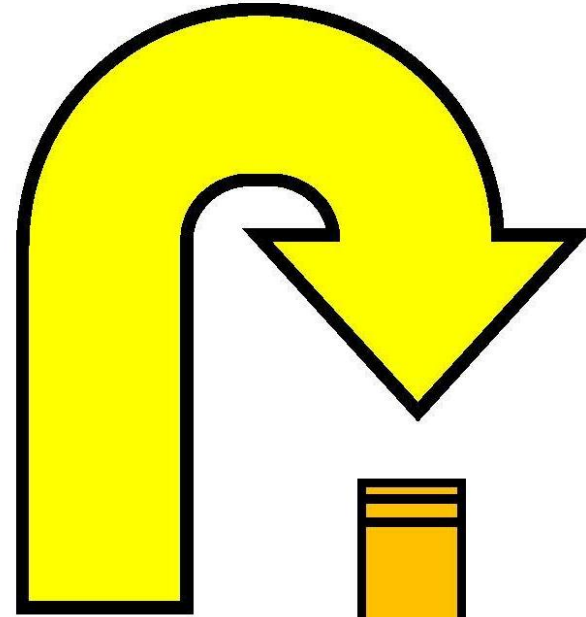
**Call Front - Finish**



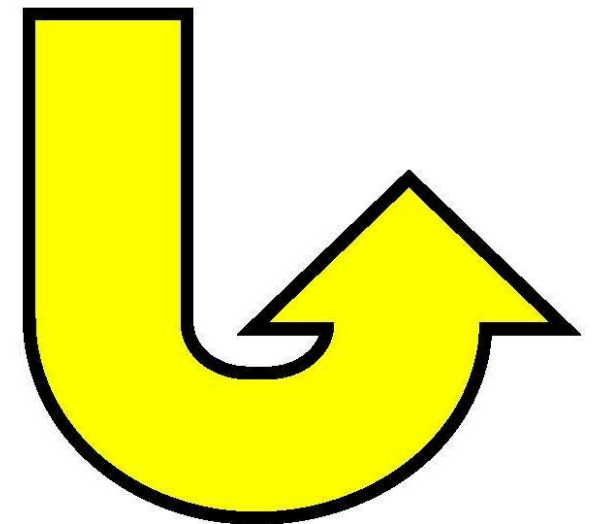
**Double  
Left  
About  
Turn**



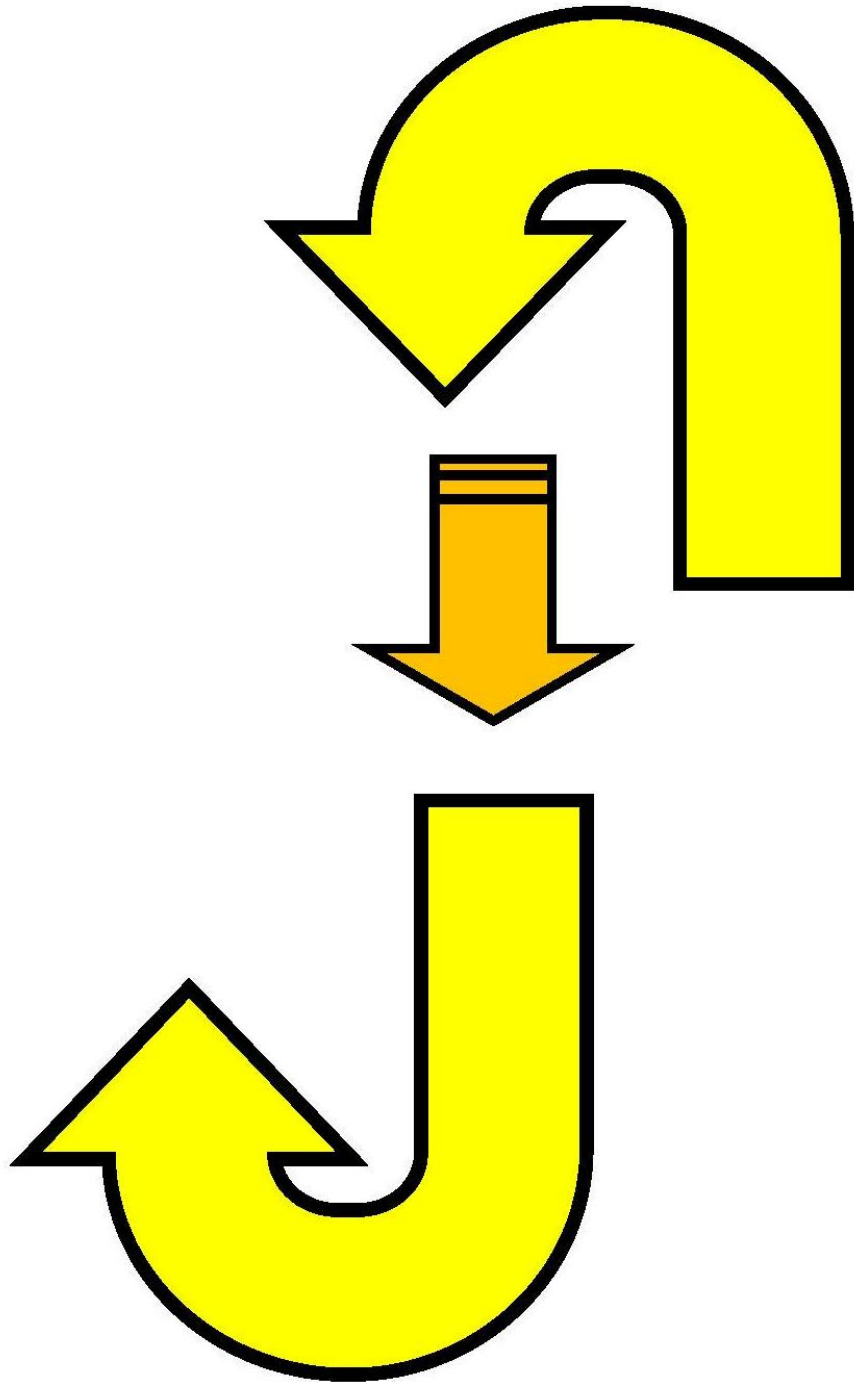
**About Turn  
Right**



**About U  
Turn**



**X,M – # 213**

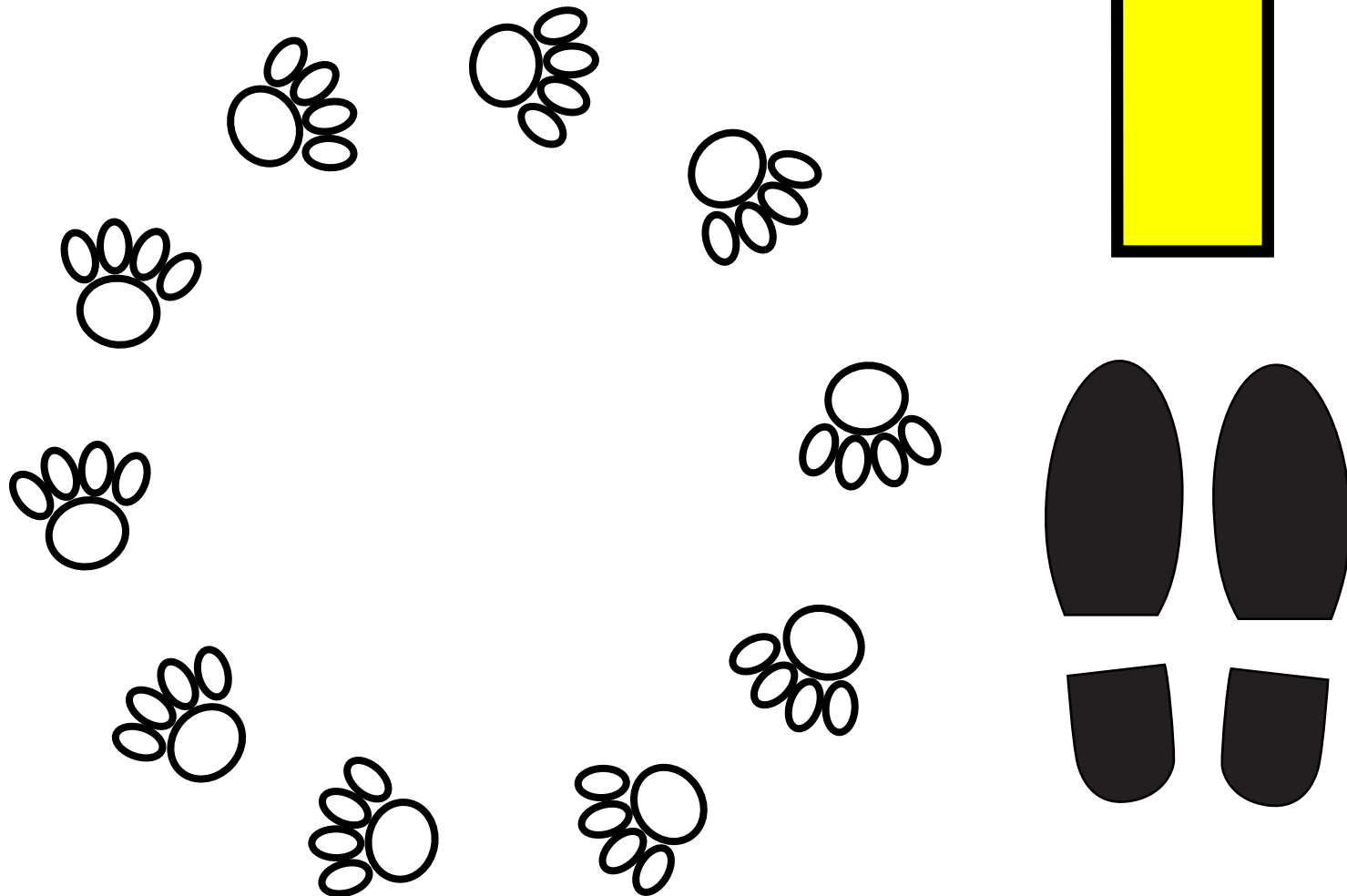
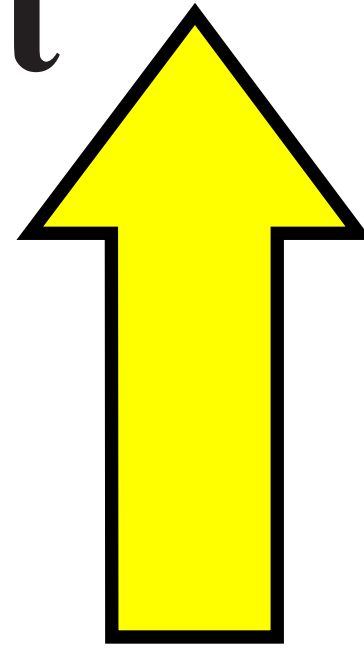


**About U  
Turn**

**About Turn  
Right**

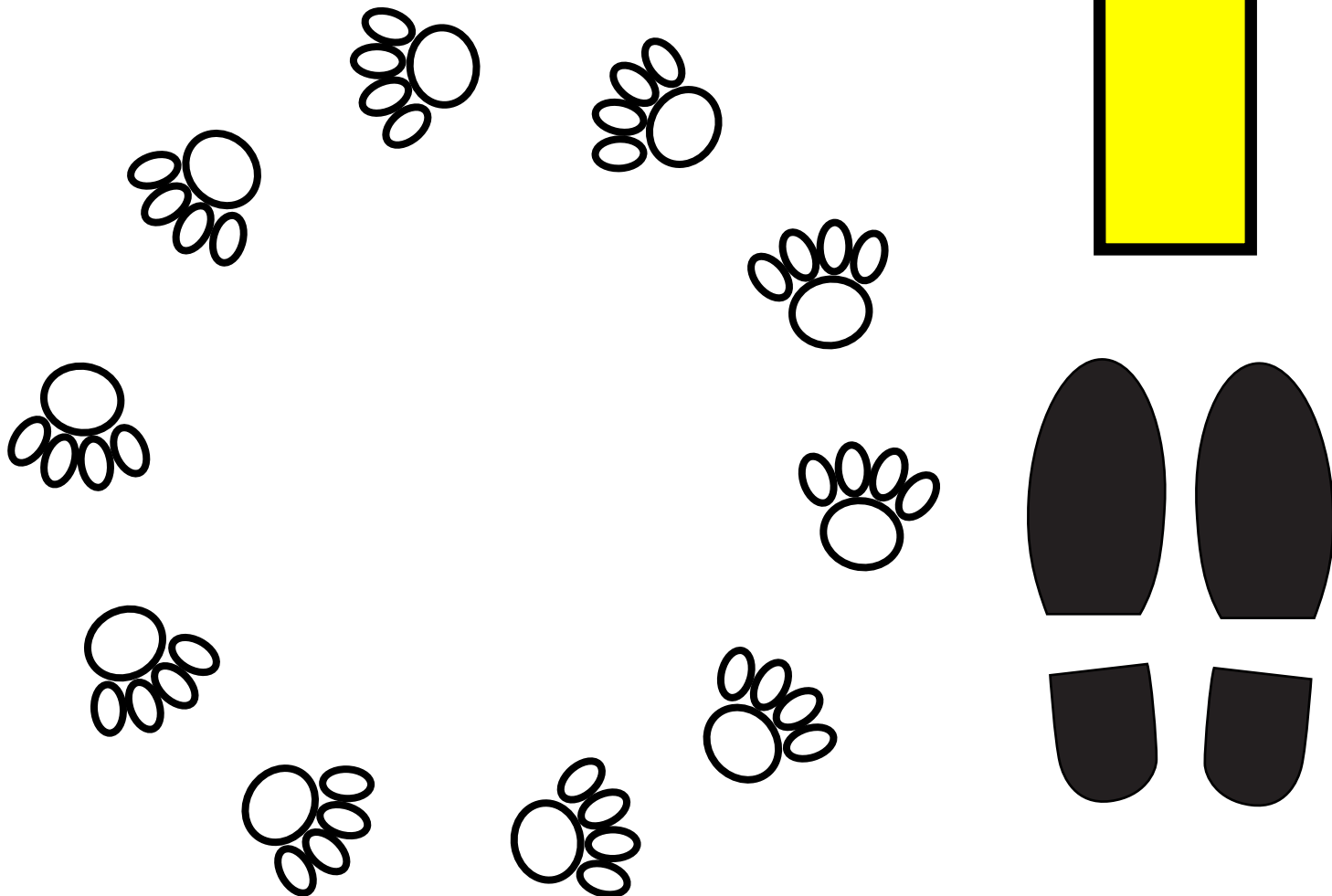
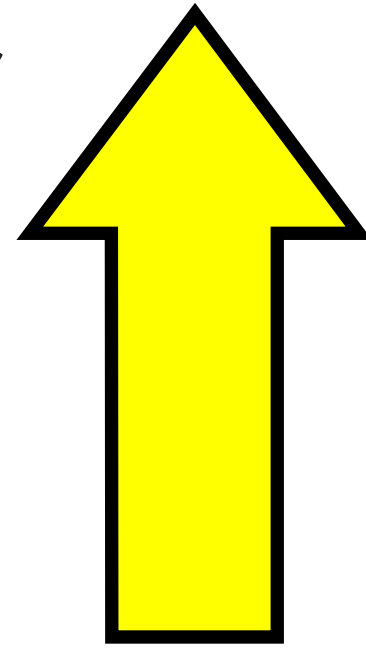
# Dog Spins Right Forward

X,M - #214



X,M - #215

# Dog Spins Left Forward



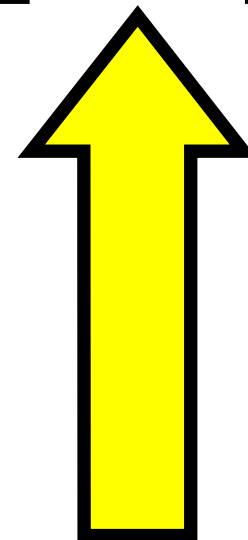
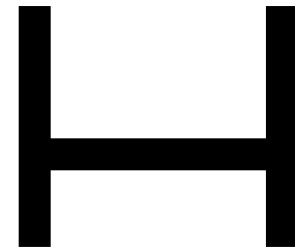
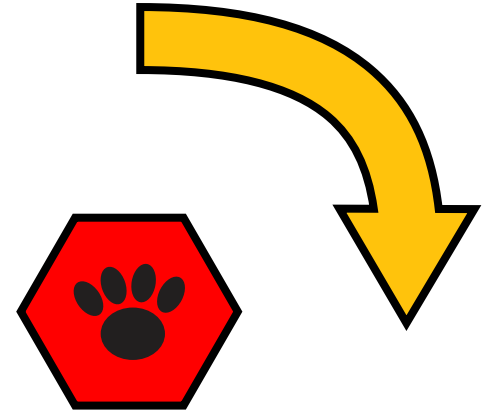


X,M - #216

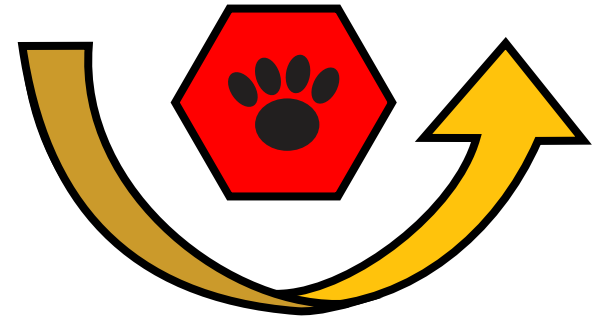


**Recall Over  
Jump**

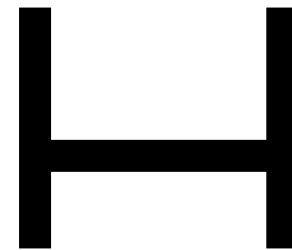
**Handler Steps into  
Heel Position**



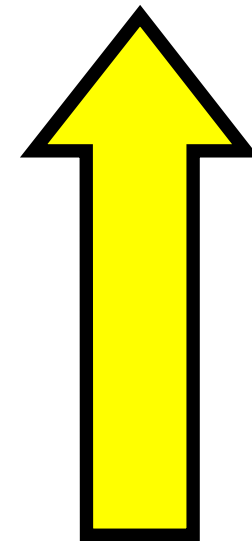
X,M - #217



**Recall Over  
Jump**



**Handler Walks  
Around Dog into  
Heel Position**

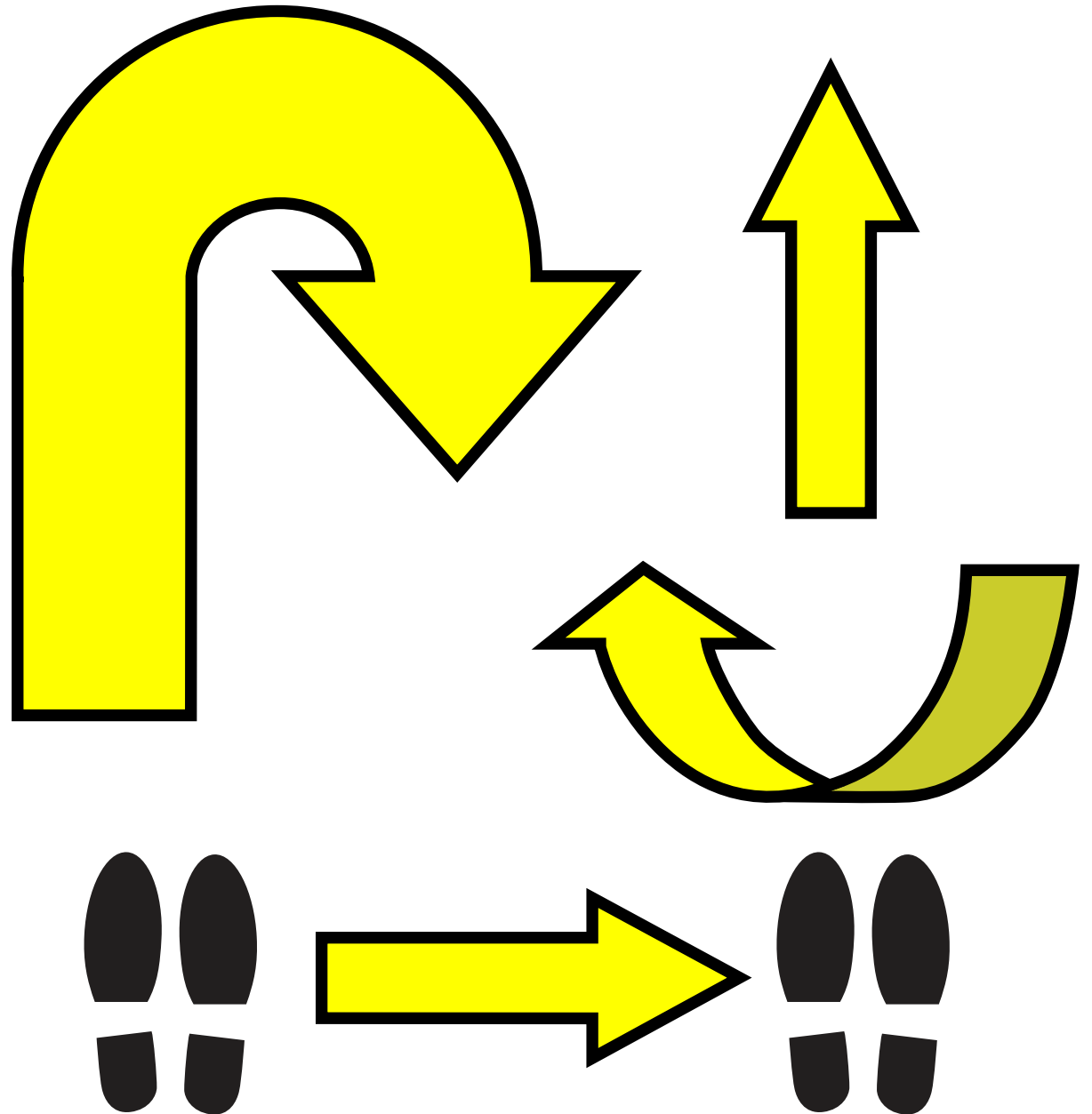


**Call Front**

**Side Step  
Right**

**Finish  
Right**

**Forward**

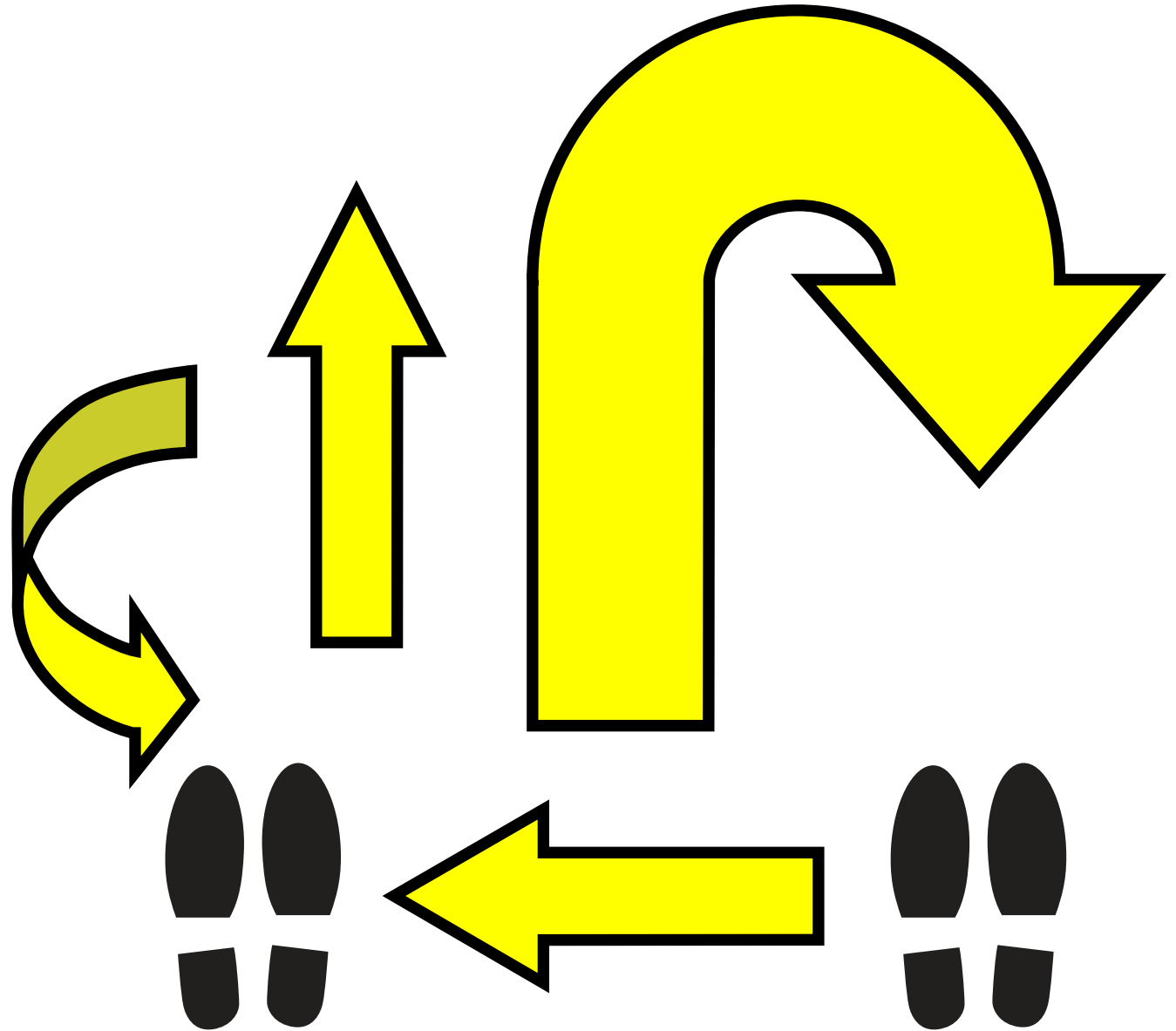


**Call Front**

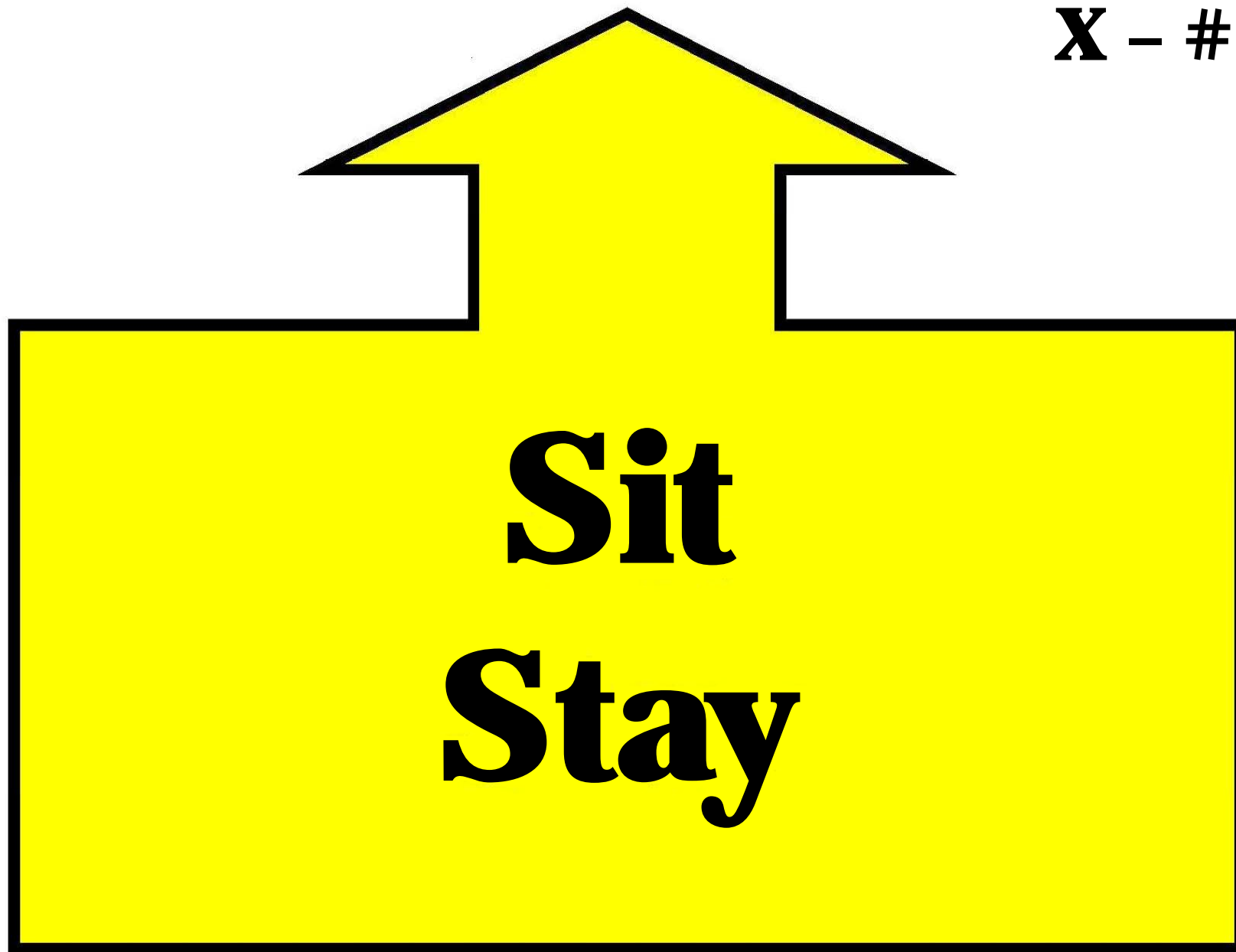
**Side Step  
Left**

**Finish  
Left**

**Forward**



**X - # 298**

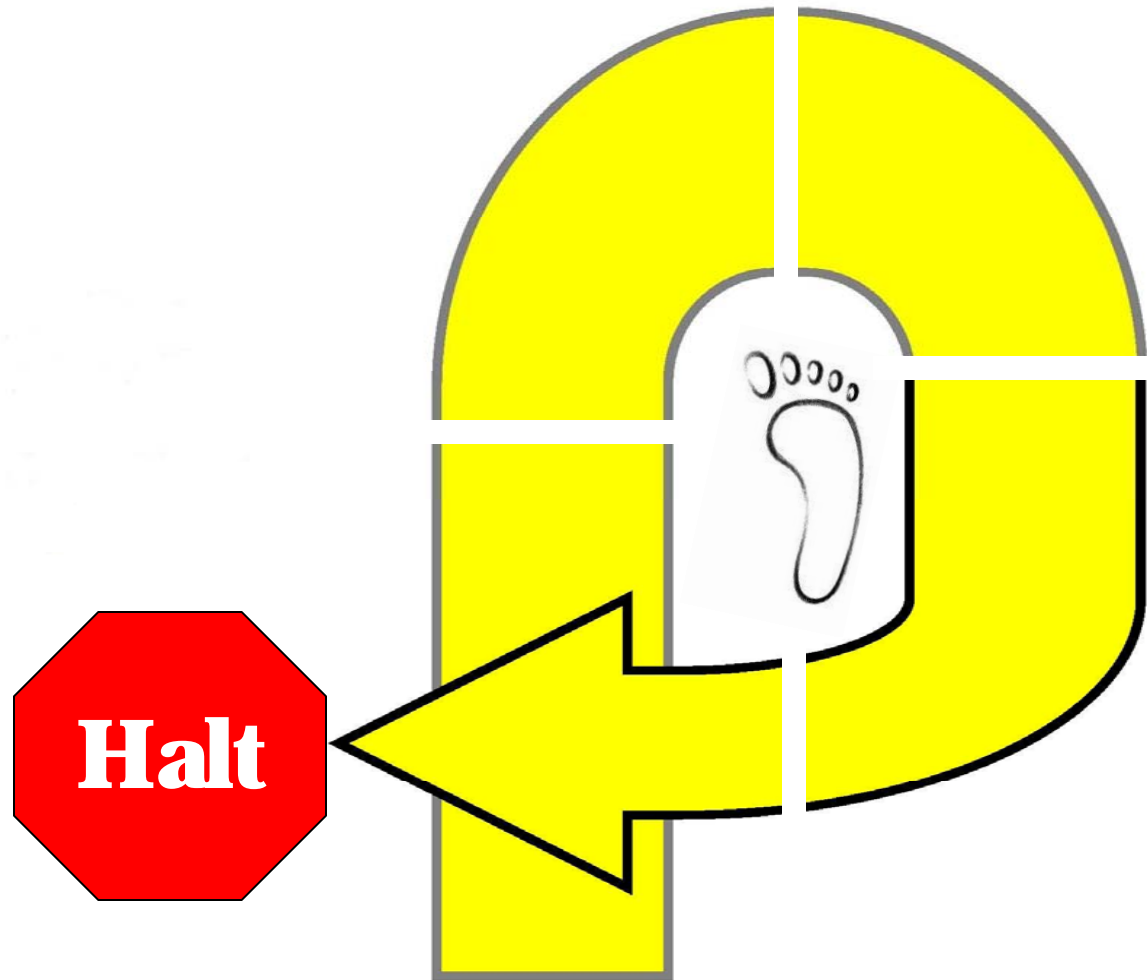


**Sit**  
**Stay**

**X,M - # 299**

**Call**

**270°  
Pivot  
Right  
Halt**



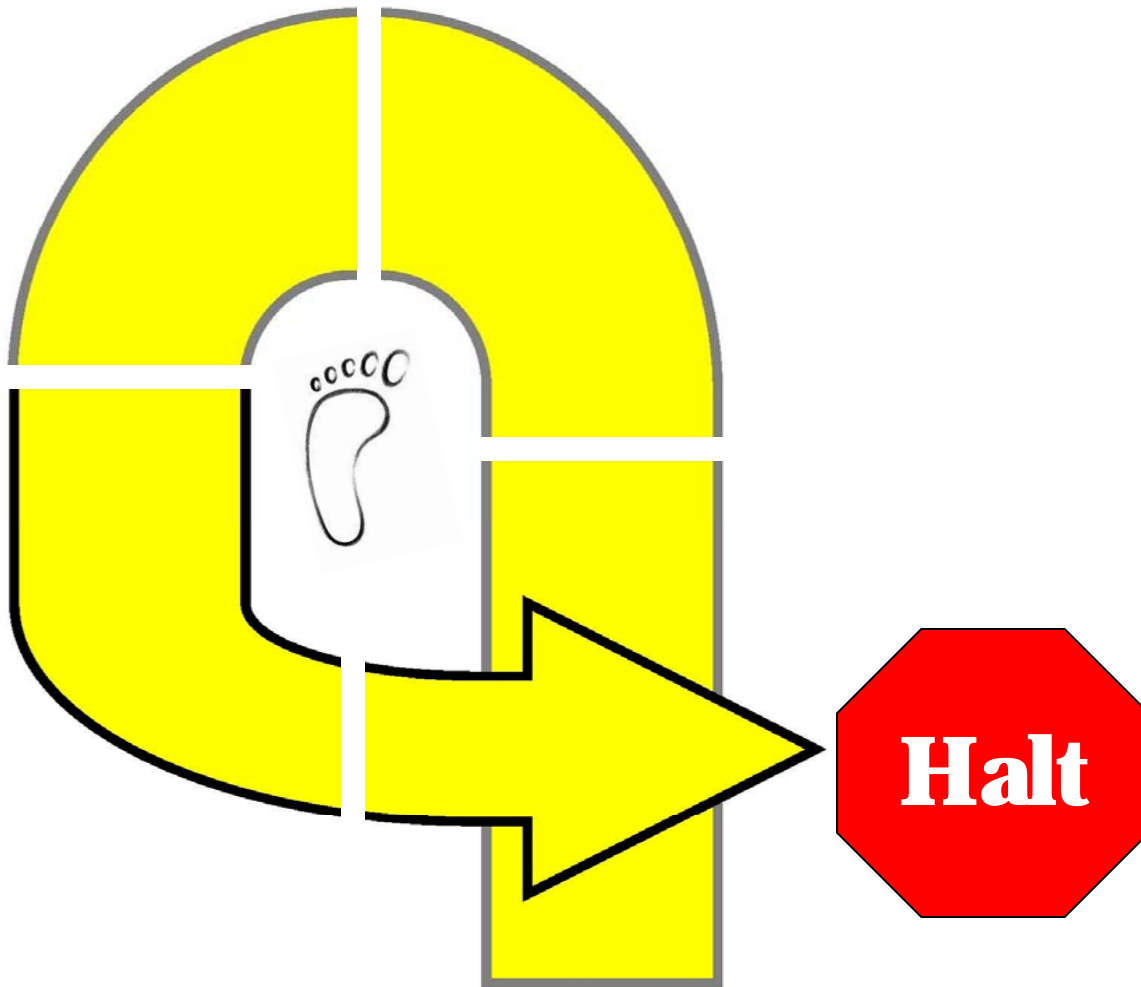
**M - # 301**

**270°**

**Pivot**

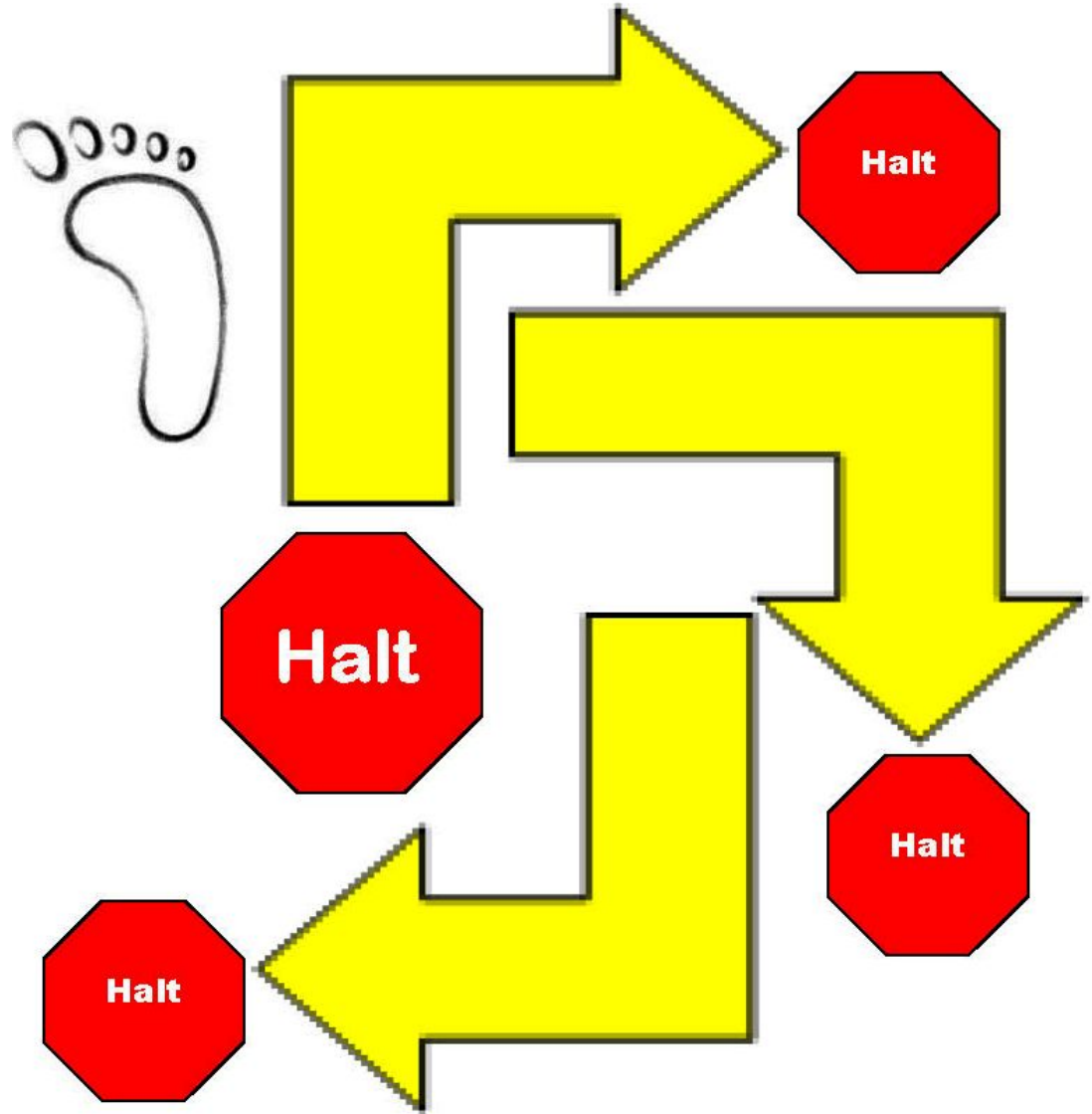
**Left**

**Halt**

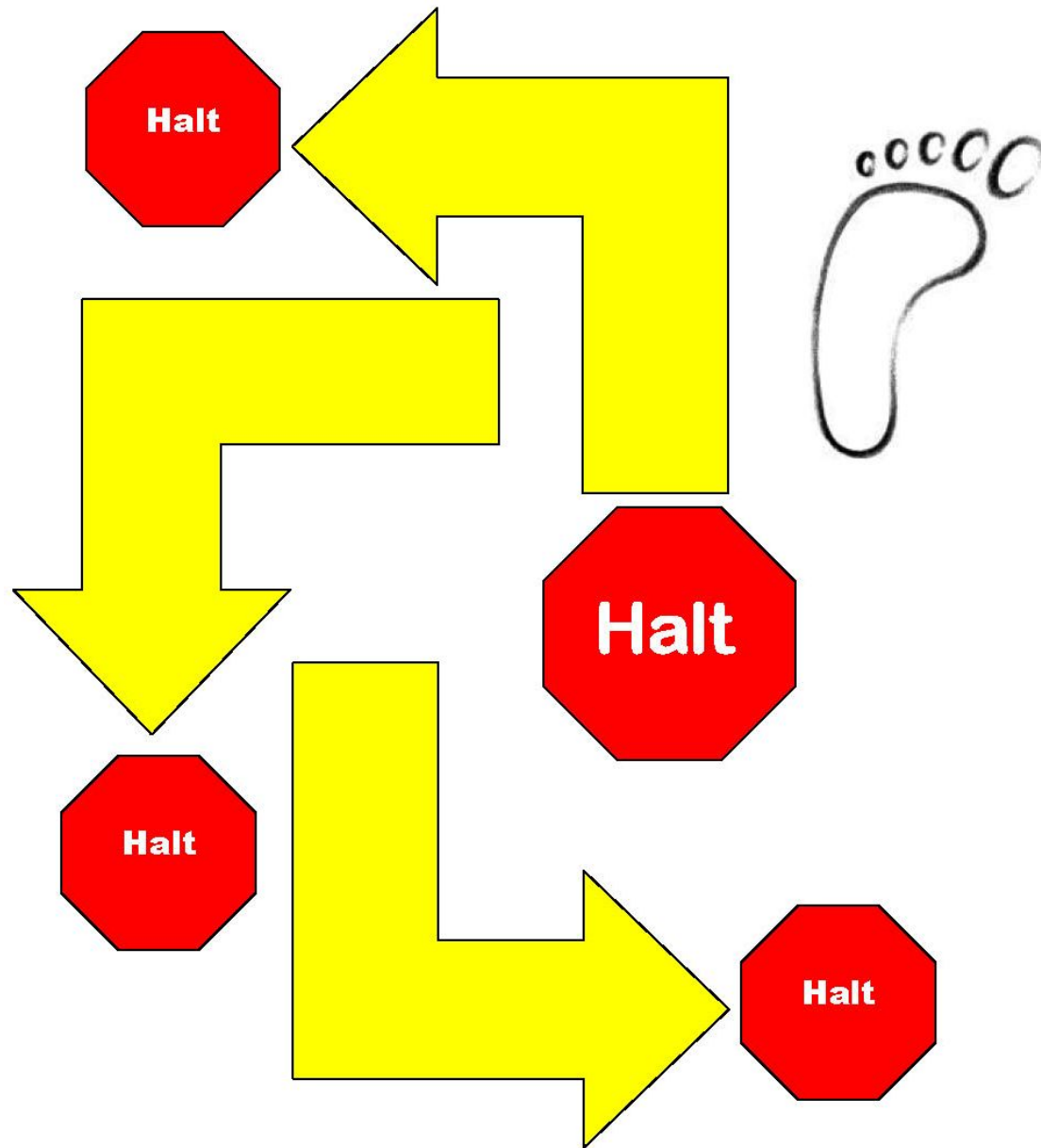




**Halt**  
**90° Pivot**  
**Right**  
**Halt**  
**3 Times**



**X- # 303**



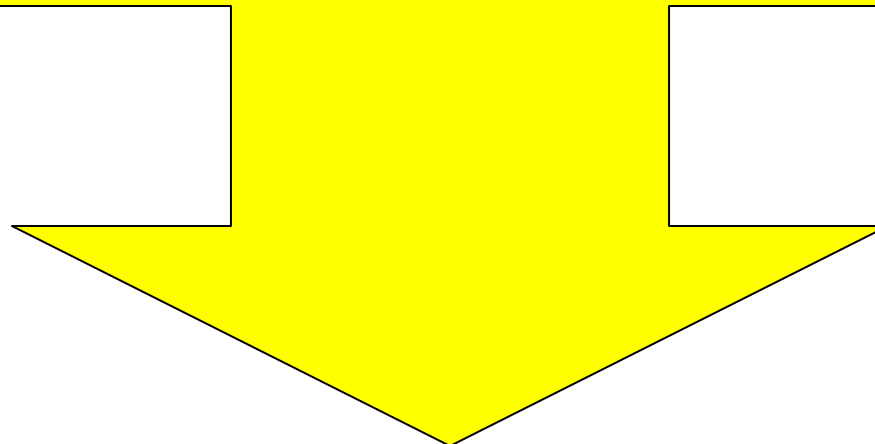
**Halt**  
**90° Pivot**  
**Left**  
**Halt**  
**3 Times**

**Call Front**



**180° Pivot Right**

**Finish Right - Halt**

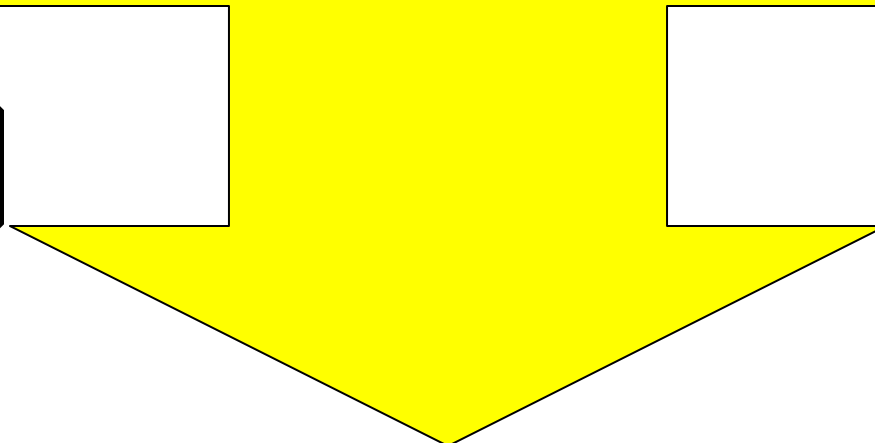


**Call Front**

**180° Pivot Left**



**Finish Left - Halt**





**3 Steps- Sit**

**2 Steps- Stand**

**1 Step- Down**

**M – # 307**

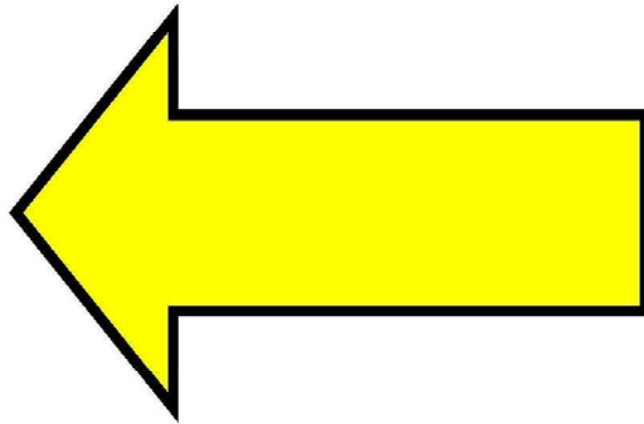


**3 Steps- Down**

**2 Steps- Sit**

**1 Step- Stand**

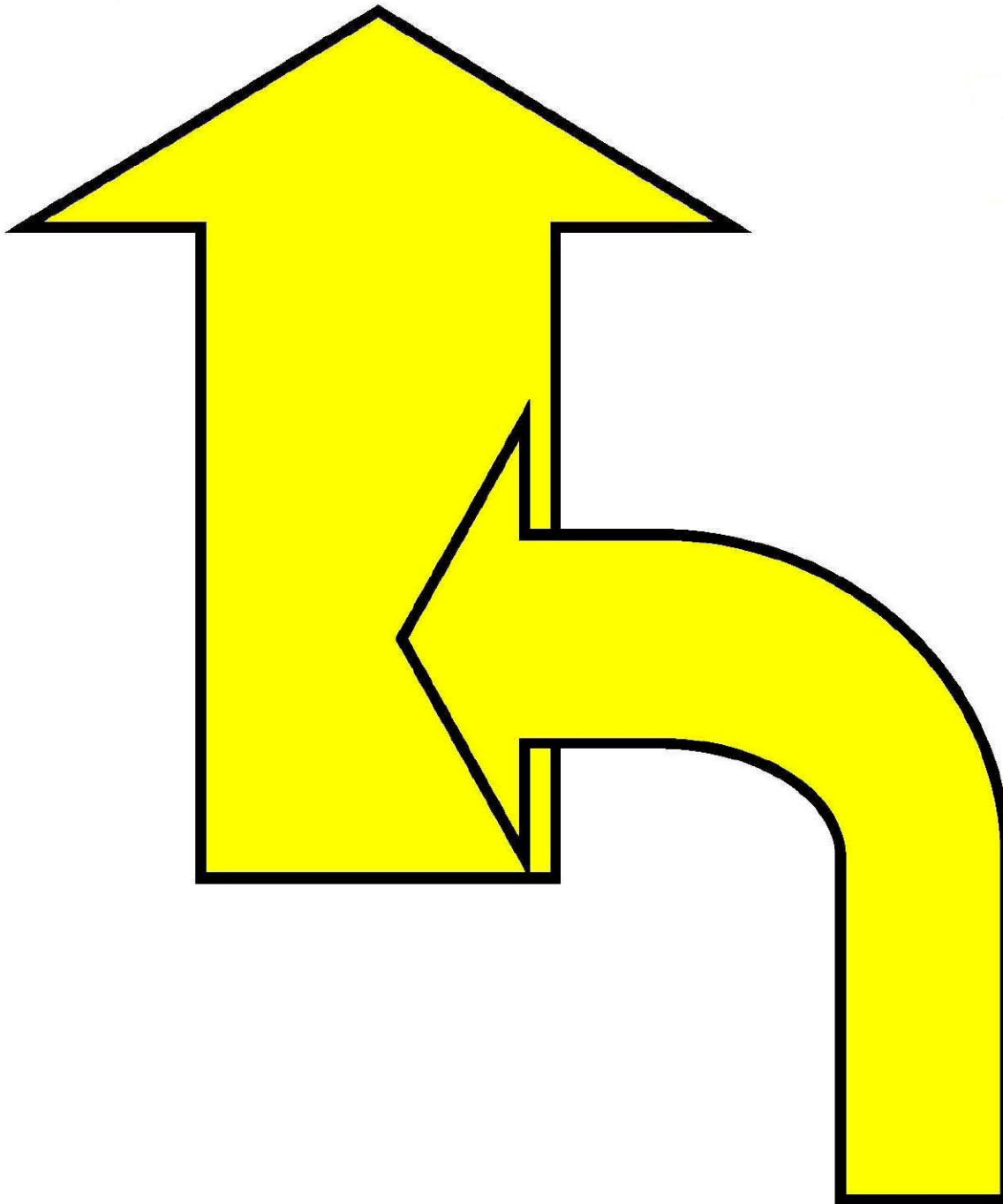
**M - # 308**



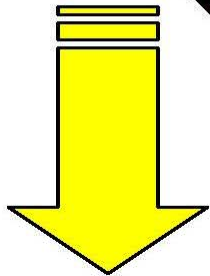
**Side Step  
Left**

**M – # 309**

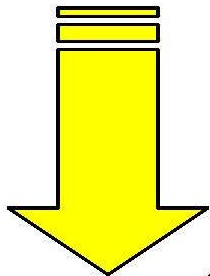
**Moving  
Side  
Step  
Left**



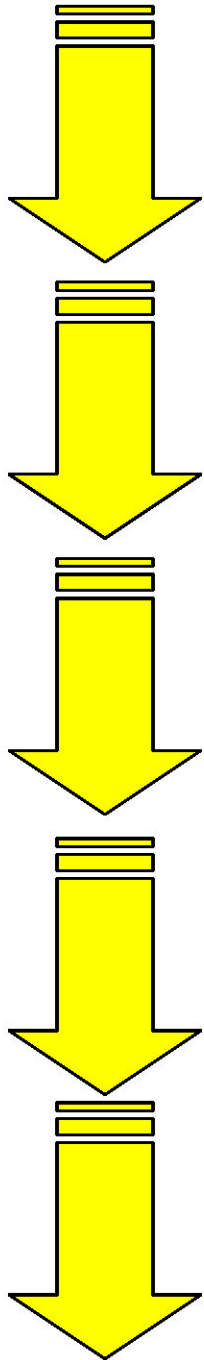




**Backup Two Steps**

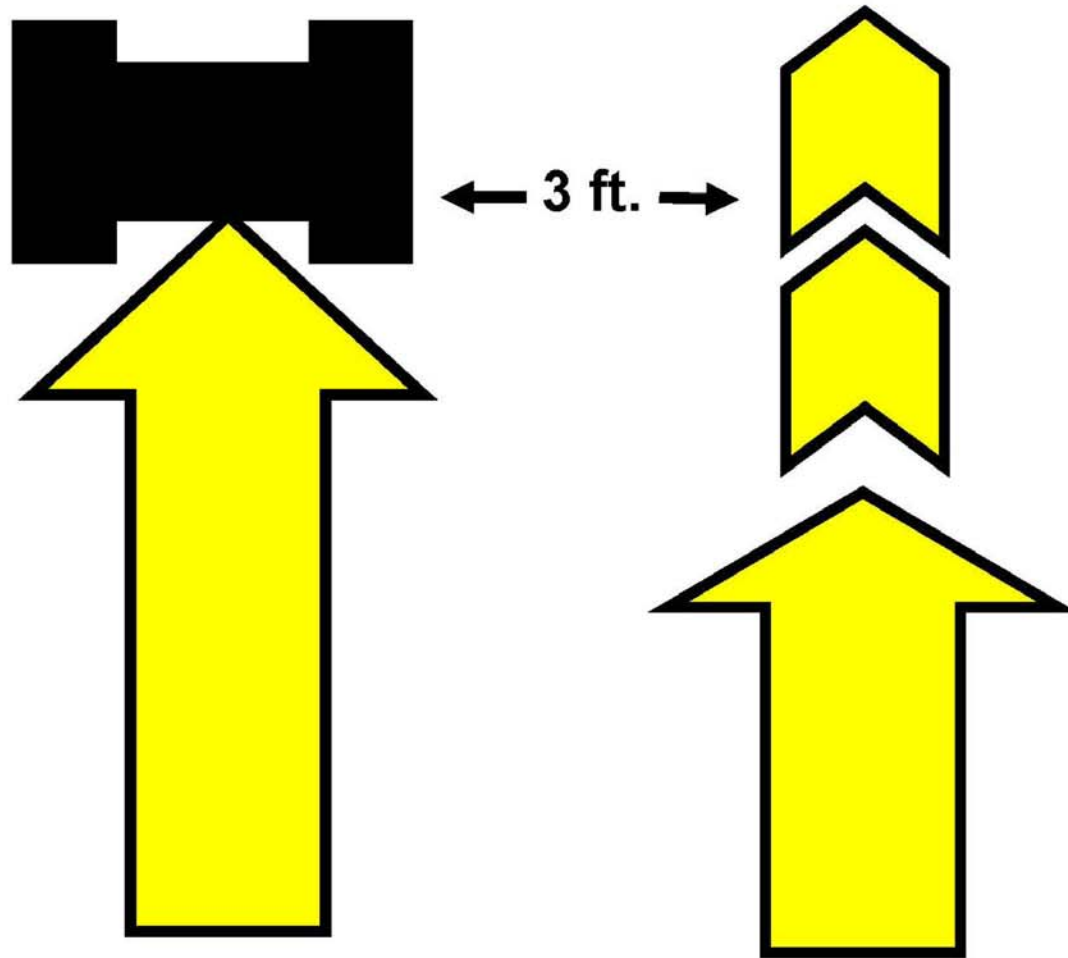


**M - # 311**



**Back Up  
5 Steps  
Dog  
Stays in  
Position**

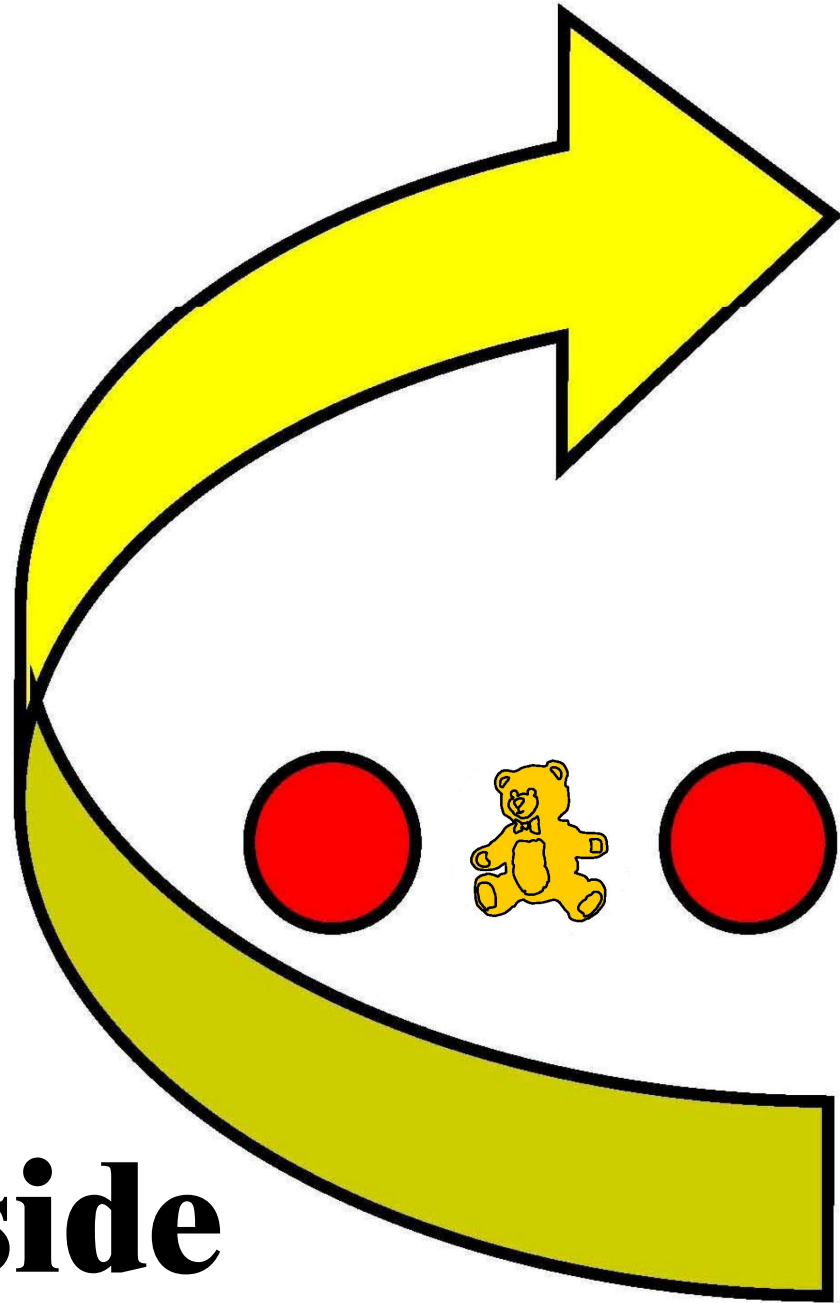
**M - # 312**



**Send To Jump**

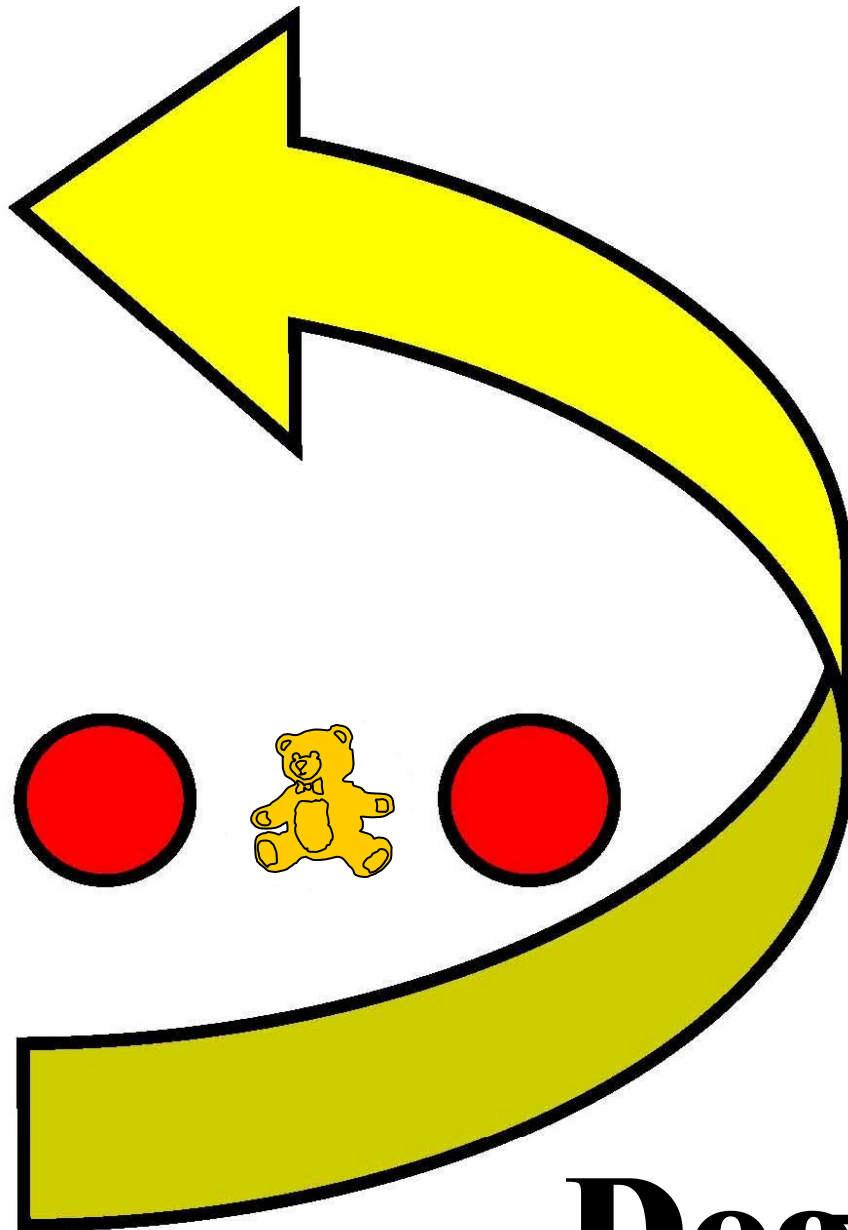
**M- # 313**

**Spiral  
Right  
With One  
Distraction**



**Dog Outside**

**M - # 314**

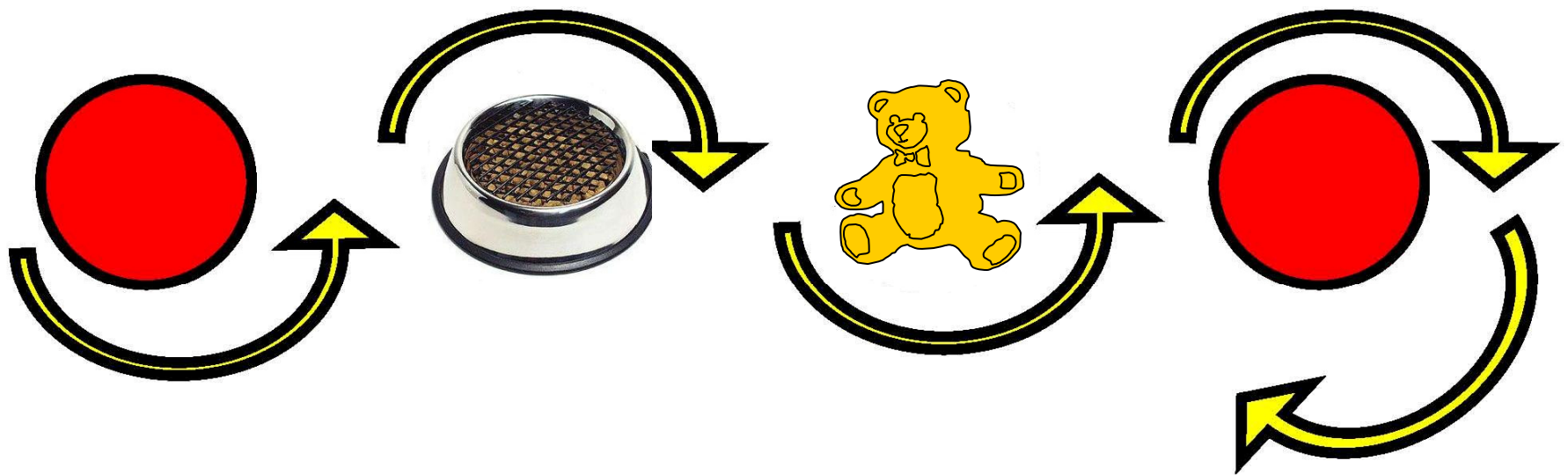


**Spiral  
Left  
With One  
Distraction**

**Dog Inside**

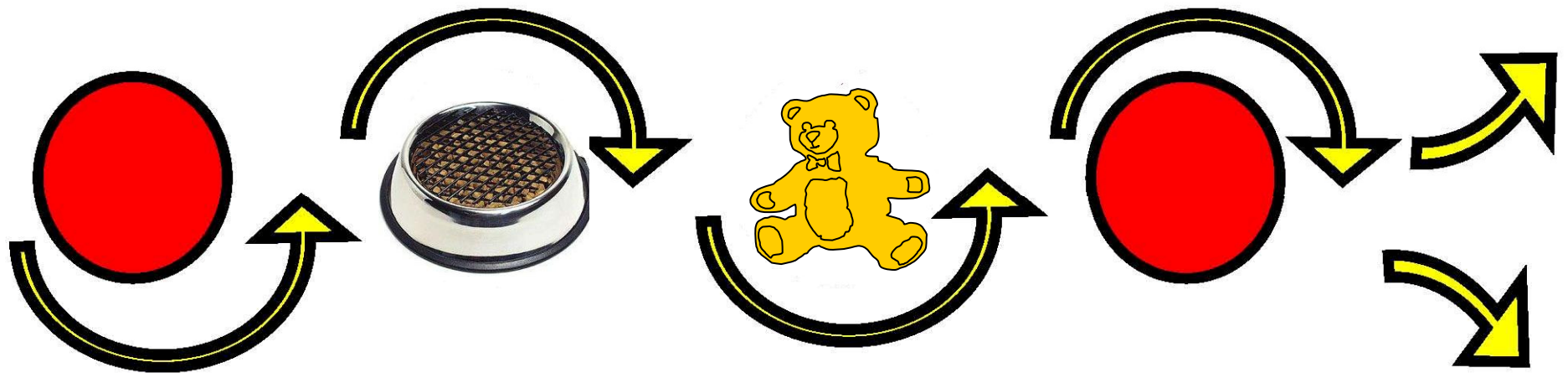
# Serpentine

## Weave Twice With Distractions

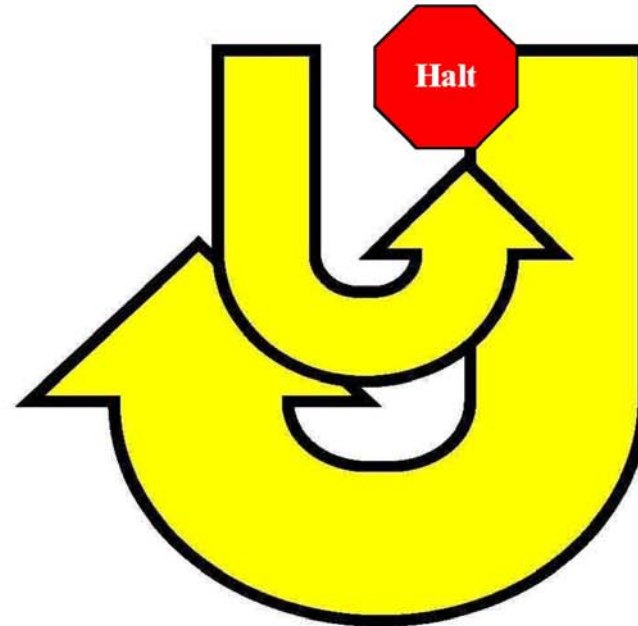
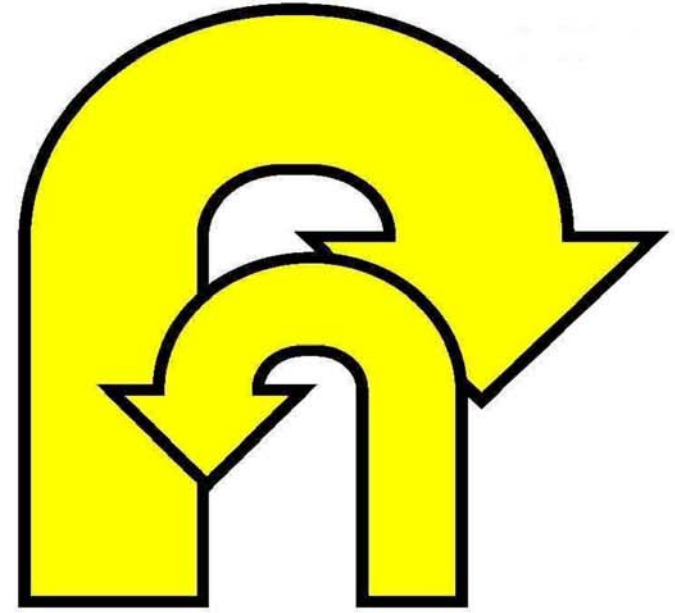


M – # 316

# Serpentine Weave Once With Distractions



**Double  
Left  
About  
Turn  
Halt**







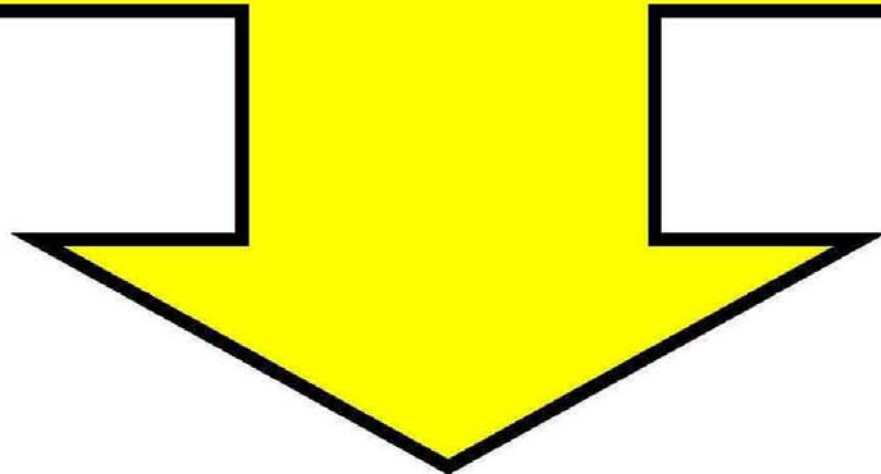
**Moving Sit  
Walk Around  
Dog**

# **Moving Down**

**Walk to Call Marker Turn Facing Dog**

# **Call to Heel**

# **Forward**



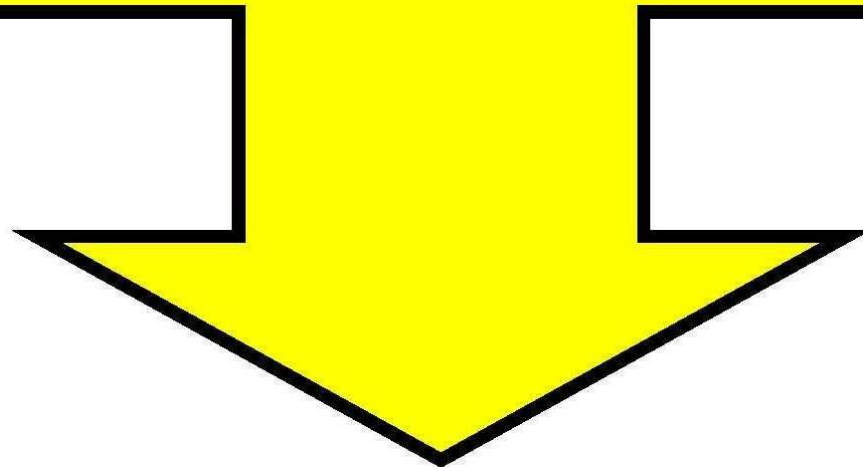
**M - # 320**

# **Moving Sit**

**Walk to Call Marker Turn Facing Dog**

# **Call to Heel**

# **Forward**



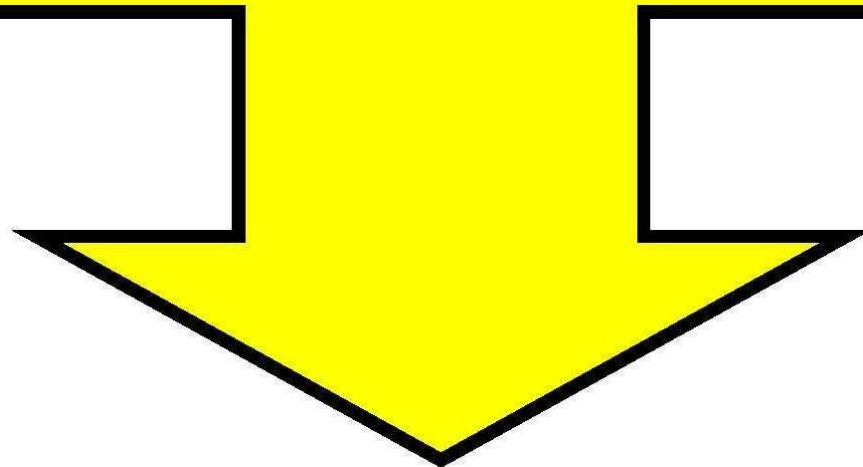
**M - # 321**

# **Moving Stand**

**Walk to Call Marker Turn Facing Dog**

## **Call to Heel**

## **Forward**



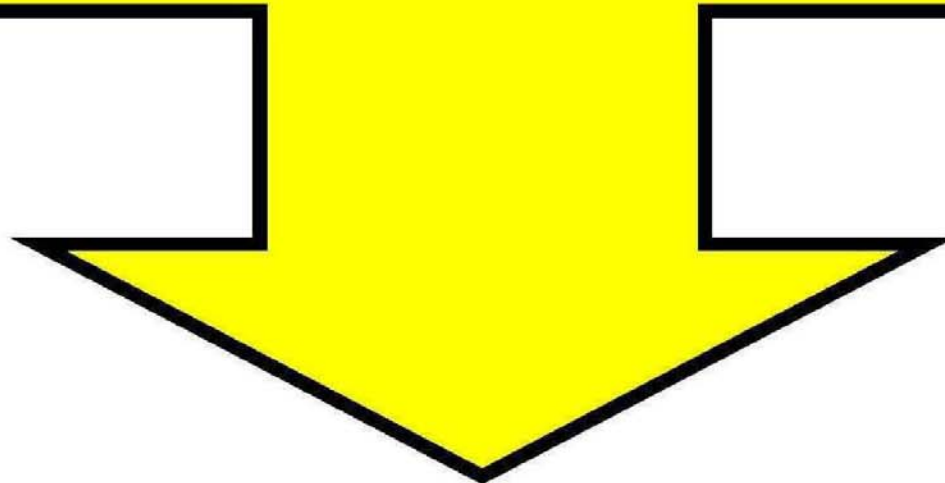
# **Moving Stand**

**Walk to Call Marker Turn Facing Dog**

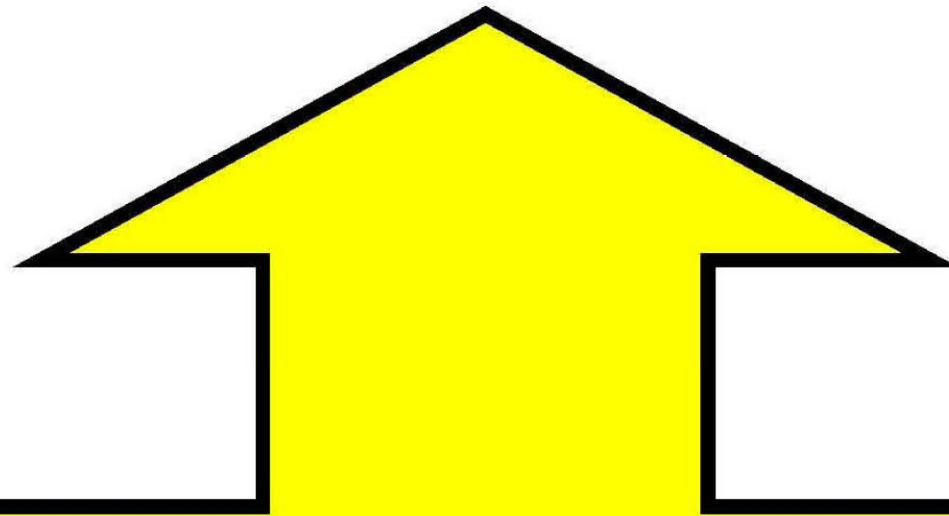
**Call to Front**

**Signal to Finish**

**Forward**



**M – # 323**



## **Moving Stand**

**Walk to Call Marker Turn Facing Dog**

**Signal to Down then to Sit**

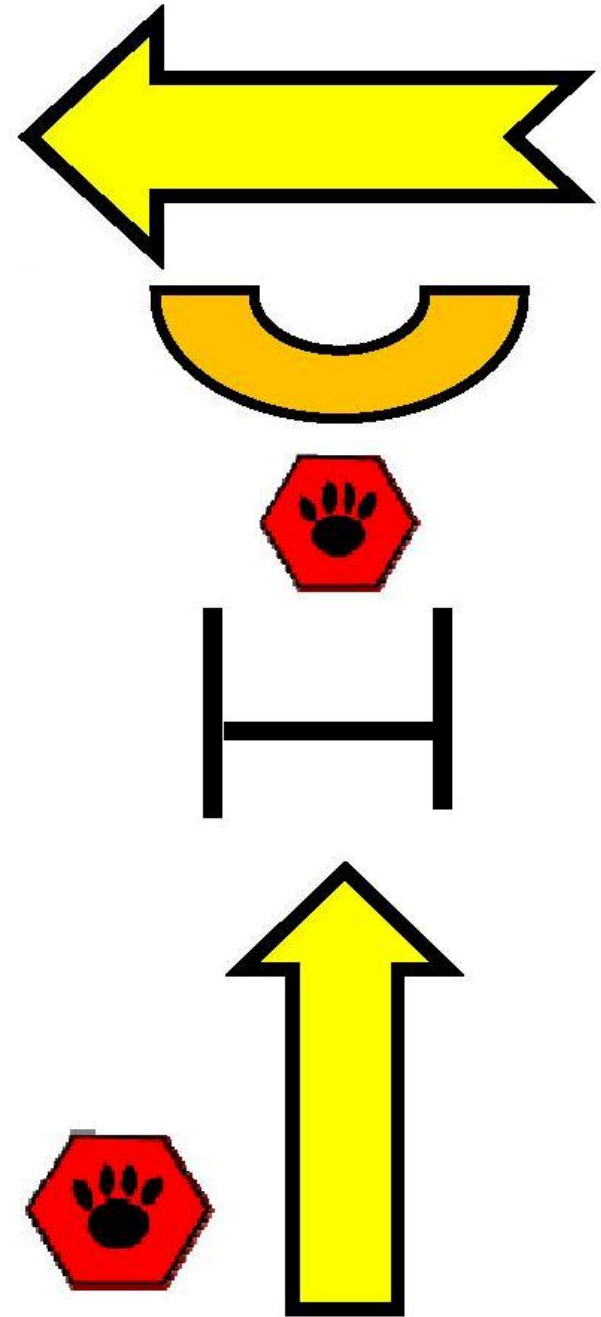
**Handler Returns to Dog**

**Forward**

M - # 324

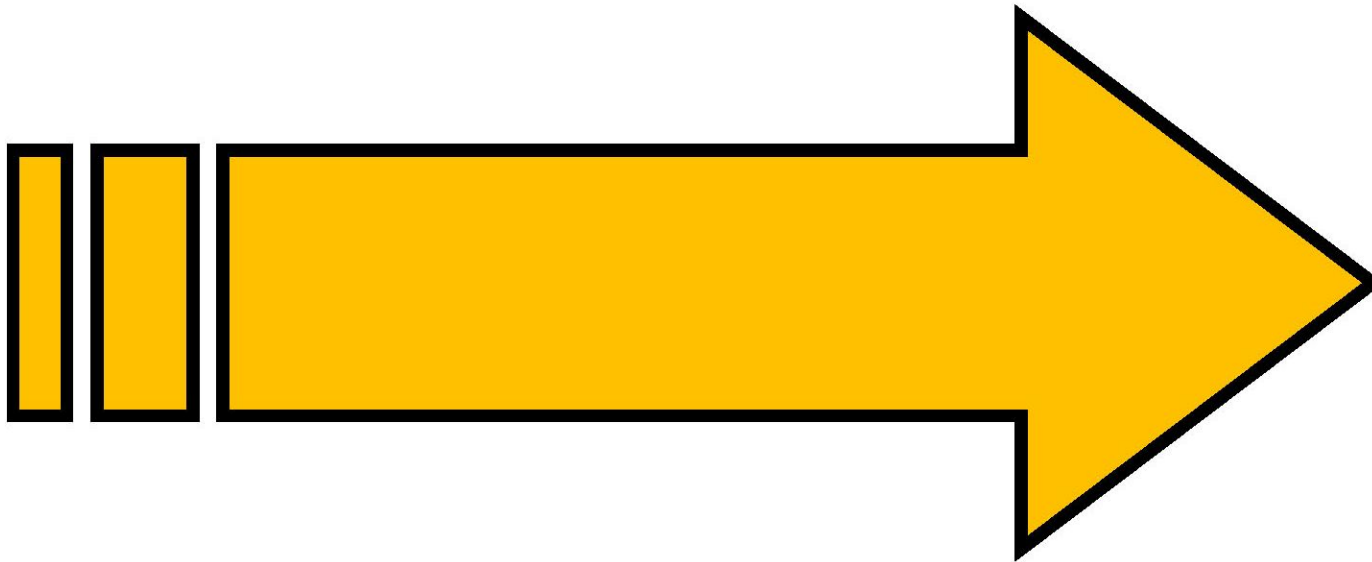


**Recall Over**  
**Jump**  
**Finish**  
**Right Turn**



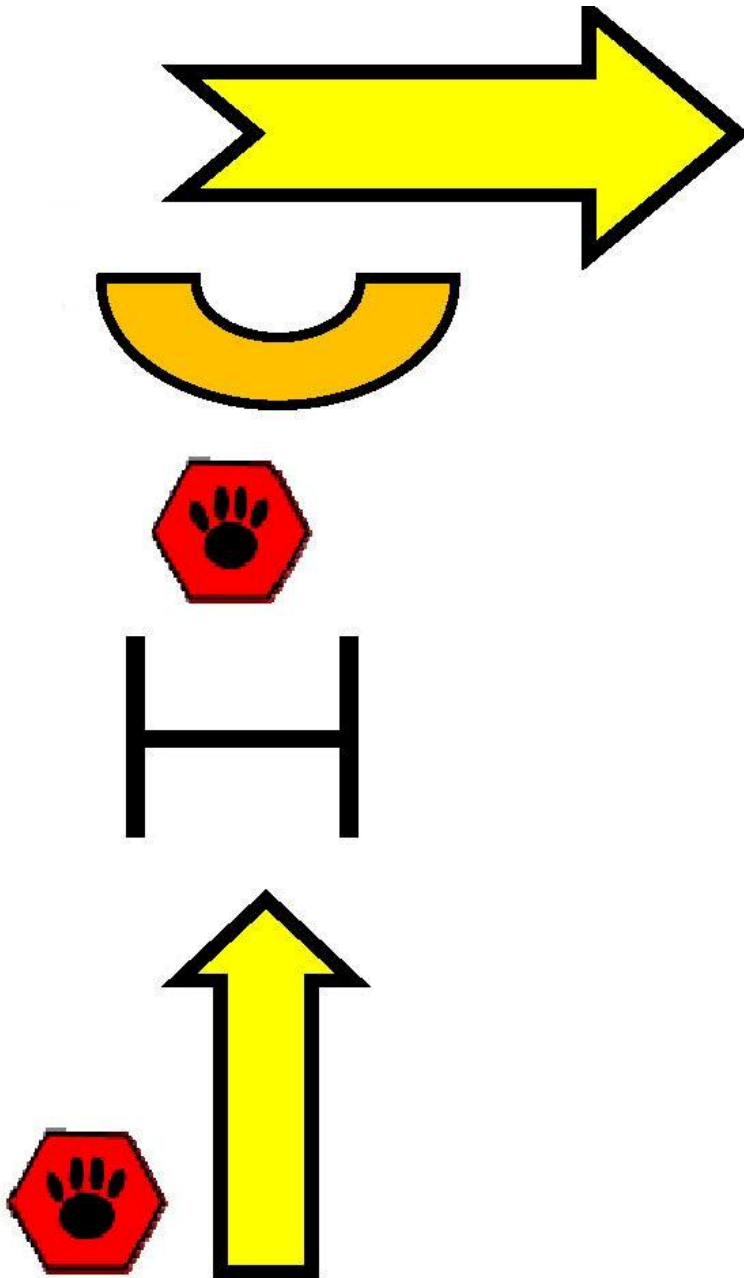
**M – # 324A**

# **Directional Arrow**





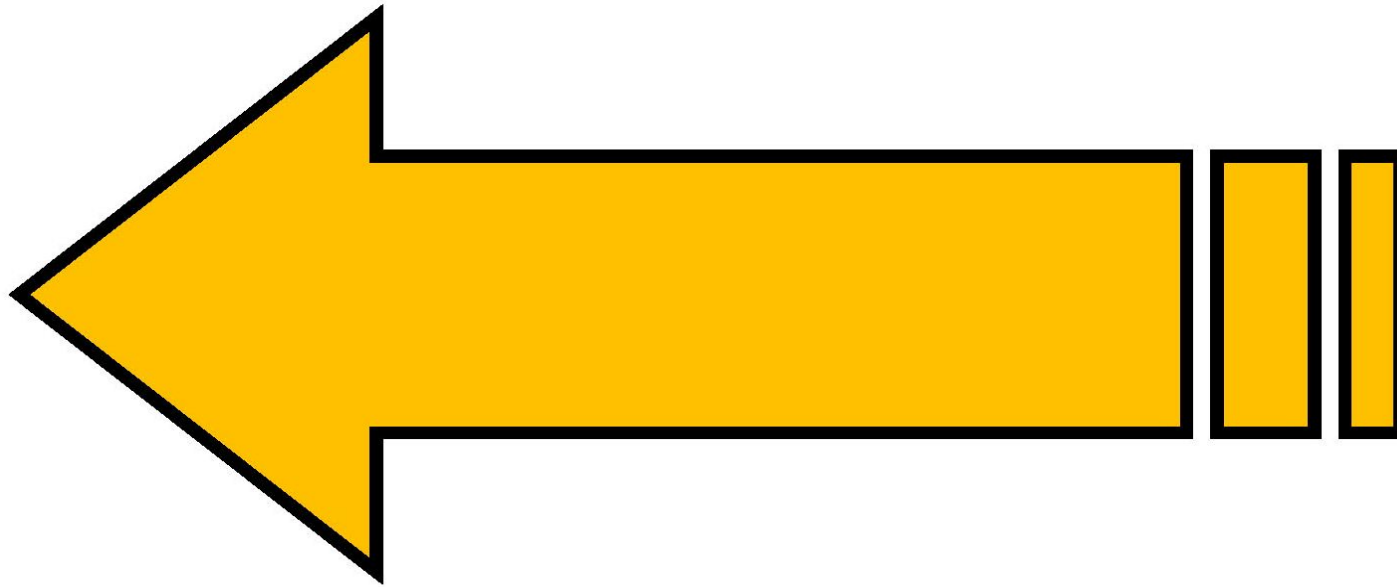
M – # 325



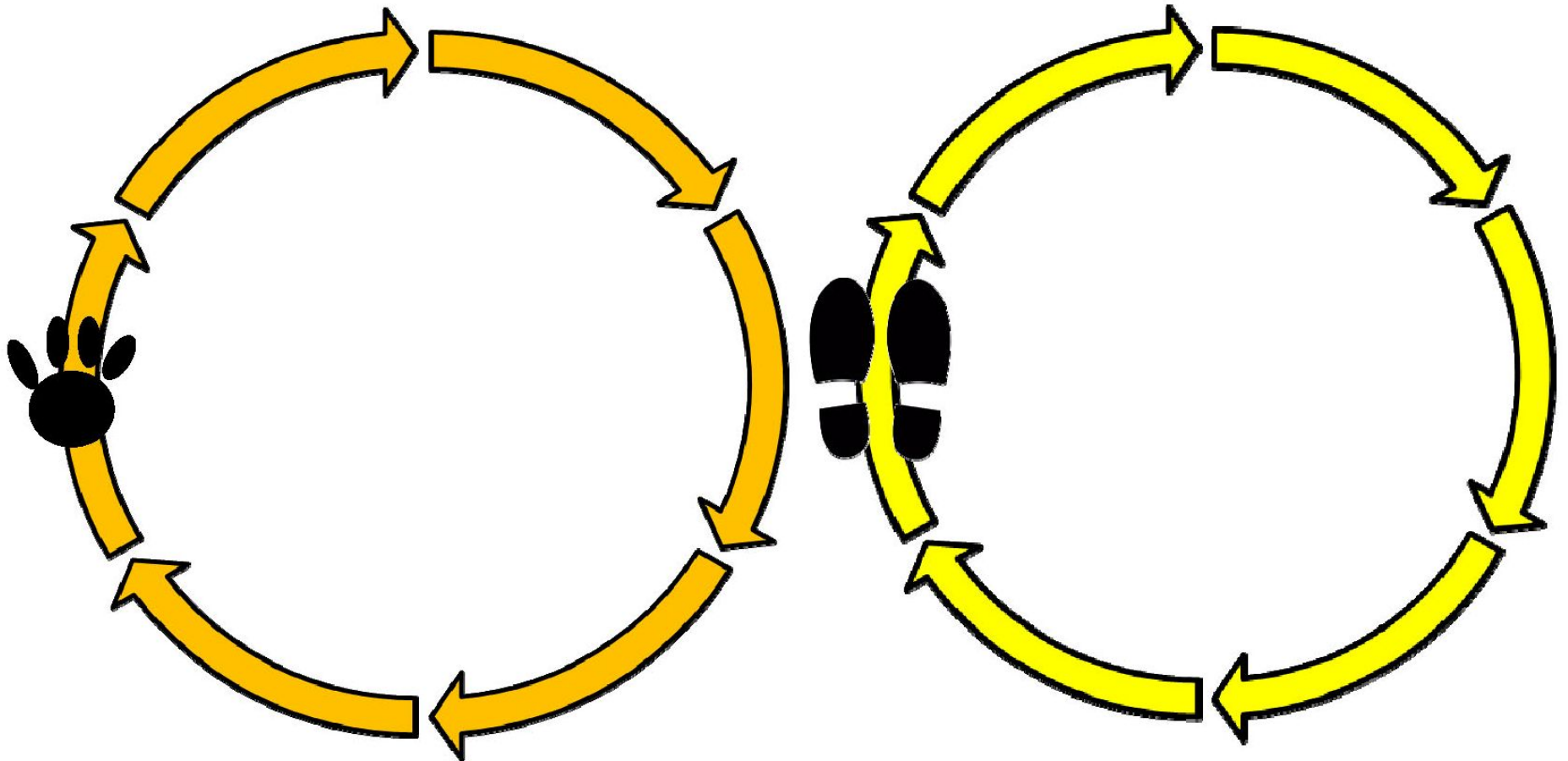
**Recall Over**  
**Jump**  
**Finish**  
**Left Turn**

**M – # 325A**

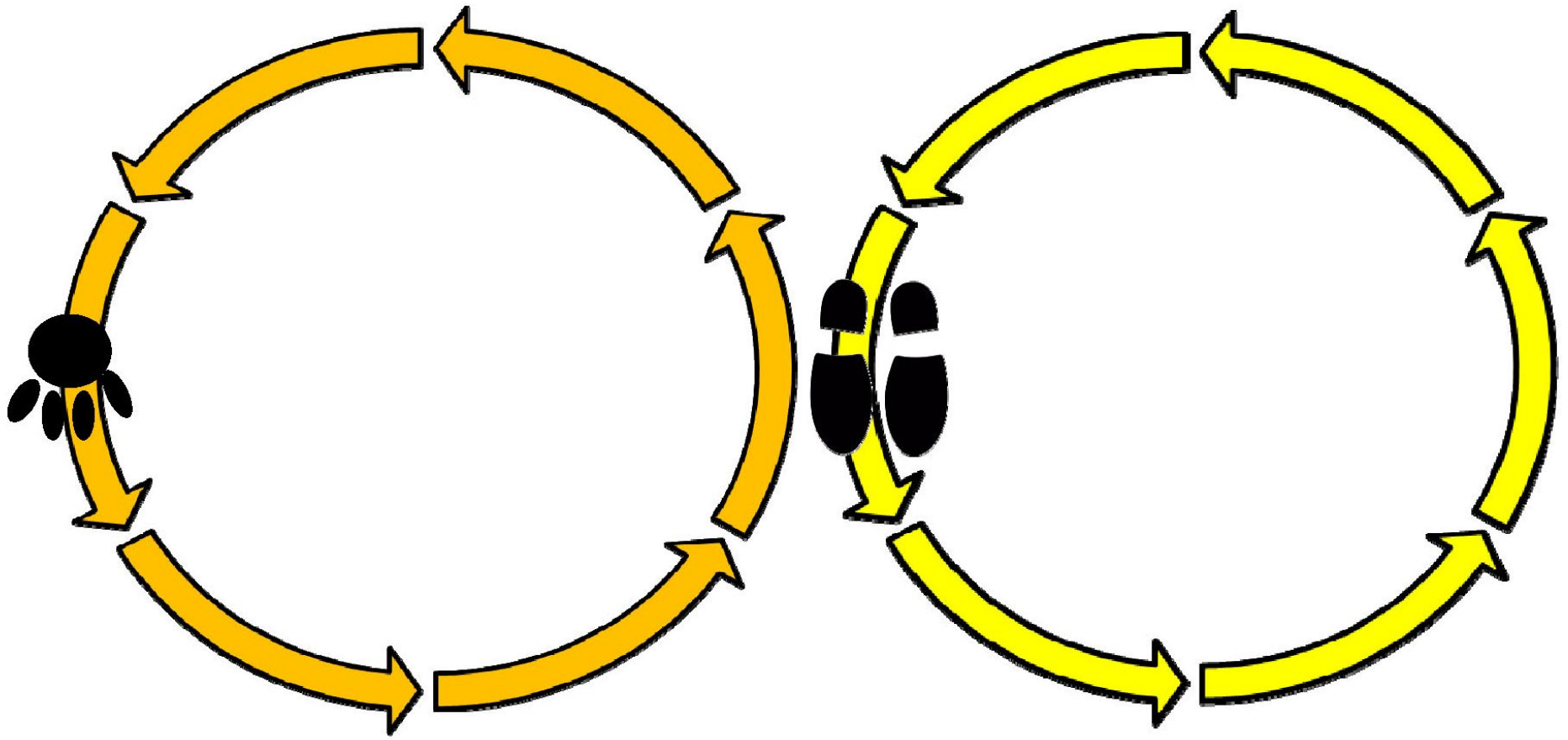
# **Directional Arrow**



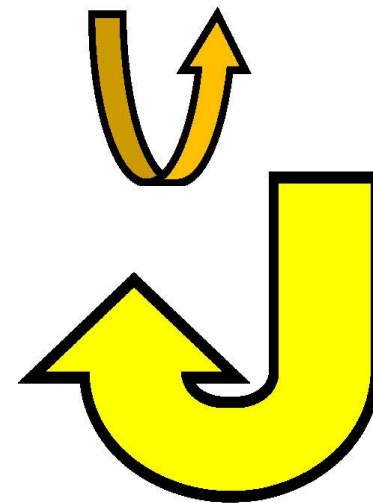
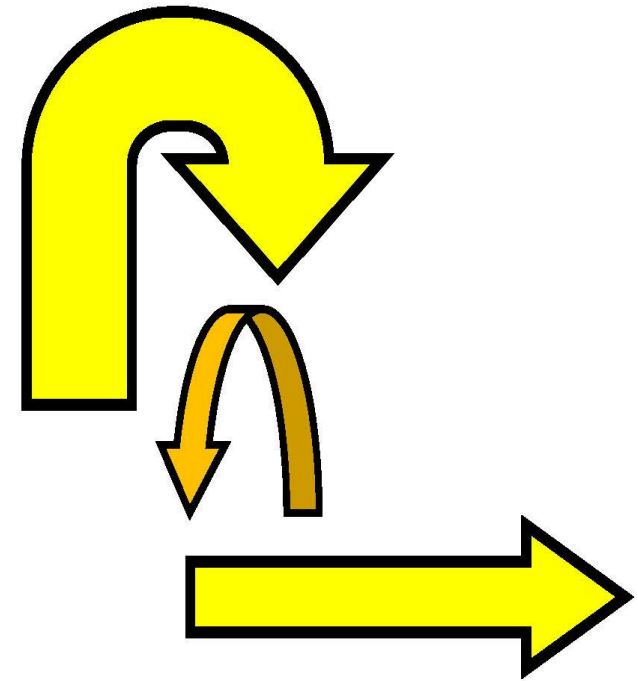
# Side by Side 360° Right Circle



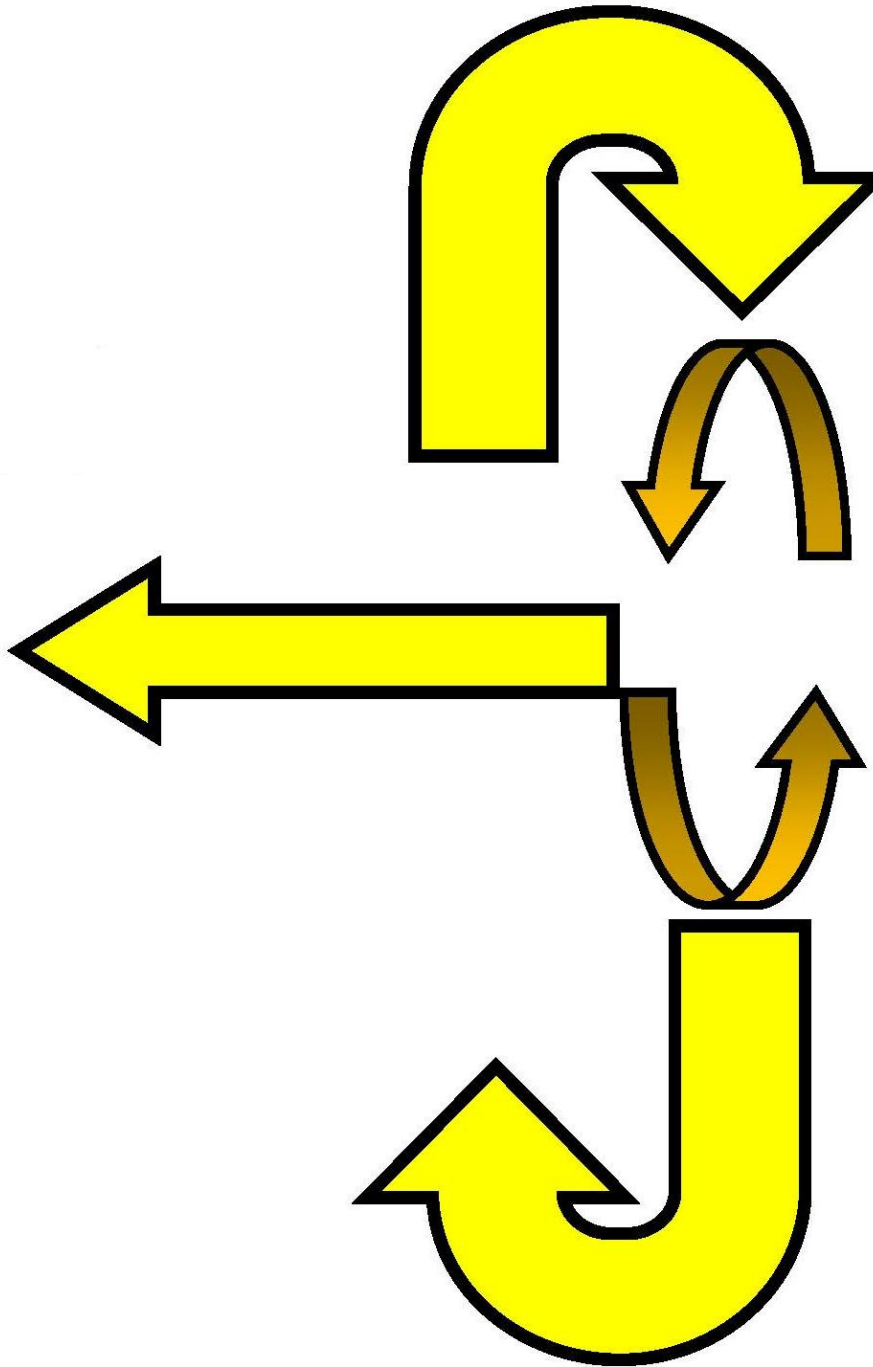
# Side by Side 360° Left Circle



**Double  
Left About  
Turn  
Right Turn**

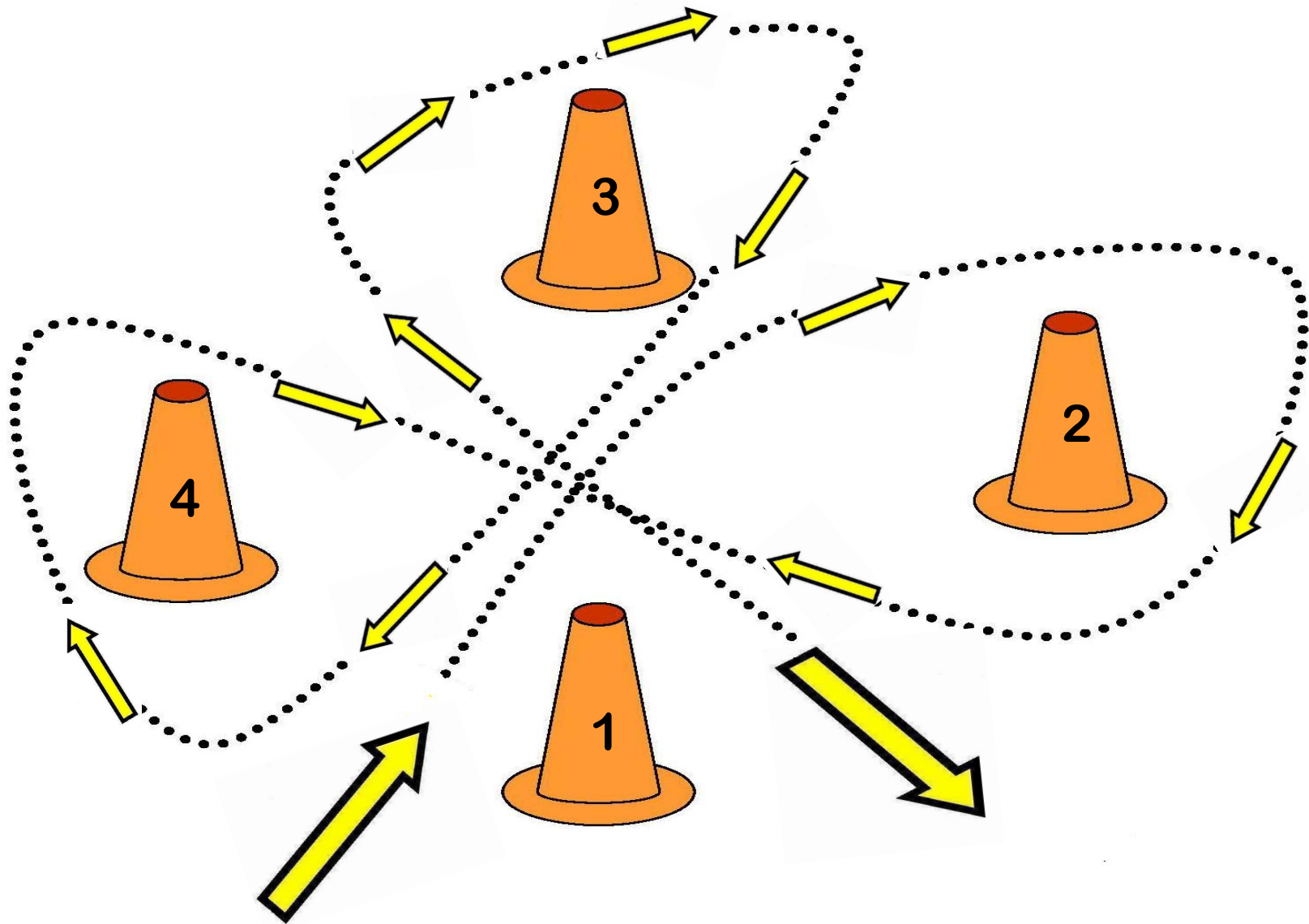


**M – # 331**

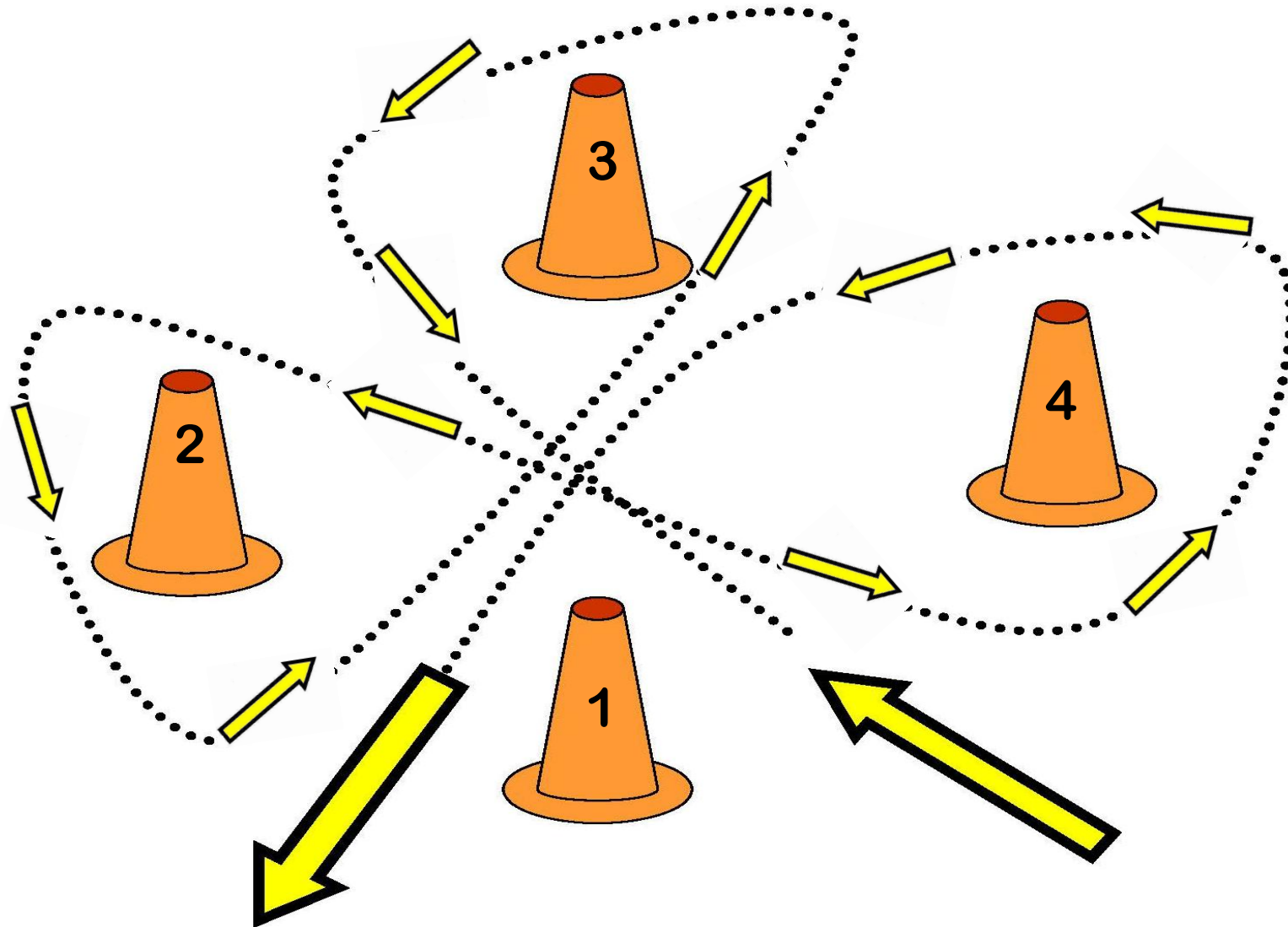


**Double  
Left About  
Turn  
Left Turn**

# Cloverleaf Right



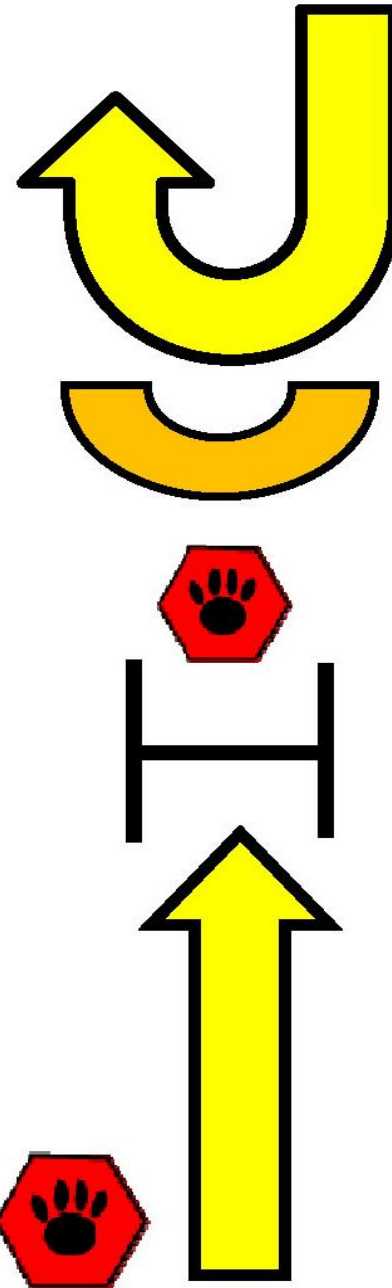
# Cloverleaf Left



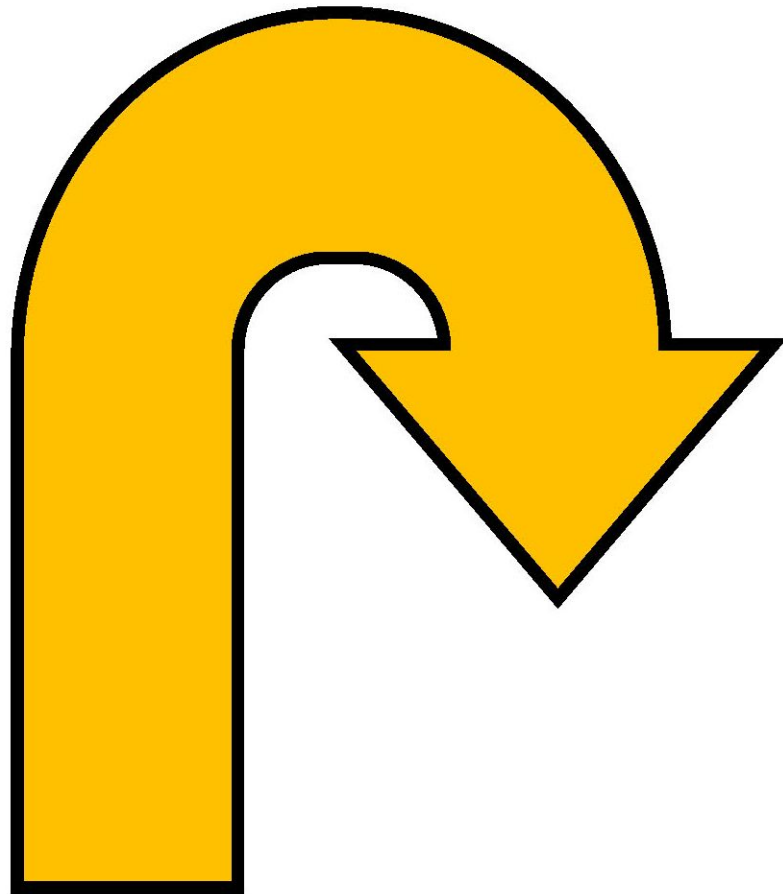




**Recall Over**  
**Jump**  
**Finish**  
**About Turn**  
**Forward**



# **Directional Arrow**





**Stand  
Stay**